VT 2010 Digital Power Meter USER'S MANUAL



IM 253101-01E 3rd Edition

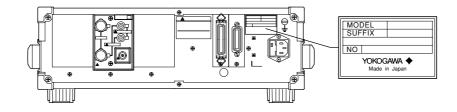
Foreword	Thank you for purchasing the YOKOGAWA Model WT2010 Digital Power Meter. This User's Manual contains useful information regarding the instrument's functions and operating procedures as well as precautions that should be observed during use. To ensure proper use of the instrument, please read this manual thoroughly before operating it. Keep the manual in a safe place for quick reference whenever a question arises.
Notes	 The contents of this manual are subject to change without prior notice. Every effort has been made in the preparation of this manual to ensure the accuracy of its contents. However, should you have any questions or find any errors, please contact your dealer or YOKOGAWA sales office. Copying or reproduction of all or any part of the contents of this manual without YOKOGAWA's permission is strictly prohibited. The guarantee certificate is attached to the packaging container. Since it will not be reissued, it should be kept in a safe place after it has been read.
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Checking Package Contents

Unpack the box and check the contents before operating the instrument. If the wrong instrument or accessories have been delivered, if some accessories are missing or if they appear abnormal, contact the dealer from which you purchased them.

WT2010 Main Body

Check that the model name and suffix code given on the name plate of the rear panel match those on your order.



MODEL

253101

SUFFIX

Suffix Code	Description
- C1	GP-IB interface
- C2	RS-232-C interface
- 1	Rated AC line voltage: 100 VAC
- 3	Rated AC line voltage: 115 VAC
- 5	Rated AC line voltage: 200 VAC
- 7	Rated AC line voltage: 230 VAC
- D	UL/CSA standard power cord
- F	VDE standard power cord
- R	SAA standard power cord
- J	BS standard power cord
/B5	Printer incorporated
/HRM	Harmonic analysis function incorporated
/DA	D/A outputs (14 channels)
/FL	Flicker Measurement Functions

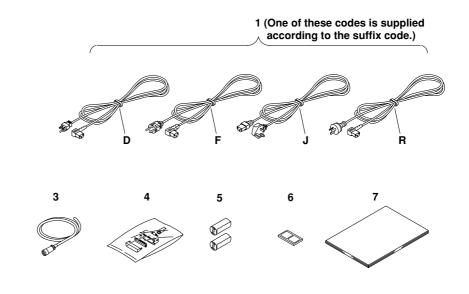
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When contacting the dealer, please give this serial number.

Standard Accessories

The following standard accessories are supplied with the instrument.

No.	Name	Part No.	Quantity	Remarks
1	Power cord	Refer to the suffix code.	1	Type of cord is specified by the suffix code.
2	Spare fuse	A1353EF	1	100 VAC/200 VAC common
3	(supplied in the fuse holder) External shunt connector cable	B9284LK	1	(250 V, 5 A) 1 for each element
4	Remote control connector	A1005JD	1	External input and output
5	Roll chart	B9293UA	2	Built-in printer (optional), 58 mm × 10 m
6	Rubber feet	A9088ZM	1	1 pair
7	User's Manual	IM253101-01E	1	This manual



Note.

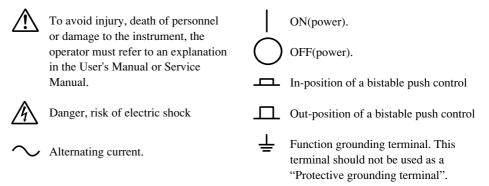
• It is recommended that the packing box be kept in a safe place. The box can be used when you need to transport the instrument somewhere.

Safety Precautions

This instrument is an IEC safety class I instrument (provided with terminal for protective grounding).

The following general safety precautions must be observed during all phases of operation, service and repair of this instrument. If this instrument is used in a manner not sepecified in this manual, the protection provided by this instrument may be impaired. Also, YOKOGAWA Electric Corporation assumes no liability for the customer's failure to comply with these requirements.

The following symbols are used on this instrument.



Make sure to comply with the following safety precautions. Not complying might result in injury, death of personnel or damage to the instrument.

WARNING

Power Supply

Ensure the source voltage matches the voltage of the power supply before turning ON the power.

Power Cable and Plug

To prevent an electric shock or fire, be sure to use the power cord supplied by YOKOGAWA. The main power plug must be plugged in an outlet with protective grounding terminal. Do not invalidate protection by using an extension cord without protective grounding.

Protective Grounding

Make sure to connect the protective grounding to prevent an electric shock before turning ON the power.

Necessity of Protective Grounding

Never cut off the internal or external protective grounding wire or disconnect the wiring of protective grounding terminal. Doing so poses a potential shock hazard.

Defect of Protective Grounding and Fuse

Do not operate the instrument when protective grounding or fuse might be defective.

Fuse

To prevent fire, be sure to use a fuse with the specified ratings (current, voltage and type). Before replacing the fuse, turn OFF the power and unplug the power cord. Do not use any fuse other than the specified one. Also do not short-circuit the fuse holder.

Do not Operate in an Explosive Atmosphere

Do not operate the instrument in the presence of flammable liquids or vapors. Operation of any electrical instrument in such an environment constitutes a safety hazard.

Do not Remove any Covers

There are some areas with high voltages. Do not remove any cover if the power supply is connected. The cover should be removed by qualified personnel only.

External Connection

To ground securely, connect the protective grounding before connecting to measurement or control unit.

How to Use this Manual

If you are using this instrument for the first time, we suggest that you read Chapter 1 before starting operation.

Chapter	Description
1	Main features, functions and the name of each part of the power meter
2	General precautions for use, installation method, how to turn the power on and off, and setting the date and time
3	How to connect the object to be measured and display using function keys
4	Setting measuring conditions and ranges
5	Operation method for measuring voltage, current, active power and peak values, and for display of computed apparent power, reactive power, power factor and phase angle
6	Operation method for measurement of frequency
7	Setting and operation of crest factor MATH, scaling and averaging functions
8	Setting and operation for integration of active power and current.
9	Operation method for harmonic analysis functions
10	Operation method for measuring voltage and flicker directly using the voltage fluctuation/flicker measurement function
11	Setting and operation for printing measured values and set-up information using the built-in printer
12	Setting and operation for remote control and D/A output
13	Storing, recalling and initializing set-up information, key lock operation, and back-up function for set-up information
14	Communications using a GP-IB or RS-232-C interface
15	Possible causes of an alarm and corrective actions, description of error codes and corrective actions, replacement of the power supply fuse, and calibration
16	Specifications of the instrument
Appendix	Description of communication commands, sample programs and print examples (by the built-in printer)
Index	Description of important terms

Conventions Used in this Manual

Symbols used

The following symbols are used in this User's Manual.



To avoid injury or death of personnel, or damage to the instrument, the operator must refer to the User's Manual. In the User's Manual, these symbols appear on the pages to which the operator must refer.

WARNING



Describes precautions that should be observed to prevent the danger of minor or moderate injury to the user, or the damage to

Describes precautions that should be observed to prevent the

danger of serious injury or death to the user.

Note

Provides information that is important for proper operation of the instrument.

Key Operation Rules

• To activate the function marked below a key, first press the SHIFT key (to light up the green indicator), then press the key. The sequence for key operation is described as follows in this manual.

```
      SHIFT + ENTER (KEY LOCK)
      Function to be activated (marked below the key)

      Image: Shift + ENTER (KEY LOCK)
      Image: Shift + ENTER (KEY LOCK)

      Image: Shift + ENTER (KEY LOCK)
      Image: Shift + ENTER (KEY LOCK)

      Image: Shift + ENTER (KEY LOCK)
      Image: Shift + ENTER (Key Lock)

      Image: Shift + ENTER (Key Lock)
      Image: Shift + ENTER (Key Lock)

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      Image: Shift + ENTER (Key Lock)
      Image: Shift + ENTER (Key Lock)

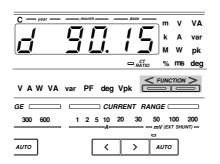
      Image: Shift + ENTER (Key Lock)
      Image: Shift + ENTER (Key Lock)
```

• On the display, " — " means that the digit indicated by " — " is blinking.

the property.

• The active key is indicated with a " as in the display example shown in the figure below.

— This digit is blinking.



Digital Numbers/Characters

This instrument is equipped with a 7-segment LED which imposes some restrictions on the usable characters. The numbers/characters are styled as follows.

0 → []	$A \rightarrow R$	K → Ł	U → ¦/ Small u → ⊔	+ → }-
1 → ¦	B→b	L → L	$V \rightarrow H$	- → -
2 → <i>2</i>	$C \rightarrow [$ Small $c \rightarrow c$	M→ā	W→ <u>-</u>	$\mathbf{X} \rightarrow \mathbf{u}$
3 → ∃	$D \rightarrow d$	N → ¬	$X \rightarrow ::$	÷ →]
4 → ੫	E → <i>E</i>	0→ <u></u>	Y → ⅓	^ → ⊓
5 → 5	$\mathbf{F} \rightarrow F$	P → <i>P</i>	$Z \rightarrow \frac{1}{2}$	
6 → £	G→Ľ	Q → ק		
7 → 7	$H \rightarrow H$ Small $h \rightarrow h$	R → -		
8 → 8	$I \rightarrow ;$ Small $i \rightarrow ,$	S → 5		
9 → g	J → Ľ	T → Ł		

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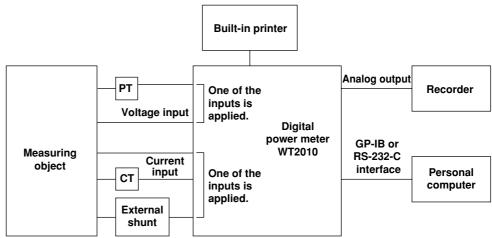
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1.1 System Configuration and Functional Block Diagram

System Configuration



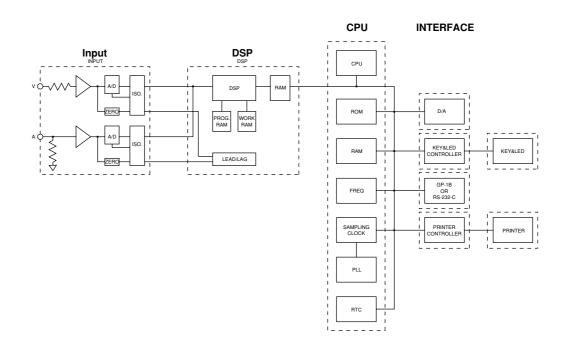
Functional Block Diagram

Operation Principle and Circuit Structure

The WT2010 Digital Power Meter consists of various sections; input, DSP (Digital Signal Processor), CPU and display sections. The Input section consists of the voltage input circuit and the current input circuit, and there are isolated from each other. In the voltage input circuit, the input voltage is normalized by a voltage divider and operational amplifier, then sent to the A/D converter. In the current input circuit, the input current is converted into voltage by a shunt resistor, amplified and normalized by an operational amplifier, and then sent to the A/D converter.

The output from the A/D converter in the current input and voltage input circuits is sent to the DSP via a photo-isolator, which is used to provide insulation between the current input circuit (or voltage input circuit) and the DSP. The DSP performs computation of voltage, current, active power, apparent power, reactive power, power factor and phase angle, using the output data of the A/D converter.

Computation results are then sent from the DSP to the CPU, where computation such as range conversion, sigma computation and scaling is carried out, and the results are then displayed on the displays of the instrument.



1.2 Functions

Measuring Functions

This function enables measurement of voltage (rms value, mean-value rectification calibration, linear averaging), current (rms value, mean-value rectification calibration, linear averaging) and active power.

 Voltage range
 : 10 V, 15 V, 30 V, 60 V, 100 V, 150 V, 300 V and 600 V

 Current range
 : 1 A, 2 A, 5 A, 10 A, 20 A, 30 A

 External shunt input range : 50 mV, 100 mV and 200 mV

Computing Functions

This function enables computation of active power, apparent power, reactive power, power factor and phase angle, using input voltage and current.

When performing measurements with an external PT and shunt connected, the scaling function is very useful. This function enables display of the measured values in terms of the primary-side values by setting the scaling factor according to the primary/secondary ratio. When this function is used, the active power, apparent power, reactive power and integrated power are multiplied by the scaling factor, then displayed.

An averaging function is also available. This function is used to perform exponential or moving averaging on the measured values before displaying them in cases where the measured values are not stable.

Frequency Measurement Functions

This functions enables measurement of the frequency of an input voltage or input current. Measuring range: 2 Hz to 1 MHz

Integrator Function

This function enables integration of active power and current. Integrated values (power or current) and elapsed time of integration can be displayed during integration. Furthermore, display of positive and negative integrated values is also possible. This enables the positive watt-hour (i.e. watt-hour consumed only in positive direction) and negative watt-hour (i.e. watt-hour returned in negative direction to the power supply) to be displayed independently. However, only the measured power is displayed during integration.

Harmonic Analysis Functions (Optional)

This function enables measurement of up to the 50th harmonic of voltage, current and power, and relative content for each order, as well as phase angle relative to the reference wave for each order, in accordance with IEC1000-3-2. It also enables computation of total rms value (fundamental waveform + harmonics) of voltage, current and total active power, harmonic distortion rate (THD), apparent power and inactive power of the fundamental waveform (first order).

Voltage Fluctuation/Flicker Measurement Functions (Optional)

This function enables measurement of voltage fluctuation and flicker in accordance with IEC 1000-3-3.

External Shunt Input Functions

This function enables measurement of current exceeding 30 A, by using an external voltage-output type shunt.

Built-in Printer (Optional)

The built-in printer enables printing of set-up items. It can also print voltage, current, active power and phase angle in the form of a bar graph during harmonic analysis. Furthermore, the printer can be set so that it automatically prints at certain intervals.

During measurement of flicker, the printer can print the relative steady-state voltage change, maximum relative voltage change and the maximum period during which relative voltage exceeds the threshold level within one voltage change, as well as printing the short-term flicker value and cumulative probability function graph.

Communications Function

Either a GP-IB or RS-232-C interface is provided as standard according to the customer's preference. Measured/computed data can be sent to a personal computer through the interface. It is also possible to control this instrument from the personal computer.

Other Useful Functions

Remote Control Signals and D/A Outputs

The following functions can be performed using remote controlled input/output signals (contact or logic-level (TTL, active low).)

External Input Signals

EXT HOLD

Holds updating of the displayed values or releases the hold status.

EXT TRIG Updates the displayed values in hold mode.

EXT START

Starts integration.

EXT STOP

Stops integration.

EXT RESET

Resets integration.

EXT PRINT

Starts printing.

External Output Signals

INTEG BUSY Output during integration.

FLICKER BUSY

Output during measurement of flicker.

D/A output (optional)

Outputs specified measured items as a DC analog signal with full scale of +/-5V. Output items up to 14 channels can be selected.

Set-up Information Backup Function

The instrument has a function that backs up the set-up information (including integrated values) in case power is cut off accidentally as a result of a power failure or for any other reason.

Set-up Information Initialization Function

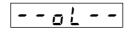
The instrument also has a function that resets the set-up information to the factory settings.

1.3 Over/Error Display during Measurement

Display at Measurement Error

Over range

In normal measurement, an over range occurs if the measured voltage or current exceeds 140% of the rated value for the range used. In auto range setting range, an over range error occurs if **140% of the rated value for the maximum range** is exceeded. The following code will appear on the display in case of an over range.

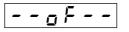


During harmonic analysis, an over range also occurs if the total rms voltage or current value (fundamental waveform + harmonics) exceeds the measuring range as follows.

600 V range	140%
30 A range	140%
20 A range	210%
200 mV range (EXT SENSOR)	140%
Other ranges	250%

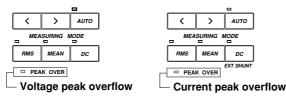
Computation overflow

If a computed value cannot be displayed with the specified decimal point position or unit of measurement, the following code will appear on the display.



Peak overflow

If the peak value of the input voltage or current exceeds approximately 350% of the range (or approximately 700% if the crest factor is 6), the PEAK OVER LED of the element in which the peak overflow occurs will light up.



When measured voltage or current is below 0.3% of the rated value of the range used

If the measured voltage or current is below 0.3% of the rated value, the following will appear on the display. (Applicable when the measurement mode is RMS or MEAN)

Function	Display
V (voltage)	
A (current)	"0" is displayed.
VA (apparent power)	
var (reactive power)	
PF (power factor)	P F E ~ ~
deg (phase angle)	d E 5 E m m

Interruption during measurement

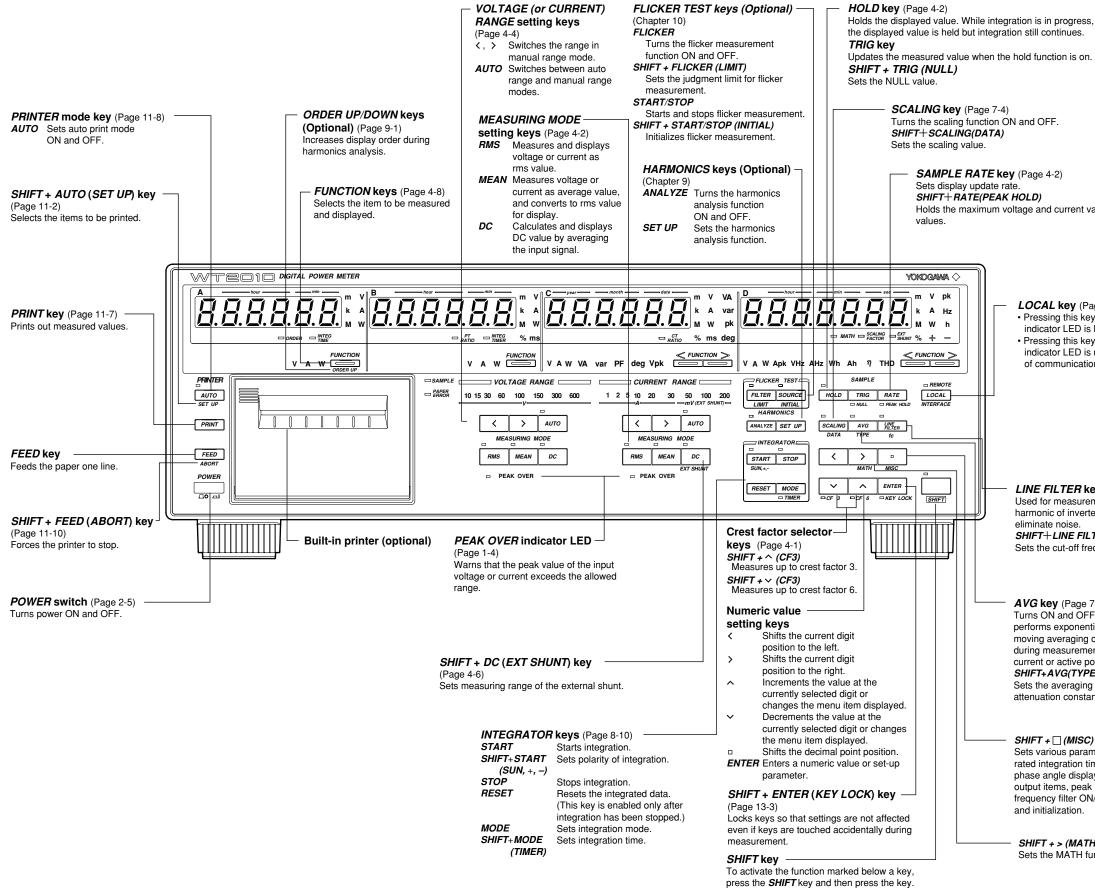
If the measuring range or display item is changed during measurement, the following will appear on the display. It will also appear if no measured or computed value is present due to measurement conditions.



1.4 Part Descriptions and Functions

Front Panel

The number to the right of the name of each key corresponds to the page number where detailed information about the key function can be found.



Holds the maximum voltage and current values in absolute

LOCAL key (Page 14-4) • Pressing this key while the REMOTE indicator LED is lit clears remote state. Pressing this key while the REMOTE indicator LED is not lit allows alteration of communication setting conditions.

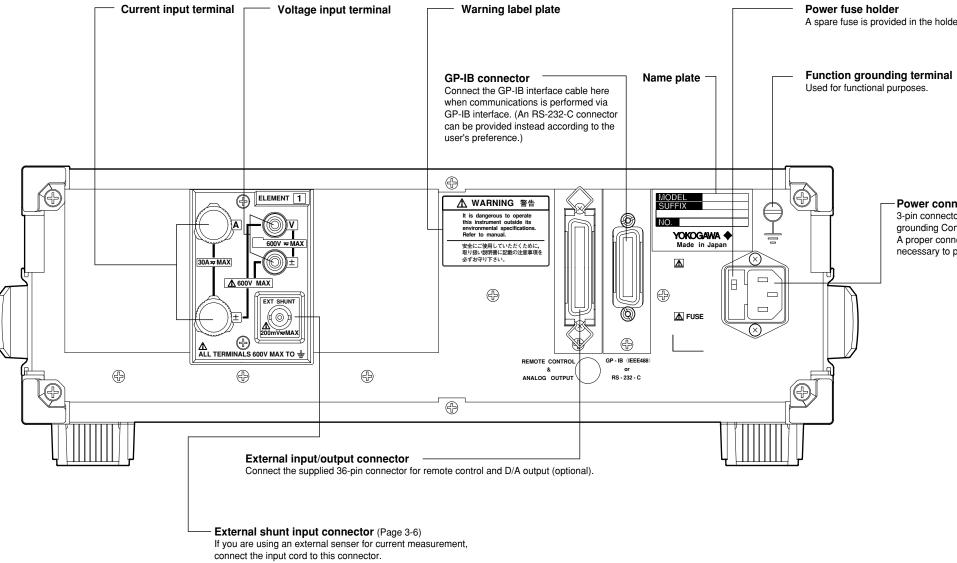
LINE FILTER key (Page 4-1) Used for measurement of fundamental harmonic of inverter waveforms or to eliminate noise SHIFT+LINE FILTER (fc) Sets the cut-off frequency.

AVG key (Page 7-6) Turns ON and OFF the function that performs exponential averaging or moving averaging of measured values during measurement of voltage, current or active power. SHIFT+AVG(TYPE) Sets the averaging type and attenuation constant

SHIFT + (**MISC**) key (Page 2-9) Sets various parameters such as date, rated integration time, D/A output, phase angle display, communication output items, peak hold function, frequency filter ON/OFF, store/recall and initialization.

SHIFT + > (MATH) key (Chapter 7) Sets the MATH function.

Rear Panel



A spare fuse is provided in the holder

-Power connector

3-pin connector providing connection for grounding Connect the supplied power cord here. A proper connection to ground is absolutely necessary to prevent electric shock.

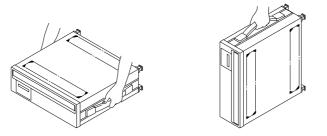
2.1 Usage Precautions

General Handling Precautions

Observe the following precautions when handling the instrument.

- Never place anything on top of the instrument, especially objects containing water. Entry of water into the instrument may result in breakdowns.
- Observe the following precautions when moving the instrument. Disconnect the power cords and connecting cables.

Always carry the instrument by the handles as shown below.



- To prevent internal temperature rise, do not block the vent holes in the instrument case.
- Keep input/output terminals away from electrically charged articles as they may damage internal circuits.
- Do not allow volatile chemicals to come into contact with the case or operation panel. Also do not leave any rubber or vinyl products in contact with them for prolonged periods. Doing so may result in breakdowns.
- The operation panel is made of thermoplastic resin, so take care not to allow any heated articles such as a soldering iron to come into contact with it.
- If the instrument will not be used for a long period, unplug the power cord from the AC outlet.
- For cleaning the case and the operation panel, unplug the power cord first, then gently wipe with a dry, soft, clean cloth. Do not use chemicals such as benzene or thinner, since these may cause discoloration or damage.

Safety Precautions

Do not remove the case from the instrument.

Some areas in the instrument use high voltages, which are very dangerous.

When the instrument needs internal inspection or adjustment, contact your dealer or nearest YOKOGAWA representative.

- If you notice smoke or unusual odors coming from the instrument, immediately turn OFF the
 power and unplug the power cord. Also turn OFF the power to all the objects being measured that
 are connected to the input terminals. If an such irregularity occurs, contact your dealer or the
 nearest YOKOGAWA representative.
- Do not place anything on the power cord. Also keep it away from any heat generating articles. If the power cord is damaged, contact your dealer or nearest YOKOGAWA representative.
- When unplugging the power cord from the AC outlet, never pull the cord itself. Always hold the plug and pull it.

Storage Area

Never store the instrument in places where it may be exposed to any of the following conditions.

- Relative humidity of 80% or higher
 Excessive vibration
- · Direct sunlight

- Corrosive or flammable gases
- Excessive amount of dust, dirt, salt or iron filings
- Proximity to any high-temperature heat sources

• Temperature of 60°C or higher.

Splashes of water, oil or chemicals

2.2 Installing the Instrument

Installation Conditions

- The instrument must be installed in a place where the following conditions are met.
 - · Ambient temperature and humidity
 - Ambient temperature : 5 to 40°C
 - Ambient humidity : 20 to 80% RH (no condensation)
 - · Well-ventilated place

Vent holes are provided on the top and bottom of the instrument. To prevent rise in internal temperature, do not block these vent holes.

Note .

- To ensure high measurement accuracy, the instrument should only be used under the following conditions. Ambient temperature : 23 ±3°C
 - Ambient humidity : 30 to 75% RH (no condensation)

When using the instrument in the temperature ranges of 5 to 18 or 28 to 40°C, multiply the measured values by the temperature coefficient specified in Chapter 16, "Specifications."

- If the ambient humidity of the installation site is 30% or below, use an anti-static mat to prevent generation of static electricity.
- Internal condensation may occur if the instrument is moved to another place where both ambient temperature and humidity are higher, or if the room temperature changes rapidly. In such cases acclimatize the instrument to the new environment for at least one hour before starting operation.

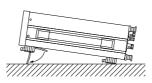
Never install the instrument in the following places. Otherwise, the internal circuits and the case may be affected adversely, hindering accurate measurement.

- · In direct sunlight or near heat sources
- Where an excessive amount of soot, steam, dust or corrosive gases is present.
- Near magnetic field sources
- · Near noise sources such as high voltage equipment or power lines
- · Where the level of mechanical vibration is high
- In an unstable place

Installation Position

Desktop Installation

Place the instrument in a horizontal position or tilted using the stand as shown below.



Rack Mount

To install the instrument in a rack, use one of the following optional rack mount kits.

Rack mount kit (optional)

Model	Standard
751535-E3	EIA IIS

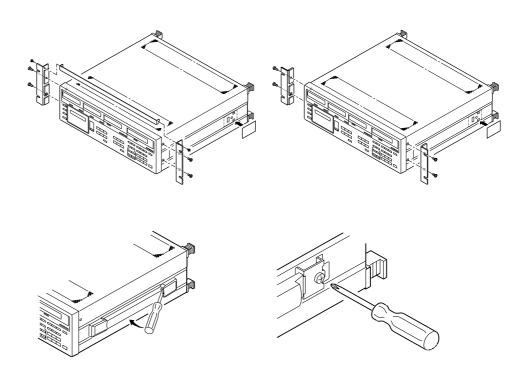
Mounting Procedure

- 1. Remove the seal cover from the mounting holes on both sides of the instrument. (Four seal covers in total)
- 2. Attach the mount kit as shown below.
- 3. Remove the four legs from the bottom of the instrument.
- 4. Remove the handle from each side of the instrument.
- 5. Cover each handle mount hole with a seal.
- 6. Mount the instrument in the rack.
 - When mounting the instrument, support it from underneath.
 - Refer to Chapter 16, "Specifications" for rack mounting dimensions.

Note .

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 The upper and lower sides of the instrument are equipped with ventilation holes. When these are blocked e.g. due to rack mounting, the specified accuracy may not be met, therefore allow at least 20 mm of space between the ventilation holes and the rack mount.



2.3 Power Supply Connection

Power Supply Requirements

The useable supply voltage of this instrument varies depending on the suffix code.

Suffix code	: -1	-3	-5	-7
Rated supply voltage	: 100 VAC	115 VAC	200 VAC	230 VAC
Permitted supply voltage range	e: 90 to 110 VAC	100 to 132 VAC	180 to 220 VAC	198 to 264 VAC
Rated supply voltage frequenc	y : 50/60 Hz	50/60 Hz	50/60 Hz	50/60 Hz
Permitted supply voltage				
frequency range	: 48 to 63 Hz	48 to 63 Hz	48 to 63 Hz	48 to 63 Hz



- Before plugging in the power cord, make sure that the voltage of the AC outlet fits with the rated supply voltage on the rear panel of the instrument.
- When checking the power supply fuse, refer to Section 15.3 "Replacing the Power Supply Fuse" (page 15-4).
- When checking the power cord, refer to the ratings specified in the suffix code in "Checking Package Contents" (page 2).

Connecting the Power Cord



- Be sure to connect the protective grounding to prevent an electric shock before turning on the power. Connect the power cord only after having verified that the power switch is turned OFF.
- Before plugging in the power cord, make sure that the voltage of the AC outlet is within the specified range.
- To prevent electric shock or fire, use only the power cord supplied by YOKOGAWA.
- Never use an extension cord without a grounding wire, otherwise the protection feature will be invalidated.

2.4 Turning the Power ON or OFF

Items to be Checked Before Turning ON the Power

- Check whether the power supply voltage from the AC outlet matches the one selected by the voltage selector switch.
- Check that the instrument is installed correctly as instructed in Section 2.2 "Installing the Instrument" (page 2-2).

Location of the Power Switch

The power switch is located in the lower left corner of the front panel.

Turning Power ON/OFF

A pushbutton switch is used as the power switch. The power is turned ON and OFF alternatively as the switch is pressed.

Note .

- The instrument uses a lithium battery so that set-up information together with the date and time entered from the operation panel will be backed up and not lost in case of power failure.
- A warm-up time of approximately 30 minutes is required before all specifications of the instrument are met.
 However, a warm-up time of approximately 2 hours is required before start of flicker measurement.

Response and Display at Power ON

When the power switch is turned ON, the test program starts. The test program checks each memory. If the check results are satisfactory, opening messages will appear as shown on page 2-7, and the instrument is ready for measurement.

If an error code appears at the end of the test program, the instrument is not functioning properly. In this case, turn OFF the power immediately, and contact your dealer or the nearest YOKOGAWA representative. Inform them of the model name and serial no. specified on the name plate on the rear panel, as well as the error code that was displayed.

Note .

In the case of an error code, refer to Section 15.2 "Error Codes and Corrective Actions" (page 15-2), and carry
out the specified corrective actions.

Response at Power OFF

When the power switch is turned OFF, the set-up information which was in effect just prior to the power switch being turned OFF will be retained. Thus, when the power switch is next turned ON, the operation state of the instrument just prior to the power switch being turned OFF will be resumed.

Note

The set-up information is backed up by a lithium battery. The battery lasts for approximately ten years if it is
used at an ambient temperature of 23°C. If the battery runs out, an error code appears when the power switch
is turned ON (refer to 15.2, "Error Codes and Corrective Actions"). In this case, the battery needs to be
replaced immediately. The battery cannot be replaced by the user. Contact your dealer or the nearest
YOKOGAWA representative.

Default Settings (Factory Initialization Settings)

	Display	Factor	LED
Display	A	V1	V
	B C	A1 W1	A kW
	D	W1 W1	kW kW
Massuring range	VOLTAGE	600V	600V
Measuring range	AMP	30A	30A
	Shunt scaling value	50.000A/FS	JUA
Measurement mode	RMS/MEAN/DC	RMS	RMS
Measuring conditions	Wiring system	1¢2W	
	Hold	OFF	
	Sample rate	500ms	
	Scaling	OFF	
	Averaging	OFF	
	Line filter	OFF	
	Cut-off frequency	0.5kHz	
	Crest factor	3	
	Peak hold Peak hold function	OFF Peak	
	Frequency filter	OFF	
	NULL function	OFF	
	Integration	Invalid	
	Harmonic analysis (optional)	OFF	
	Phase angle display	180°	
	MATH	Crest factor for volta	ge (FFHI)
	Key lock	OFF	
Scaling constant	Kv	1.0000	
-	Ki	1.0000	
	Kw	1.0000	
Averaging	Averaging method Attenuation constant	Exponential averagir	ng(EP)
			1 /
Integration	Integration mode	Standard integration	mode(חם ר
	Integration timer	0 h 0 min SUM	
	Integration polarity	SUM	
Communications Command group	Used to select 2531 command	CM3 (WT2000 com	mand group)
Command group	group whether the scaling	CIVI5 (W 12000 com	nand group)
	constant is to be selected for all		
	the elements at once or for one		
	element at a time. Also used to		
	select WT2000 command group		
	or 2533E command group.		
GP-IB	Address	1	
	Output interval during	0 s	
	talk-only mode		
	Communication mode	A	
	Status byte	15 CD-1 E	
	Delimiter	CR+LF	
RS-232-C	Communications mode	Normal	
	Output interval during	0 s	
	talk-only mode	0	
	Handshake mode	0	
	Format	0	
	Baud rate Delimiter	9600 CD+LE	
	Status byte	CR+LF 15	
	2		
GP-IB,RS-232-C Common	Communications output	ASCII	
- ,	Communications output function	dFLE-1	

Harmonic analysis (optional)	Display format PLL source Number of orders THD equation Harmonic order Anti-aliasing filter Window width	n-th harmonic V1 50 IEC 1 OFF 16
Flicker measurement (optional)	Existing rated voltage Limit for relative steady-state voltage change Limit for maximum relative	Auto 230 V ON, 3.00%
	voltage change Duration during which voltage exceeds the threshold level	ON, 4.00%
	within one voltage change Limit for short-term flicker value	ON, 200 ms, 3.00% ON, 1.00
	Limit for long-term flicker value Constant used in the equation for	ON, 0.65
	long-term flicker value Observation period for short-term flicker value	12 10 min
	Number of times measurement is performed for short-term flicker value Steady-state range	
Printer (optional)	Auto print mode Print interval Print synchronization Print output function	OFF 1 min Synchronize to time dFLE- ↓
D/A output (optional)	D/A output Rated integration time for D/A output	<i>ሬ Բ Լ Է - </i>

Opening Messages

When the power switch is turned ON, the following messages will appear. The messages vary depending on the options used. If the power switch is turned ON with the *SHIFT* key held down, no message for any optional functions will be displayed. Once this is done, no message for any optional functions will be displayed whenever the power switch is turned ON. To display messages for optional functions, turn ON the power switch again while holding down the *SHIFT* key.

	Display A	Display B	Display C	Display D	٦
(Power ON (POWER) ON →	255000	Blank	Blank	£85£	
\sim		♦ All displays	light up.		
Messages vary depending on the options			Blank	Blank	7
used.	Model	ROM ve	rsion		4
	When D/A output option 모르고 기다		d₽_c	Blank	
	When printer option is u	B	Pr, n <u>k</u> c	Blank	
	When harmonic analysis	s option is used	HRrāc	Blank	►
	When FLICKER TEST fu	nction option is used			f
	2F5010 v	់ព្រូ រ ^B	FL'ERc	Blank D	
	When GP-IB interface is	incorporated and ad		selected	Γ.
	775010 v	l III B	<u>СР, Б</u> С	Rddr.R ^D	
	When GP-IB interface is	incorporated and ad		selected	7
	2F5010 v		<u>СР, Б</u> С	Rddr.b	
	When GP-IB interface is		k-only mode is seled		f
	<u> 465010</u>	10 I B	<u>СР.</u> ЬС	toniy D	
	When GP-IB interface is	incorporated and 48	8.2 mode is selected		=
	265010 *		<u>С</u> Р, Ь <mark>С</mark>	4882 ^D	┢
	When GP-IB interface is	incorporated and ad		is selected	7
	9550 10 *	10 I B	<u>69.6</u>	Adrr 1	
	When RS-232-C interface				f
	<u>455010</u>	10 l	-5232[C	nor D	
	When RS-232-C interfac	e is incorporated and	I talk-only mode is s	elected	٦
	<u>455010</u>	10 I B	~5232C	tonly D	
	When RS-232-C interfac	e is incorporated and	1 488 2 mode is sele	cted	7
	<u>455010</u>		<u>-5232</u>	488.2 D	
	When RS-232-C interfact	e is incorporated 님유규립급 ^B	ForGo	6-9600 ⁰	
		Handshake	Data format	Baud rate	
	NO	Are messa	iges for es and options		
		display	ed?	Desit (
		YES 🗆		Ready for measureme	

Setting the Date and Time 2.5

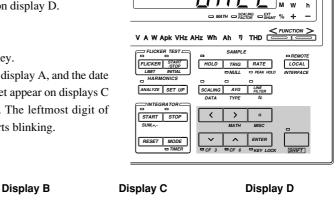
Setting the Date/Time Mode

Mode Setting

1. Press the **MISC** key (**SHIFT** + \Box) Keep pressing the up \land or \lor key until " $\exists R \vdash E$ " appears on display D.

2. Press the **ENTER** key.

" $d R \in E$ " moves to display A, and the date and time currently set appear on displays C and D respectively. The leftmost digit of display C (date) starts blinking.





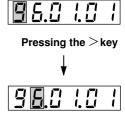
Setting the Date and Time

- 3. Set the desired value for the blinking digit using the \wedge or \vee key. Press the \langle or \rangle key to move to another digit and set a value. Repeat this step until the entire date has been set.
- 4. When the entire date has been set, press the **ENTER** key. This causes the leftmost digit of display D (time) to start blinking. Repeat step 3 to set the desired time.
- 5. When the time has been set, press the **ENTER** key. The timer begins to operate.

Shifting the Blinking Position

The blinking position can be shifted to the left or right by pressing the < or > key. Pressing the < key causes the digit to the left of the currently blinking digit to blink, and pressing the > key causes the digit to the right of the currently blinking digit to blink. The blinking position wraps around in both directions.

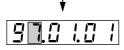




Setting a Value

To select a value for the blinking digit, press the \wedge or \vee key. Pressing the \wedge key changes the value according to the sequence 1, 2, 3 ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction.





Note .

- If the time is not set properly, "E - IB" will appear.
- · Years whose final two digits are less than "96" will be treated as 21st century years.

00	\rightarrow	2000
	•	•
	•	•
95	\rightarrow	2095
96	\rightarrow	1996
	•	•
	•	•
	•	•
99	\rightarrow	1999

YOKOGAWA 🔶

Hz Δ

3.1 Wiring Precautions

To prevent hazards, a protective grounding connection must be made as follows. The power cord supplied with the instrument has a 3-pin plug. One of the three pins is used for grounding. The power cord must be connected to a 3-pin AC outlet (including a grounding terminal).

- Always turn OFF the power to the object being measured, before connecting it to the instrument. Never connect or disconnect the measurement lead wires from the object while power is being supplied to it, otherwise a serious accident may result.
- Be sure that you do not connect a current circuit to the voltage input terminal or vice versa. Incorrect connection may cause damage not only to the circuit or equipment under test and to this instrument, but may also endanger the operator.
- When the power switch is ON, never apply a voltage or current exceeding the level specified in the table below to the voltage input terminal or current input terminal. If the power switch is OFF, turn OFF the power to the object.

Permissible Maximum Input	Voltage Input	Current Input
Maximum Instantaneous Input (for 1 s)	The peak value is 2.5 kV or RMS value is 3.0 kV, whichever is the lower.	The peak value is 90 A or RMS value is 50 A, whichever is the lower. Peak current of 20 times the rated measuring range or lower in the case where an external input is used
Maximum Continuous Input	The peak value is 1.4 kV or RMS value is 2.5 kV, whichever is the lower.	The peak value is 60 A or RMS value is 35 A, whichever is the lower. Peak current of 10 times the rated measuring range or lower in the case where an external input is used

- If you want to use an external current transformer (CT), use one which has a sufficient withstand voltage against the voltage to be measured. Also be sure not to allow the secondary side of the CT to go open-circuit while power is supplied, otherwise an extremely dangerous high voltage will be generated on the secondary side of the CT.
- If the instrument is used in a rack, provide a power switch so that power to the instrument can be shut off from the front of the rack in an emergency.
- Make sure that the bare end of the measurement lead wire connected to each input terminal does not protrude from the terminal. Also make sure that the measurement lead wires are connected to the terminals securely. Do not use any plug-in type terminal with protruding bare lead wire (e.g. banana-shaped terminal connector) to connect the object to the voltage terminal. This may lead to a very dangerous situation if the input terminal is disconnected.
- The voltage ratings across the measuring (voltage and current) input and the ground for this instrument varies under operating conditions.
- When protective covers are used on GP-IB or RS-232-C and external input/ output connectors

Voltage across each measuring input terminal and ground 600 Vrms max.

- When protective covers are removed from GP-IB or RS-232-C and from external input/output connectors; or when connectors are used
 - Voltage across A, \pm (V and A side) input terminals and ground 400 Vrms max. Voltage across V terminal and ground 600 Vrms max.

```
• The lead wires must have a sufficient margin in both breakdown voltage and current against those to be measured. They must also have insulation resistance appropriate to their ratings.
```

Example: If measurement is carried out on a current of 20 A, use copper wires with a conductor cross-sectional area of at least 4 mm².

Note .

- When measuring high currents, or currents or voltages that contain high-frequency components, wiring should
 be made with special attention paid to possible mutual interference and noise problems.
- · Keep the lead wires as short as possible.
- For current circuits indicated by thick lines in the wiring diagrams shown in Section 3.2 (page 3-2 and subsequent pages), use thick lead wires appropriate for the current to be measured.
- The lead wire to the voltage input terminal should be connected as close to the load of the object under measurement as possible.
- To minimize stray capacitance to ground, route both lead wires and grounding wires so that they are as away from the instrument's case as possible.

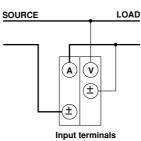
3.2 Wiring the Measurement Circuit

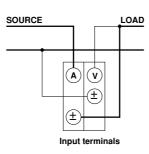
The table below gives a list of wiring systems and their examples (diagrams) for each wiring system.

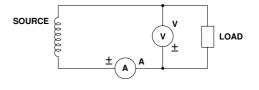
Wiring Diagram	When an input is applied directly	Fig.3.1
	When PT and CT are used (page 3-5)	Fig.3.4
	When an external shunt is used (page 3-7)	Fig.3.7

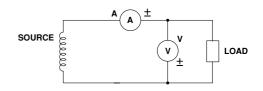
Wiring Method when Voltage and Current are Applied Directly

Fig. 3.1 Wiring Diagram











When applying a current to be measured directly to the input terminals of the instrument, make sure that the external shunt cable is not connected to the instrument.

A load current flows in the thick lines shown in the diagrams, therefore a wire with sufficient current capacity must be used for these lines. The wire connected from the source to the \pm current terminal must be routed as close as possible to the ground potential in order to minimize measurement error. (Refer to "Note" on page 3-3.)

Note

The wire connected from the source to the ± current terminal must be routed as close as possible to the ground
potential in order to minimize measurement error. Fig. 3.2 shows the input circuit diagram of the instrument.

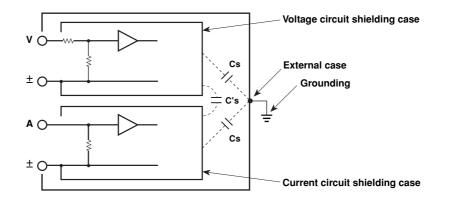


Fig. 3.2 Input Circuit of the Instrument

The voltage circuit is enclosed in its own shielding case, and the current circuit is also enclosed in its own shielding case. Both shielding cases are then enclosed in the external case. The voltage circuit shielding case is connected to the \pm voltage terminal, whilst the current circuit shielding case is connected to the \pm current terminal.

Although insulation is provided between the shielding cases as well as between the external case and each shielding case, stray capacitance Cs and C's are still present. Cs is approximately 100 pF. With power meters such as this instrument that are capable of measurement of current, voltage etc. of high frequency, these stray capacitance cannot be ignored as they cause measurement errors.

As an example, let's imagine the circuit shown in Fig. 3.7, where one end of the SOURCE (power source) and the external case are grounded. Current iL from the power source enters the current terminal (A), passes the shunt, comes out from the current terminal (\pm), then returns via the LOAD (load) to the power source, as indicated by the dotted line. The other route (iCS) is indicated by the dashed line; from the power source, through the shunt, stray capacitors, external case grounding, and power source grounding.

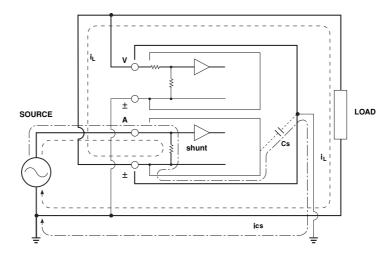


Fig. 3.3

From this, it is obvious that the sum (vector sum) of the load current iL and ics, which flows through the stray capacitors, is always measured even though we want to measure load the current iL only. The current ics, which flows through the stray capacitor Cs, is calculated as follows.

Where, the common-mode voltage applied to Cs is VCs ics = VCs × $2\pi f \times Cs$ 3

Wiring

In the upper circuit shown in Fig. 3.1, no measurement error will occur since V_{Cs} is zero because both current terminal (\pm) and voltage terminal (\pm) are close to the ground potential. Effects of the stray capacitance are calculated below for reference.

 $\mathrm{Cs} = 100 \mathrm{pF} = 100 \times 10^{-12} \mathrm{F} = 10^{-10} \mathrm{F}$

Therefore,

ics[A] = VCs[V] × $2\pi f[Hz]$ × Cs = VCs × $2\pi f$ × 10⁻¹⁰

 $= 2\pi \times 10^{-4} \times VCs \times f[kHz] [mA]$

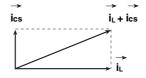
Assuming f = 100kHz, VCs = 100V, ics = 6.28mA

If iL = 1A, the current is expressed as a vector sum, as below, where the load consists of resistance only (i.e. $COS\phi = 1$),

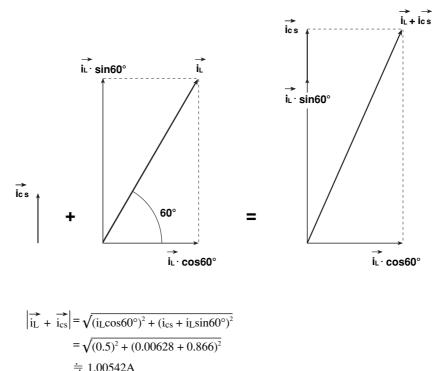
$$\left|\overrightarrow{i_{L}} + \overrightarrow{i_{cs}}\right| = \sqrt{1^{2} + 0.00628^{2}}$$

$$= 1.00002$$

Therefore, the measurement error is 0.0002%, indicating that the effect on the measurement of the stray capacitance is very slight.



If $COS\phi = 0.5$, the current can be obtained as follows.



≡ 1.00542A

Therefore, the measurement error is 0.542%.

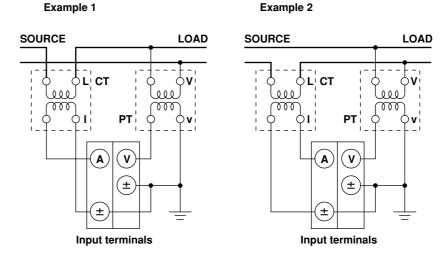
If $COS\phi = 0$, iL + ics = 1 + 0.00628 = 1.00628, therefore, the measurement error is 0.628%. Since active power is obtained using the equation W = VA $COS\phi$, the error is the same as that in the measurement of the current.

Wiring Method when PT and CT are Used

Use of a PT (or CT) enables measurement of voltage or current even if the maximum voltage or maximum current of the object to be measured exceeds the maximum measuring range.

- If the maximum voltage of the object to be measured exceeds 600 V, connect an external potential transformer (PT), and connect the secondary side of the PT to the voltage input terminals.
- If the maximum current of the measuring object exceeds 30 A, connect an external current transformer (CT), and connect the secondary side of the CT to the current input terminals. In the diagrams below, the thick lines represent the current circuit, and the thin lines represent the voltage circuit.

Fig. 3.4 Wiring Example with PT and CT Connected



WARNING When using an external CT, do not allow the secondary side of the CT to go opencircuit while power is supplied, otherwise an extremely dangerous high voltage will be generated on the secondary side of the CT.

Note

- Use of the scaling function enables direct reading of measured values on the display. For a description of how to set the scaling function, refer to Section 7.3 "Using the Scaling Function" (page 7-4).
- · It must be noted that measured values are affected by the frequency and phase characteristics of PT and CT.

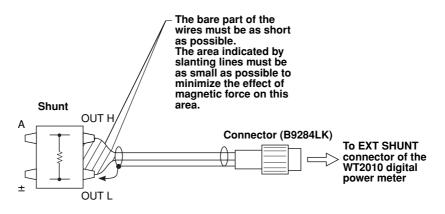
က Wiring

Wiring Method when External Shunt is Used

In cases where the maximum current of the object to be measured exceeds 30 A, connect a voltageoutput type current shunt having the desired rated current to the external shunt input connector. The sensor must have appropriate frequency and phase characteristics.

Connecting an External Shunt to an External Shunt Input Cord

Connect the shielding wire of the cord to the output terminal (OUT L) of the shunt, as shown below, to minimize measurement error.



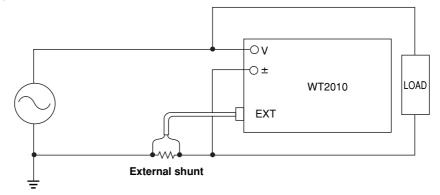
Since 50, 100 and 200 mV ranges are available for the external shunt, use an external shunt whose voltage drop matches these ranges. If an external shunt that does not match these ranges is used, convert the measured values on the display to input current values using the scaling function. Refer to Section "4.2 Setting Measuring Ranges" (page 4-4).

- For safety, use a shunt that is enclosed in a case and whose wires are isolated from the case. Also make sure that the shunt has a sufficient withstand voltage against the voltage to be measured. Use of a bare shunt may cause an electric shock if the shunt is touched accidentally.
- A voltage is present on the current terminal of the instrument while power is supplied to the measurement circuit, so the current terminal should never be touched nor should the measurement lead wire be connected to it.
- The connector to be connected to the external shunt input connector (EXT SHUNT) must be constructed in such a way that no lead wires are exposed. It is dangerous not to follow this instruction since a voltage is present on the lead wires while power is supplied to the measurement circuit.
- Do not connect anything to the input current terminals (A, ±) of the instrument, otherwise damage to the instrument or personnel injury may result.
- Before connecting an external shunt, make sure that the power to the shunt is turned OFF. A voltage is present on the external shunt while power is supplied to it, so do not touch the shunt with your hands.

Note

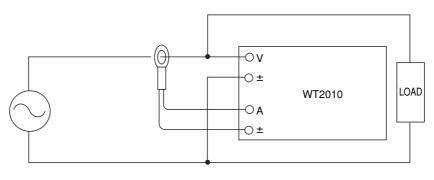
- The external shunt must be selected carefully and its frequency and phase characteristics taken into account.
- The external shunt must be wired so that the area between the wires connected to both ends of the shunt is minimized, in order to reduce the effect of the magnetic field generated by the current to be measured. Measurement is affected by magnetic field lines entering this area. Minimizing this area also reduces the effects of external noise.
- To avoid the effects of common-mode voltage, the external shunt must be connected to the grounding side of the power source.

Fig. 3.5

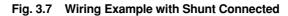


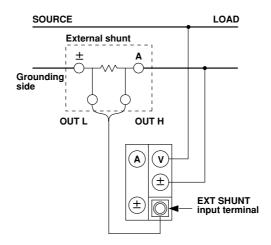
 If the measuring object is high frequency and high power and is not grounded, the effects of inductance present on the shunt connecting cable will be increased. In this case, use an isolation sensor (CT, DC-CT, clamp).





For safety, use a shunt that is enclosed in a case. Use of a bare shunt may cause an electric shock if the shunt
is touched accidentally. If a case is provided separately, the case must have a sufficient withstand voltage
against the voltages to be measured. However, this requirement does not need to be met if the shunt is
connected to the grounding side of the power source as shown in Fig. 3.5, the single-phase, two-wire system.





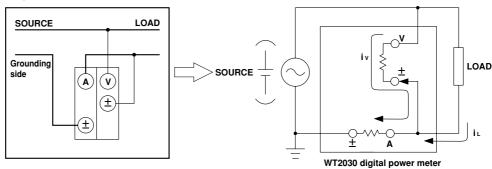
3.3 Improving Measurement Accuracy

Recommended Wiring Method

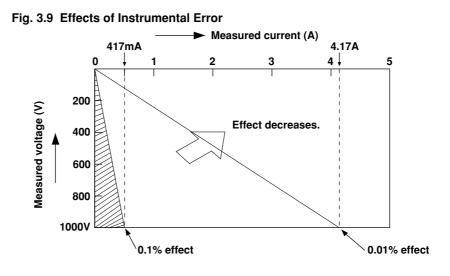
This instrument is designed so that voltage input impedance is high and current input impedance is low to reduce the effect of instrumental loss on measurement accuracy.

Voltage input impedance : Approximately 2.4 M Ω (all ranges), with a capacitance of approximately 13 pF connected in parallel Current input impedance : Approximately 6 m Ω + 0.07 µH (all ranges)

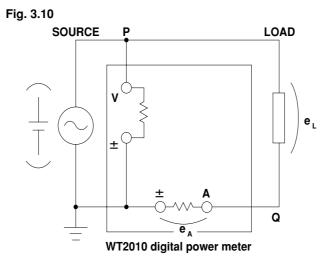




In the above diagram, the voltage measurement circuit is connected to the load side. The effects of instrumental loss on measurement accuracy are explained below. To simplify understanding, it is assumed that a DC power source and resistive load are used. The current measurement circuit measures the sum of the current iL that flows to the load (object being measured) and the current iV that flows to the voltage measurement circuit. This means that the current iV is erroneous since the current to be measured is iL. Since the input impedance of the voltage measurement circuit is high (approximately 2.4 M Ω), and even if the input voltage is 600 V iV becomes approximately 0.25 mA (=600 V/2.4 M Ω). If the instrumental error is assumed to be below 0.1%, the measured current (iL) will be 250 mA or higher (load resistance: 2.4 Ω or lower). If the input voltage is 10 V, iL is 4.2 mA or higher. The relationship between the input voltage and the measured current in cases where instrumental error is within 0.1% and 0.01% is given on the next page as a reference.



In many cases the recommended wiring method is suitable. For instance, when the input voltage and current are 100 V and 5 A, iV is 0.04 mA (=100 V/2.4 M Ω), therefore the effect on measurement accuracy is 0.0008% (=0.04 mA/5 A), which is low. On the other hand, measurement accuracy is significantly affected when the measured current is low (i.e. high load resistance). In this case, make the connections as follows so that the current measurement circuit is located on the load side. The voltage measurement circuit measures the sum of the voltage drop eL at the load and eA at the current measurement circuit, therefore eA is erroneous. However, the effect of this error is small since the input impedance of the current measurement circuit is low. For instance, if the load resistance is 600 Ω , the input impedance is approximately 6 m Ω , therefore the error in measurement is approximately 0.001% (=eA/(eL + eA)), which is low.



From the above explanation, it can be understood that the effect of instrumental loss on measurement accuracy can be reduced by wiring according to the load resistance.

4.1 Setting Measuring Conditions

Setting the Crest Factor

The crest factor for the input can be set to either "3" or "6" using the crest factor setting key.

	YOKOGAWA 🔶
To set the crest factor to "3" Press the CF3 key (<i>SHIFT</i> + \lor).	D NOW → NOW
To set the crest factor to "6"	V A W Apk VHz AHz Wh Ah り THD
Press the CF6 key (SHIFT + \land).	FLICKER TEST SAMPLE DEMOTE FLICKER STAPF HOLD TTRIG RATE LOCAL UNIT NITAL DNUL DEMOTE LOCAL INTERFACE
The LED for the selected crest factor will light up.	AMALVZE SET UP SCALING AVG MERE DATA TYPE to "INTEGRATOR" START STOP SUMA RESET MODE
	TIMER CF 3 CF 6 KEY LOCK SHIFT

Note

- Measurement accuracy in the case of a crest factor of 6 will be 1.5 times the range error for a crest factor 3.
- The crest factor cannot be changed while integration or measurement of voltage fluctuation/flicker is in
 progress or when it has been interrupted.

Measuring with Line Filter ON

Use of a line filter during normal measurement of PWM waveforms, such as inverter waveforms, has the following advantages.

- In the case of measurement of voltage and current, similar results to those obtained in the measurement of fundamental waveforms can be obtained. Measured values are also the same as those obtained in the MEAN measurement mode.
- In the case of measurement of power, similar results to those obtained in the measurement of fundamental waveforms can also be obtained.

It is also possible to select cut-off frequency suitable for the fundamental component of the waveform to be measured.

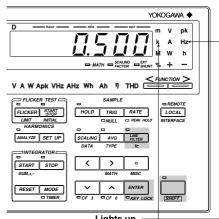
• A 5th order butterworth lowpass filter is used.

Setting the Cut-off Frequency

- Press the *fc* key (*SHIFT* + *LINE FILTER*). Display C displays "*F_c*" and display D displays the currently selected cut-off frequency.
- 2. The cut-off frequency on display D changes in the following order each time the \wedge key is pressed, so select the desired cut-off frequency.

 $0.500 \rightarrow 5.500 \rightarrow 0.500 \rightarrow \ldots$

Pressing the \lor key causes the cut-off frequency to change in the opposite order. The cut-off frequency is displayed in units of kHz. The default is 0.500.



Lights up. -

3. Press the **ENTER** key.

Turning Filter ON or OFF

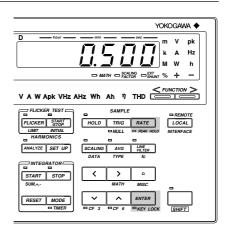
Press the *LINE FILTER* key. The LED above the *LINE FILTER* key is lit when the filter is ON.

Note

- The line filter cannot be turned ON and OFF during integration
- Pressing the LINE FILTER key during harmonic analysis will allow you to turn the anti-aliasing filter ON and OFF. The cut-off frequency of the anti-aliasing filter is 5.5 kHz.

Setting the Display Update Cycle (Sample Rate)

- Press the **RATE** key. Display C displays
 "5 - R E E" and display D displays the currently selected sample rate.
- 2. The sample rate on display D changes in the following order each time the ∧ key is pressed, so select the desired sample rate.
 □ 5 □ □ (500 ms) → 2 □ □ □ (2 s) → □ 2 5 □ (250 ms) → □ 5 □ □ → ...
 Pressing the ∨ key causes the sample rate to change in the opposite order



Sample Rate	Lower Limit Frequency (for Measurement of V, A and	Frequency Range d W)
250ms	20Hz	20 Hz $\leq f \leq 1$ MHz
500ms	10Hz	$10Hz \le f \le 500kHz$
2s	2Hz	$2 \mathrm{Hz} \leq \mathrm{f} \leq 100 \mathrm{kHz}$
Default setting	is 0.500 (500 ms)	

3. Press the **ENTER** key.

Note -

• The sample rate is fixed at 2 seconds during integration and measurement of voltage fluctuation/flicker.

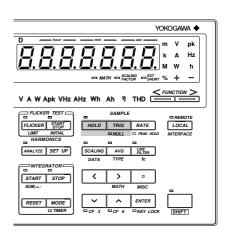
Display and Data Output

Holding Display and Output

To hold the currently displayed measured values, press the *HOLD* key. The LED above the *HOLD* key will light up, indicating that the hold function is currently on. Pressing the *HOLD* key again causes the LED to go out, indicating that the hold function is now off.

Updating the Data during Hold Mode

Pressing the **TRIG** key while the HOLD indicator LED is lit will update the measured values. The measured values are also updated when the external trigger signal is received.



If the measured values are output (by means of a communications channel or the D/A converter), the output values are also updated when the **TRIG** key is pressed.

Voltage and Current Measurement Modes

One of the following measurement modes can be selected for measurement of voltage and current.

- RMS : Measures and displays true rms value.
- MEAN : Displays rectified mean value calibrated to the rms value.
- DC : Displays DC value obtained by averaging the input signal.

The default setting for measurement mode is RMS.

RMS

This mode is used to display input voltage or current as a true rms value. The theoretical equation is given below.

$$\sqrt{\frac{1}{T}} \int_{0}^{T} f(t)^{2} dt$$

 $\begin{array}{l} f(t): \mbox{ Input signal} \\ T &: \mbox{ One period of the input signal} \end{array}$

MEAN

This mode is used to display input voltage or current as a rectified mean value calibrated to the rms value. Since a sine wave is used for calibration, the value displayed will be the same as that obtained in RMS mode if a sine wave is measured. However, the value displayed will be different from that obtained in RMS mode if a distorted or DC waveform is measured. The theoretical equation is given below.

$$\frac{\pi}{2\sqrt{2}} \cdot \frac{2}{T} \int_{0}^{\frac{T}{2}} |f(t)| dt$$

f(t) : Input signal T : One period of the input signal

DC

This mode is used when the input voltage or current is DC. The input signal is averaged and the result is displayed.

Typical Waveform Types and Differences in Measured Values Between Measurement Modes

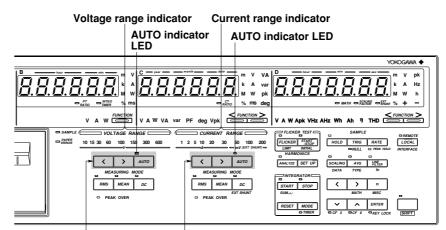
	Measurement mode	rms value	Mean value	Mean-value rectification	Linear averaging
Name	Display Waveform	RMS	_	MEAN	DC
Sine Wave		$\frac{Ep}{\sqrt{2}}$	$\frac{2}{\pi}$ • Ep	$\frac{\text{Ep}}{\sqrt{2}}$	0
Half-wave rectification	$\int_{0}^{\pi} \int_{\pi} \int_{2\pi} E^{\mu}$	Ep2	<u>Ер</u> л	$\frac{\text{Ep}}{2\sqrt{2}}$	<u>Ep</u> π
Full-wave rectification	$\int_{0}^{\pi} \frac{1}{\pi} \frac{1}{2\pi} E^{\mu}$	$\frac{\text{Ep}}{\sqrt{2}}$	$\frac{2}{\pi}$ • Ep	$\frac{\text{Ep}}{\sqrt{2}}$	$\frac{2}{\pi}$ • Ep
Direct current	ţe) Ep	Ep	$\frac{\pi}{2\sqrt{2}} \bullet \text{Ep}$	Ep
Triangular wave	0 π 2π E	$\frac{\text{Ep}}{\sqrt{3}}$	<u> </u>	$\frac{\pi}{4\sqrt{2}}$ • Ep	0
Square wave	0 π 2π	Ер	Ер	$\frac{\pi}{2\sqrt{2}} \cdot \text{Ep}$	0
Pulse	→ τ ←	$\int \frac{\tau}{2\pi} \cdot \mathrm{Ep}$	$\frac{\tau}{2\pi} \cdot Ep$	$\frac{\pi \cdot \tau}{4\pi \sqrt{2}} \cdot \text{Ep}$	$\frac{\tau}{2\pi}$ • Ep
	$ \begin{array}{c c} & \rightarrow & \tau & \leftarrow \\ \hline & & & & \\ \hline & & & & \\ 0 & & & 2\pi \end{array} $			$\frac{\tau}{2\pi}$) is applied	
		$\sqrt{D} \cdot Ep$	D•Ep	$\frac{\pi \cdot \mathbf{D}}{2\sqrt{2}} \cdot \mathbf{E}\mathbf{p}$	D • Ep

4.2 Setting Measuring Ranges

Manual and Auto Range Setting

Measuring Range Setting Method

There are two methods of setting the measuring range; auto range setting, in which the most suitable range is selected automatically, and manual range setting, in which the range is selected manually.



Voltage range setting key Current range setting key

Manual Range Setting

When the AUTO indicator LED is not lit, manual range setting mode is valid. In this mode, the next lowest or highest range can be selected manually by pressing the < or > key respectively. If the AUTO indicator LED is lit, press the < or > key. This will cause the AUTO indicator LED to go out, indicating that manual range setting mode is valid.

Auto Range Setting

When the AUTO indicator LED is lit, auto range setting mode is valid. The measuring range is switched automatically according to the input voltage or current.

- Range Up : A higher range is selected immediately if the instantaneous input voltage or current exceeds approximately 350% of the rated value (or approximately 700% if the crest factor is 6) during sampling. If the measured voltage or current exceeds 110% of the rated value, or if an over range for the measured value occurs during harmonic analysis, a higher range will be selected at the end of the current measurement cycle (i.e. at the next update).
- Range Down : A lower range is selected if the measured voltage or current drops below 30% of the rated value.

Switching from Auto Range Setting to Manual Range Setting (when the AUTO Indicator LED is Lit)

Switching to manual range setting can be performed using one of the following procedures. Procedure

Press the < or > key.
 The AUTO indicator LED will go out, and manual range setting mode becomes valid. The next highest or lowest range relative to the range set in auto range setting mode will be selected.

Press the *AUTO* key.
 The AUTO indicator LED will go out and manual range setting mode becomes valid.

Note

- In auto range setting mode, the range may be switched frequently if a waveform such as a pulse, which has a high crest factor, is input. In this case, set the range manually.
- "- - - " will be displayed if no measured data is present, measuring range will not be selected automatically even if auto range setting mode is selected.
- If the measuring range is changed during harmonic analysis, PPL synchronization will be disabled, then reenabled. As a result no correct measured value will be obtained, therefore the measuring range changes all the time. In this case, carry out measurement in manual range setting mode.
- Auto range will be canceled automatically when the measurement mode is switched to voltage fluctuation/ flicker measurement mode.
- · Refer to Section 16, "Specifications", for measurement accuracy.

Display Resolution and Power Range

The measuring range for active power, apparent power and reactive power is determined as follows.

Power range = Voltage range × Current range

Display resolution is given below, based on the above specifications.

- 1. The lowest display digit will not be used when the frequency exceeds 199999 counts or when computed result or efficiency exceeds 50000 counts.
- 2. If the crest factor is 6, the lowest digit will not be used when the computed result or efficiency exceeds 10000 counts.
- 3. When the voltage range x current range exceeds 1000 W, the display unit will switch to "kW", and when it exceeds 1000 kW, the display unit will switch to "MW".

Note

• In auto range setting mode, the measuring range switches according to range up/range down conditions as described on page 4-4. Therefore, the range may vary even if the measured values remain the same.

The decimal point position and unit for voltage, current and power are shown below in the case of direct input range.

				Curren	t Range		
		1.0000A	2.0000A	5.000A	10.000A	20.000A	30.000A
	10.000V	10.000W	20.000W	50.000W	100.00W	200.00W	300.00W
g	15.000V	15.000W	30.000W	75.00W	150.00W	300.00W	45.000W
aŭ	30.000V	30.000W	60.00W	150.00W	300.00W	600.0W	90.00W
–	60.00V	60.00W	120.00W	300.00W	600.0W	1.2000kW	180.00W
ge	100.00V	100.00W	200.00W	500.00W	1.0000kW	2.0000kW	3.0000kW
olta	150.00V	150.00W	300.00W	750.0W	1.5000kW	3.0000kW	4.5000kW
Ĭ	300.00V	300.00W	600.0W	1.5000kW	3.0000kW	6.000kW	9.000kW
	600.0V	600.0W	1.2000kW	3.0000kW	6.000kW	12.000kW	18.000kW

Measuring Range for External Shunt

Scaling Function

The maximum current measuring range of this instrument is 30 A.

If the current to be measured is higher than this maximum, an external shunt can be used. Use of the scaling function enables direct reading of the measured value.

Display Item	Measured/Computed Value	Scaled Value
Current	А	Ks × A
Active power	W	$Ks \times W$
Reactive power	var	Ks × var
Apparent power	VA	Ks × VA

Ks: External shunt scaling value

Setting Measuring Range

1. Press the \langle or \rangle key to select the measuring range (50, 100 or 200 mV).

Setting External Shunt Scaling Value

Press the EXT SHUNT key (SHIFT + DC). "5 hun t" will be displayed on display A.

Display D displays the external shunt scaling value, with the digit on the extreme left blinking.

2. Shifting the blinking position

The blinking position can be shifted to the left or right by pressing the \langle or \rangle key respectively.

3. Setting a value

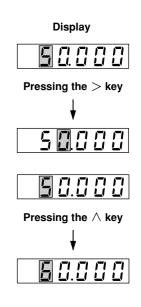
To set the value of the blinking digit, press the \wedge or \vee key.

Pressing the \land key changes the value in the order 1, 2, 3 ... 9, 0 and back to 1.

Pressing the \lor key changes the value in the opposite direction.

Default scaling value:50.000Minimum scaling value:0.0200Maximum scaling value:1000.0

- 4. Shifting the decimal point position The decimal point can be shifted by pressing the key.
- After the scaling value has been set, press the ENTER key. To exit from setting mode in the middle of making settings, press the SHIFT key or DC (EXT SHUNT) key.



Setting Example for External Shunt Scaling Value

When the external shunt range is 50 mV and the following shunt is used

Shunt used: 100 A/100 mV

Set the scaling value to "50.000".

When the secondary-side rating of the external shunt is not 50 mV, 100 mV or 200 mV

This problem can be solved by using the scaling function. An example is given below.

When a shunt with a rating of 50 A/60 mV is used:

 $(50/60 \text{ mV}) \ge 50 \text{ mV}$ (setting range) = 41.666...

From the above calculation, set the scaling value to "41.667".

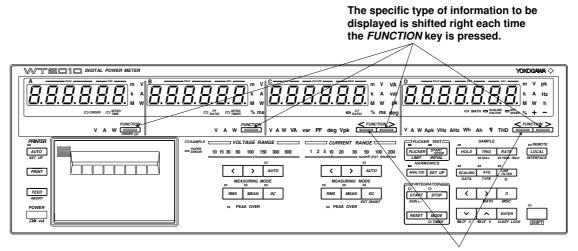
Since the measuring range is 50 mV, make sure that the input is within the range 0 to 50 mV.

Note .

- If an attempt is made to set a scaling value that is outside the setting range, error code " *E* r r *l 2*" is displayed. In this case, re-enter the correct value.
- To read the measured value directly when an external shunt is being used, SCALING must be set to OFF. If SCALING is ON, the measured value will be further multiplied by the CT ratio (scaling value for current) before it is displayed.

4.3 Selecting What to Display on Digital Displays

The instrument has four digital displays as shown below. The information to be displayed on each display can be selected with the *FUNCTION* key below the display. Each display has its own *FUNCTION* key.



The specific type of information to be displayed is shifted left each time the *FUNCTION* key is pressed.

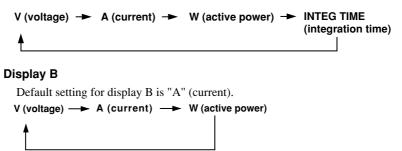
Operating the FUNCTION Key

Pressing the **FUNCTION** key switches the display in the following order. In the case of displays C and D (refer to next page), the sequence below shows the order in which the display information type is switched when the right-side **FUNCTION** key is pressed. Pressing the left-side **FUNCTION** key switches display information type in the opposite order.

Display A

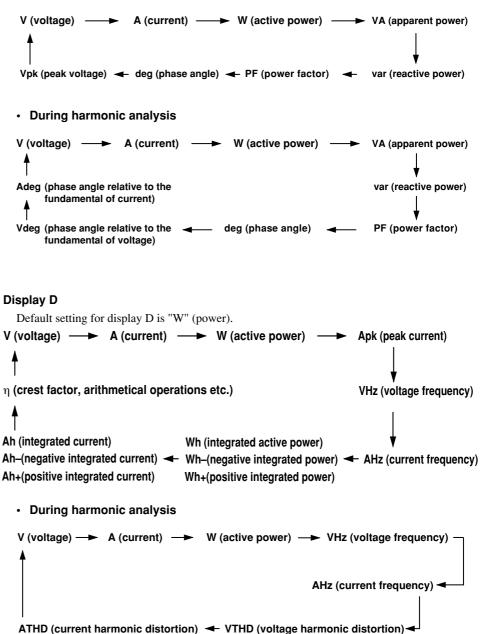
Default setting for display A is "V" (voltage).

The harmonic order is displayed during harmonic analysis.



Display C

Default setting for display C is "W" (power).



5.1 Measuring Voltage, Current and Active Power

Selecting What to Display

 Select V (voltage measurement) , A (current measurement) or W (active power measurement) by pressing the *FUNCTION* key for the display on which the measured value is to be displayed. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-8).

Setting Measuring Ranges

2. Press the voltage range or current range setting key to set the desired measuring range. For details, refer to 4.2 "Setting Measuring Ranges" (page 4-4).

Setting Voltage/Current Measurement Mode (RMS, MEAN or DC)

3. Press the measurement mode setting key (RMS, MEAN or DC key) to set the desired measurement mode. For details, refer to Section 4.1 "Setting Measuring Conditions" (page 4-2).

Power Range

- The power measuring range is determined according to the selected voltage and current ranges. For details, refer to Section 4.2 "Setting Measuring Ranges" (page 4-5).
- For power measuring range, refer to Section 16. "Specifications."

5

5.2 Measuring Peak Voltage and Current

Measured peak voltage is displayed on display C, whilst measured peak current is displayed on display D.

Function Setting

 Select Vpk (peak voltage) by pressing the *FUNCTION* key below display C, and select Apk (peak current) by pressing the *FUNCTION* key below display D. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).

Setting Measuring Ranges

 Press the voltage range or current range setting key to set the desired measuring range. For details, refer to 4.2 "Setting Measuring Ranges" (page 4-4).

Setting Voltage/Current Measurement Mode (RMS, MEAN or DC)

Measured peak voltage or current is independent of the measurement mode.

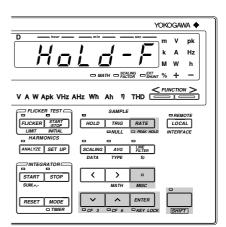
Setting Peak Hold Mode

Setting the Peak Hold Function

- Press the MISC (SHIFT + □) key.
 Press the ∧ or ∨ key until "H□Ld-F" is displayed on display D.
- 2. Press the **ENTER** key.
- 3. "H □ L d F" will move to display C, and "P E R L" on display D begins to blink. Press the ∧ or ∨ key to set the desired peak hold function.
 - PERL
 : Holds Vpk (peak voltage)

 and Apk (peak current) in

 absolute values.



- Holds V (voltage), A (current), W (active power), VA (apparent power), var (reactive power), Vpk (peak voltage) and Apk (peak current) in absolute values.
- 4. Press the **ENTER** key.

Turning Peak Hold Mode ON/OFF

Press the **PEAK HOLD** (**SHIFT** + **RATE**) key. The PEAK HOLD LED will light up when the peak hold mode is active. To cancel the peak hold mode, press the **PEAK HOLD** (**SHIFT** + **RATE**) key again.

Note

· Peak hold mode will be canceled if the range, measurement mode, line filter or averaging setting is changed.

5.3 Displaying Computed Apparent Power

Basic Computing Equation

For details, refer to Section 16 "Specifications."

Computing Accuracy

For details, refer to Section 16 "Specifications."

Computing Range for Apparent Power

For details, refer to Section 16 "Specifications."

Rated Value for Apparent Power

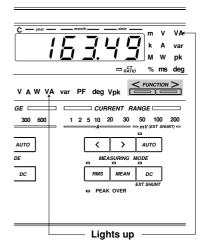
Voltage and current ranges are combined to measure apparent power. For details, refer to Section 4.2 "Setting Measuring Ranges" (page 4-5).

Function Setting

Operating the FUNCTION Key

Computed apparent power is displayed on display C. Press the *FUNCTION* key below display C to select VA (apparent power).

For details, refer to Section 4.3 " Selecting What to Display on Digital Displays" (page 4-9).



Note

 Even if the measurement mode for voltage is different from that for current, computation is still carried out with the modes unchanged.

For instance, if the voltage measurement mode is Vrms and the current measurement mode is Amean, the computed apparent power will be the result of Vrms × Amean.

5.4 Displaying Computed Reactive Power

Basic Computing Equation

For details, refer to Section 16, "Specifications."

Computing Accuracy

For details, refer to Section 16, "Specifications."

Computing Range for Reactive Power

For details, refer to Section 16, "Specifications."

Rated Value for Reactive Power

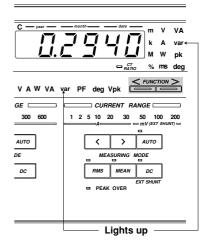
Voltage and current ranges are combined to measure reactive power. For details, refer to Section 4.2 "Setting Measuring Ranges" (page 4-5).

Function Setting

Operating the FUNCTION Key

Press the **FUNCTION** key below display C to select **var** (reactive power).

For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).



Note

Even if the measurement mode for voltage is different from that for current, computation is still carried out with the modes unchanged.

For instance, if the voltage measurement mode is Vrms and the current measurement mode is Amean, the apparent power will be obtained using the equation "var = $\sqrt{(Vrms \times Amean)^2 - W^2}$."

5.5 Displaying Computed Power Factor

Basic Computing Equation

For details, refer to Section 16, "Specifications."

Computing Accuracy

For details, refer to Section 16, "Specifications."

Display Range

Display range: -1.0000 to 1.0000

If the computation result exceeds "1" due to inputs being outside the effective operating input range, the following will be displayed.

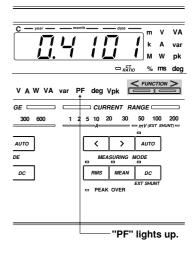
Computation Result	Display
1.0001 to 2.0000	10000
2.0001 or higher	PFE

If either input voltage or input current is below 0.5% of the rated value of the range used, " $P \not\in \xi \neg \tau$ " will be displayed.

Function Setting

Operating the FUNCTION Key

Press the **FUNCTION** key below display C to select **PF** (**power factor**). For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).



Note .

Even if the measurement mode for voltage is different from that for current, computation is still carried out with the modes unchanged.

For instance, the voltage measurement mode is Vrms and the current measurement mode is Amean, the power factor will be obtained using the equation "PF = $\frac{W}{Vrms \times Amean}$."

5.6 Displaying Computed Phase Angle

Basic Computing Equation

For details, refer to Section 16, "Specifications."

Computing Accuracy

For details, refer to Section 16, "Specifications."

Computing Range for Phase Angle

For details, refer to Section 16, "Specifications."

Display Resolution

For details, refer to Section 16, "Specifications."

Distinction between phase lag and lead is indicated as below.



If the power factor exceeds "1", the following will be displayed.

Power Factor	Display	
1. 0001 to 2.0000 2. 0001 or higher	0.00 decerr	deg

Note .

- Before computing the phase angle (deg), make sure that both the voltage and current are within the effective measurement range.
- Distinction between phase lag and lead is made properly only when both voltage and current are sine waves.
- If either the measured voltage or current is below 0.5% of the rated value of the range used, "d E L E r r" will be displayed.

• Even if the measurement mode for voltage is different from that for current, computation is still carried out with the modes unchanged.

For instance, if the voltage measurement mode is Vrms and the current measurement mode is Amean, the phase angle (deg) will be obtained using the equation

 $deg = \cos^{-1}\left(\frac{W}{Vrms \times Amean}\right)$

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VAW VA var PF deg Vpk

1 2 5 10 20 30 50 100

GE 🗆

Αυτο

DC

DE

300

600

CURRENT RANGE

> AUTO

MEAN DC

MODE

Lights up

Display B

188

Ē

var

pk

200

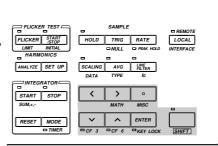
Function Setting

Operating the FUNCTION Key

Press the **FUNCTION** key below display C to select **deg (phase angle)**. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).

Setting Phase Angle Display Method

Press the MISC key (SHIFT + □.)
 Press the ∧ or ∨ key until " d E L" appears on display D.



2. Press the **ENTER** key.

" d E G" will disappear from display D, and instead will appear on display A. The phase angle currently set will appear on display B.
 Default setting: 180°

- 3. Press the \wedge or \vee key to set the phase angle display method (180° or 360°).
- 4. Press the **ENTER** key.

Note _

	The phase angle is displayed as follows when the 360° display method is selected.
	Calculation is performed using $\cos^{-1}\left(\frac{W}{VA}\right)$, which gives a phase angle between 0° and 180°.
	Distinction of phase lag/lead is then made, and computed results are displayed.
	In the case of phase lag : phase angle calculated using $\cos^{-1}(\frac{W}{VA})$ is displayed.
	In the case of phase lead : phase angle calculated using $360^{\circ} - \cos^{-1} \left(\frac{W}{VA} \right)$ is displayed.
	No phase lag or lead code ($\frac{1}{2}$ or $\frac{1}{2}$) is indicated.
_	

6

6.1 Measuring Frequency

Display Range

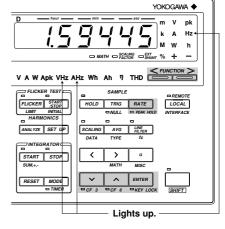
For display range, refer to Section 16."Specifications."

- If the input signal level is low or the input frequency is below the measurement range, the error code " E r r L o" will be displayed. The same error code will also be displayed if no input signal is input to the element.
- If the input frequency is above the measurement range, error code "E - H," will be displayed.

Function Setting

 Press the FUNCTION key below display D to select VHz (voltage frequency) or AHz (current frequency).

For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).



Setting the Sample Rate

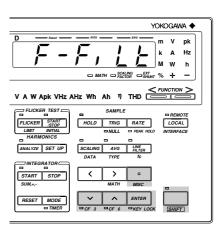
Press the *RATE* key to set the desired sample rate. The measurable frequency range varies according to the sample rate. For a detailed description of how to set the sample rate. refer to Section 4.1, "Setting Measuring Conditions" (page 4-2).

Sample Rate	Lower Limit Frequency	Frequency Range	Minimum Display	Measurement Time
0.250 (250ms)	20Hz	$20 \mathrm{Hz} \leq \mathrm{f} \leq 1 \mathrm{MHz}$	18.00Hz	60ms
0.500 (500ms)	10Hz	$10 \mathrm{Hz} \leq \mathrm{f} \leq 500 \mathrm{kHz}$	9.000Hz	120ms
2.000 (2s)	2Hz	$2 \mathrm{Hz} \leq \mathrm{f} \leq 100 \mathrm{kHz}$	1.8000Hz	600ms

Measuring Frequency with Filter ON

The frequency filter can be used to eliminate noise or harmonics, such as those that appear in inverter waveforms, when measuring the fundamental frequency. To eliminate noise during measurement of frequencies below 100 Hz, it is also recommended that you turn ON the filter.

- Press the MISC (SHIFT + □) key.
 Press the ∧ or ∨ key until "F F, L L" is displayed on display D.
- 2. Press the **ENTER** key.
 - "F F, L L" will move to display C, and " $\Box F F$ " on display D begins to blink.
- 3. Press the \wedge or \vee key to display " $\Box \neg$ ", then press the **ENTER** key.
- 4. To turn the frequency filter OFF, press the ∧ or ∨ key to display " □ F F " on display D, then press the ENTER key.



Note

If the filter is ON and a signal with a frequency of 440 Hz or higher is input, an error code "Errr-Lo" may be displayed depending on the frequency and level of the signal. This is because the signal is attenuated by the filter and therefore its presence is not recognized. In this case, turn the filter OFF.

7.1 Measuring the Crest Factor

The MATH function is used to calculate the crest factor and display it on display D.

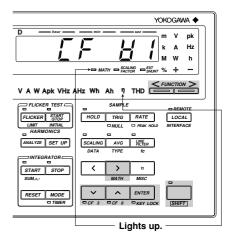
Function Setting

Operating the FUNCTION Key

 Press the *FUNCTION* key below display D to select η. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9.).

Setting the Computing Equation

- 2. Press the **MATH** key (**SHIFT** + >). " $\overline{a} R \ge H$ " will be displayed on display C.
- Press the ∧ or ∨ key. The computing equation displayed on display D changes in the following order. Select one of the computing equations from [F ∐] or [F 用].



4. Press the **ENTER** key.

Crest Factor Computing Equations and Display

- $\begin{bmatrix} F & B \\ \vdots \end{bmatrix}$: (Peak value of V1) / (rms value of V1)
- $\begin{bmatrix} F & R \\ \vdots \end{bmatrix}$: (Peak value of A1) / (rms value of A1)

Note -

- Crest factor is defined as peak value / rms value.
- "----" will be displayed if the measuring mode is MEAN or DC.

7

7.2 Four Arithmetical Operations Using Display D

The MATH function enables the four arithmetical operations on the measured values displayed on displays A and B, and displays the result on display D.

Function Setting

Operating the FUNCTION Key

 Press the *FUNCTION* key below display D to select η. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays " (page 4-9).

Setting the Computing Equation

- 2. Press the **MATH** key (**SHIFT** + >). " $\overline{a} R \downarrow H$ " will be displayed on display C.
- 3. Press the ∧ or ∨ key. The computing code on display D changes in the following order. Select one of the computing equations from "*R* + b", "*R* -

	YOKOGAWA 🔶
D how —	
FLICKER TEST	SAMPLE REMOTE HOLD TRIG RATE LOCAL UNLL DESK HOLD INTERFACE
START STOP SUM,+- RESET MODE	Imath Imath Imath
	Lights up.

 $\begin{bmatrix} F & \forall \ l \to [F & R \ l \to R + b \to R - b \to R + b \to R] b \to R] b \to R] b ^n 2 \to R^n 2] b \to [F & \forall \ l \to \dots]$

4. Press the **ENTER** key.

Note -

• The computing codes displayed on display D are described as follows.

- + :+ (addition)
- :- (subtraction)
- ... : × (multiplication)
- : / (division)
- : ^ (repeated multiplication)
- If INTEG TIME (elapsed time of integration) is selected on display A, "- - " (no data) will be displayed as the computation result.
- If the value displayed on display B is 0.0001% of the rated value or below, "- g F -" will be displayed as the computation result.

Application Examples

 \mathcal{R} ... \mathcal{L} : Result of display A \times display B is displayed.

This can be used when a function other than VA (apparent power) is set for display C to display computed apparent power (VA) on display D.

Example:

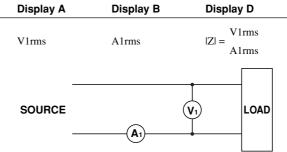
_

Display A	Display B	Display D
V1rms	A1rms	V1rms × A1rms

 \mathcal{R} _ \mathcal{L} : Result of display A / display B is displayed.

This can be used to calculate impedance absolute value.

Example:



 $B \subseteq b \cap C$: Result of display A / (display B)² is displayed.

This can be used to calculate impedance.

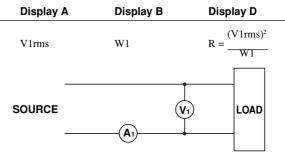
Example:

Display A	Display B	Display D
W1	A1rms	$R = \frac{W1}{(A1rms)^2}$
SOURCE	(V (V	

 $B \cap 2$: Lesult of (display A)² / display B is displayed.

This can be used to calculate impedance.

Example:



7.3 Using the Scaling Function

Overview of the Scaling Function

The scaling function multiplies measured values such as voltage, current and power by the scaling value and then displays the results. When measuring inputs that exceed the measuring range, an external potential transformer (PT) or current transformer (CT) is used. In this case, setting the scaling value to the PT ratio or CT ratio converts measured values to the corresponding values for the transformer primary side before they are displayed.

Display Item	Measured/Computed	Value Scaled Value
Voltage	V	$Kv \times V$
Current	А	Ki × A
Active power	W	$\mathrm{Kv}\times\mathrm{Ki}\times\mathrm{Kw}\times\mathrm{W}$
Reactive power	var	$Kv \times Ki \times Kw \times var$
Apparent power	VA	Kv × Ki × Kw × VA

Kv : Voltage scaling value (PT ratio)

Ki : Current scaling value (CT ratio)

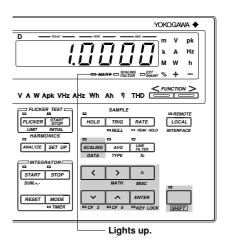
Kw: Scaling factor

Setting Scaling Values

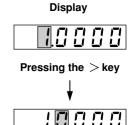
Setting the PT/CT Ratio and Scaling Factor

 Press the DATA key (SHIFT + SCALING). The currently set element, PT ratio, CT ratio and scaling factor will be displayed on displays B, C and D respectively, and each indicator LED will light up. The digit on the extreme left of the PT ratio (display B) will start blinking.

Follow steps 2 to 5 to set the PT ratio, CT ratio and scaling factor.



2. Shifting the blinking position The blinking position can be shifted to the left or right by pressing the \wedge or \vee key respectively.



1

Display

.00

Pressing the \wedge key

FI

Pressing the
key

0.00

בֿ

000

- 3. Setting a value
 To set the value of the blinking digit, press the ∧ or ∨ key.
 Pressing the ∧ key changes the value in the order 1, 2, 3 ...
 9, 0 and back to 1.
 Pressing the ∨ key changes the value in the opposite direction.
 Default value (PT and CT) : 1.0000
 Minimum value : 0.0001
 Maximum value : 10000
- After setting of the PT ratio has been completed, press the ENTER key. The leftmost digit of the CT ratio now starts blinking.
- 6. When the **ENTER** key is pressed in step 5, setting mode is finished.

Turning the Scaling Function ON

Press the **SCALING** key. The SCALING indicator LED will light up. To turn OFF scaling, press the **SCALING** key again. This causes the SCALING indicator LED to go out.

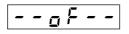
	Voltage	Current
Scaling OFF	PT secondary side	CT secondary side
Scaling ON	PT primary side	CT primary side

Note

- If an attempt is made to set a scaling value that is outside the setting range, error code "Err '2" is displayed. In this case, enter a valid value.
- When an external shunt is used, refer to Section 4.2 "Setting Measuring Ranges" (page 4-6).

Precautions When Setting Measuring Ranges with Scaling Function ON

If the scaled measured value exceeds 50000M (or 500000M in the case of integration), the following code will be displayed.



7.4 Using Averaging Functions

If reading measured values (power) is difficult due to fluctuations in the power source or load, or due to the low frequency of the measured signal, averaging functions can be used to stabilize the displayed values to make reading easier. Two types of averaging function are available with this instrument; exponential averaging and moving averaging.

Exponential Averaging

Exponential averaging is expressed by the following equation.

Dn = Dn - 1 + (Mn - Dn - 1)/K

Dn (the value at the "n"th display) is obtained by subtracting Dn - 1 (obtained by applying exponential averaging to the values up to the "n - 1"th) from the measured value Mn, dividing the result by K (the attenuation constant), then adding the quotient to Dn - 1.

Moving Averaging

Moving averaging is expressed by the following equation.

Dn = (Mn - (m - 1) + ... + Mn - 2 + Mn - 1 + Mn)/m

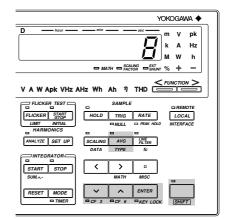
Dn is obtained by simply dividing the sum of the measured values including Mn by m (the number of data).

Setting Averaging Type (effective only for normal measurement)

1. Press the **TYPE** key (**SHIFT** + **AVG.**)

" R H L" will be displayed on display B, indicating that averaging type selection mode is now active.

- The currently selected averaging type will be displayed on display C.
 Press the ∧ or ∨key until the desired averaging type (" E P " or " L (n") is displayed on display C.
 E P : Exponential averaging
 - L in : Moving averaging



3. Press the **ENTER** key.

Setting the Attenuation Constant or Averaging Sample Number (effective only for normal measurement)

- 4. Press the ∧ or ∨ key to set an attenuation constant (K) or sample number (m).
 Exponential averaging : selectable attenuation constant (K) : 8, 16, 32, 64, 128, 256
 Moving averaging : selectable sample number (m) : 8, 16, 32, 64, 128, 256
- 5. Press the **ENTER** key.

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Averaging during Harmonic Analysis

This provides a 1st-order low-pass filter with time constant of 1.5 s if the fundamental frequency is 50/60 Hz with exponential averaging. In case the analysis window width is 16, the attenuation constant (K) will be 5.625 if the PLL synchronous source's frequency is 55 Hz or higher and below 75 Hz. If other frequency is selected, it will be 4.6875.

Starting Averaging Process

6. Press the **AVG** key.

The AVG indicator LED lights up, indicating that the averaging function is ON. To turn OFF the averaging function, press the **AVG** key again. This causes the AVG indicator LED to go out.

7.5 Using the NULL Function

Overview of the NULL Function

If DC has been selected as the voltage or current measurement mode, the measured value obtained just after the *NULL* key is pressed will be used as the NULL value. The NULL function is valid until the *NULL* key is pressed again.

Display Content

The following data is displayed when the NULL function is ON.

Voltage Measurement Mode	Current Measurement Mode	Display Content
DC	DC	$V = V_{DC} - V_{NULL}$
		$A = A_{DC} - A_{NULL}$
		$W = (V_{dc} - V_{NULL}) \times (A_{dc} - A_{NULL})$
		$= V_{dc} \times A_{dc} - V_{dc} \times A_{NULL} - A_{dc} \times V_{NULL} + V_{NULL} \times A_{NULL}$
		$= W' - V_{DC} \times A_{NULL} - A_{DC} \times V_{NULL} + V_{NULL} \times A_{NULL}$
DC	RMS, MEAN	$V = V_{DC} - V_{NULL}$
		$A = A_{AC}$
		$W = (V_{dc} - V_{NULL}) \times A_{ac}$
		$= V_{dc} \times A_{ac} - A_{ac} \times V_{NULL}$
		$= W' - A_{ac} \times V_{NULL}$
RMS, MEAN	DC	$V = V_{AC}$
		$A = A_{DC} - A_{NULL}$
		$W = V_{ac} \times (A_{dc} - A_{NULL})$
		$= V_{ac} \times A_{dc} - V_{ac} \times A_{NULL}$
		$= W' - V_{AC} \times A_{NULL}$
RMS, MEAN	RMS, MEAN	
V. · Instantaneous vol	tage value (DC mode)	V., .: Instantaneous voltage value (RMS_MEAN mode)

 $\begin{array}{lll} V_{dc} & : \mbox{ Instantaneous voltage value (DC mode)} & V_{ac} & : \mbox{ Instantaneous voltage value (RMS, MEAN mode)} \\ A_{dc} & : \mbox{ Instantaneous current value (DC mode)} & A_{ac} & : \mbox{ Instantaneous current value (RMS, MEAN mode)} \\ V_{DC} & : \mbox{ Voltage value after averaging (DC mode)} & V_{Ac} & : \mbox{ Voltage value after averaging (RMS, MEAN mode)} \\ \end{array}$

 v_{AC} : Voltage value after averaging (DC mode) v_{AC} : Voltage value after averaging (RMS, MEAN mode) A_{DC}: Current value after averaging (DC mode) A_{AC}: Current value after averaging (RMS, MEAN mode)

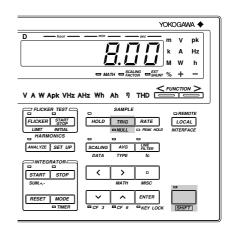
W': Power after averaging

Measuring with NULL Function ON

Press the **NULL** (**SHIFT** + **TRIG**) key.

The NULL value will be set and the NULL LED lights up.

To cancel the NULL function, press the **NULL** (**SHIFT** + **TRIG**) key again. The NULL LED will go out, indicating that the NULL function is OFF.



Note

- The NULL function will be canceled if the measurement mode, range, display update interval, line filter, averaging or crest factor is changed.
- The NULL function will not operate during integration, harmonic analysis or flicker measurement.
- If an attempt is made to turn the NULL function ON while auto range is ON, "E - 15" will occur.
- If an attempt is made to turn the NULL function ON when "DC" is not selected for both voltage and current modes, "Err /5" will occur.

8.1 Overview of Integrator Functions

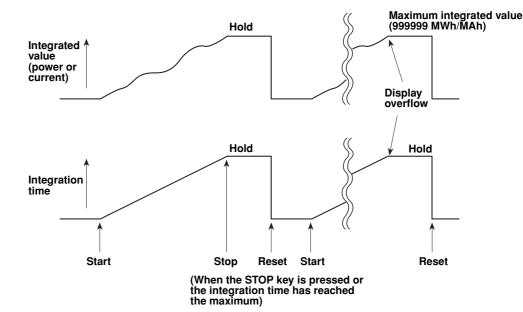
Integration Modes

Wh (integration of active power) or Ah (integration of current) can be set for display D, to allow display of the following data on each display and setting of the following 4 integration modes. The instrument does not measure or display voltage and current values.

	Display A	Display B	Display C		Display D
	Elapsed time of integration	Active power	Active pow	/er	Integrated value Frequency (Refer to Chapter 6)
					d only when "W" is e function)
	Integration Mode	Start	Stop	Repeat	Integration Time
1.	Manual integration	START key or through communications	STOP key	No	From start to stop
2.	Standard integration	START key	Integration timer	No	Time set on integration timer
3.	Continuous integration	START key	STOP key	Yes	Time set on integration timer
4.	Real time counting Standard integration Continuous integration	Reserved start time Reserved start time	Reserved stop time Reserved stop time	No Yes	Reserved time duration Time set on integration timer

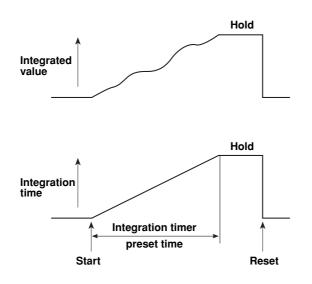
Manual Integration Mode

In this mode, integration starts when the **START** key is pressed, and stops when the integration time reaches the maximum (999 hours and 59 minutes) or the integrated power (Wh) or current (Ah) reaches the maximum (999999 MWh/MAh). The instrument holds the integration time and power (or current) of the stop point.



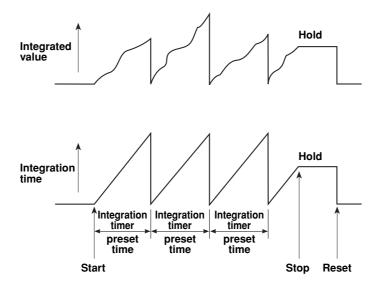
Standard Integration Mode (Timer Mode)

In this mode, integration starts when the **START** key is pressed, and stops when the timer preset time is reached or the integrated value reaches the maximum, whichever is first. The instrument holds the integration value and integration time of the stop point.



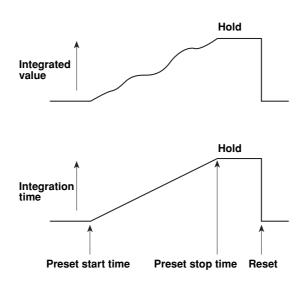
Continuous Integration Mode (Repeat Integration)

In this mode, integration starts when the **START** key is pressed. When the timer preset time is reached, the integrated value and integration time are reset automatically and restarted immediately. This is repeated continuously until the **STOP** key is pressed. If the integrated value reaches the maximum before the timer preset time is reached, integration stops and the instrument holds the integration value and integration time.



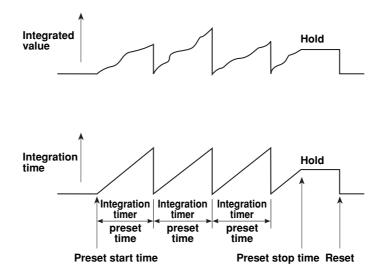
Real Time Counting Standard Integration Mode

In this mode, integration start/stop time can be set to an actual time. Integration starts at the preset start time, and it stops when the preset stop time is reached or the integrated value reaches the maximum. The instrument holds the integrated value and integration time of the stop point. If preset time has been set on the integration timer and this preset time is reached before the preset stop time is reached, the instrument will hold the integrated value and integration time.



Real Time Counting Continuous Integration Mode (Repeat Integration)

In this mode, integration start/stop time can be set to an actual time. Integration starts at the preset start time, and is repeated at intervals (timer preset time) until the preset stop time is reached. When the timer preset time is reached, the integrated value and integration time are reset automatically and restarted immediately. When the preset stop time is reached or the integrated value reaches the maximum, integration stops and the instrument holds the integrated value and integration time.



8

There are two ways to start, stop and reset integration.

For details, refer to the pages given below.

• Using the **START**, **STOP** and **RESET** keys (Integrator):

refer to Section 8.3 "Displaying Integrated Value" (page 8-10).

• Using GP-IB/RS-232-C commands:

refer to Sections 14.2 "Using the GP-IB Interface" (page 14-4) and 14.3 "Using the RS-232-C Interface" (page 14-7).

• Using an external signal:

refer to Section 12.2 "Remote control" (page 12-2).

Display Update Rate (Sample Rate)

Once integration is started, the display update rate will be set to 2 seconds automatically. If the **RATE** key is pressed in an attempt to change the display update rate during integration, an error code " $E = r + \frac{1}{2}$ " will be displayed.

Sampling Frequency and Measuring Frequency Range

A sampling frequency of approximately 110 kHz is used for integration. All sample data is integrated at this frequency.

		Measuring Frequency Range
Power integration		DC to 50 kHz
Current integration		
(Measurement mode)	RMS/MEAN	DC, 20 Hz to 50 kHz
	DC	DC to 50 kHz

Computing equations are given below.

Power integration		$\sum_{N=0}^{n} (\sum \mathbf{v}_i{\cdot}\mathbf{i}_i) = \sum_{N=0}^{n} \mathbf{v}_i{\cdot}\mathbf{i}_i$
Current integration	RMS	$\sum_{N=0}^n \ (\sqrt{\sum \ i_i^2})$
	MEAN	$\sum_{N=0}^n (\sum i_i) = \sum_{N=0}^n i_i $
	DC	$\sum_{N=0}^{n} (\sum i_i) = \sum_{N=0}^{n} i_i$

(): Integrated value at each display update interval

N: No. of updates

Vi, ii: Sample data

A description is given for polarity integration. Ah+ and Ah– are used when the measurement mode is DC.

Wh+ : Performs integration on instantaneous power with both Vi and Ii being positive.

Wh- : Performs integration on instantaneous power with both Vi and Ii being negative.

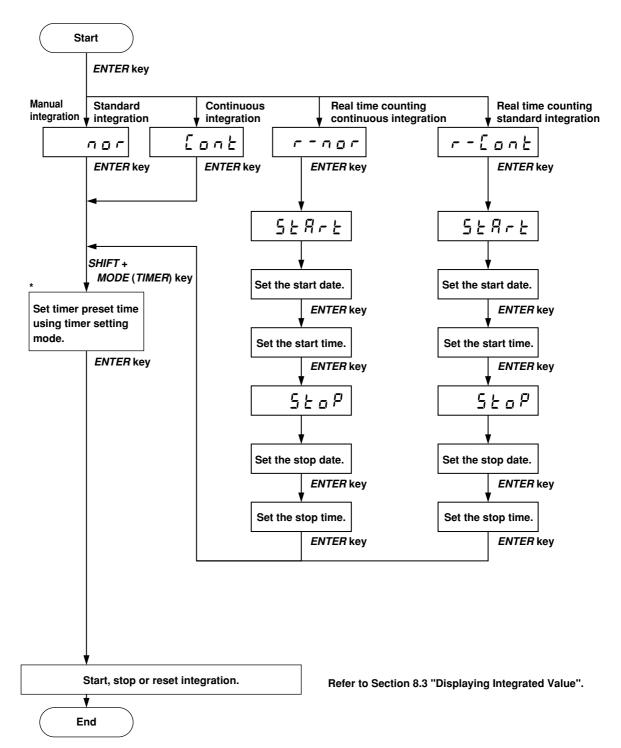
Ah+ : Performs integration on instantaneous current with Ii being positive.

Ah- : Performs integration on instantaneous current with Ii being negative.

Note

• The integration results may differ from those obtained by another instrument having a different integration method, if load fluctuates considerably.

Flow of Operations

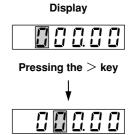


* If you are using manual integration mode, set the timer preset time to "000" hour and "00" minute.

Common Operations for All Integration Modes (Setting the Date, Time and Integration Timer)

Shifting the Blinking Position

The blinking position can be shifted to the left or right by pressing the < or > key. Pressing the < key causes the digit to the left of the currently blinking digit to blink, and pressing the > key causes the digit to the right of the currently blinking digit to blink. The blinking position wraps around in both directions.

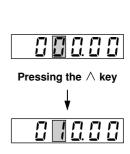


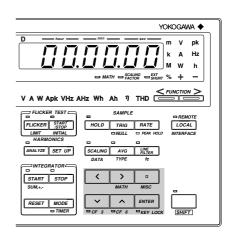
Setting a Value

To set a value of the blinking digit, press the \land or \lor key. Pressing the \land key changes the value in the order 1, 2, 3 ... 9, 0 and back to 1. However, in the time setting, the value of the second lowest digit changes in the order 1, 2, 3, 4, 5, 0 and 1. Pressing the \lor key changes the value in the opposite direction.

Confirming Entry

After setting the date (or time or integration timer), press the **ENTER** key.





Display Resolution during Integration

The display resolution for integrated values is 500000 counts. The decimal point shifts automatically according to the elapsed time of integration, constantly maintaining high measurement accuracy.

The decimal point shifting timing is determined automatically according to the selected voltage and current measuring ranges. After the rated value is set for both voltage and current measuring ranges, the decimal point shifts when the integrated value exceeds 500000 counts. However, the minimum measurement unit is 1/1000 times the power range which is determined by the rated voltage and current ranges, and the maximum measurement unit is "MWh". For instance, the elapsed time of integration and integrated value are displayed as follows when the voltage and current measuring ranges are 100 V and 5 A respectively.

Elapsed Time		Integrated Value		
Н	М	S		
		0	0.00000	mWh
		2	277.778	mWh
		3	416.667	mWh
		4	555.56	mWh
		÷		
		7	972.22	mWh
		8	1.11111	Wh
		÷		
		36	5.00000	Wh
		37	5.1389	Wh
		÷		
	10	0	50.0000	Wh
	10	1	50.0000	Wh
	10		50.159	vv II
		:		
1	0	0	500.000	Wh
1	0	1	500.14	Wh
1	0	:	500.11	
2	0	0	1.00000	kWh
		:		
6	0	0	3.00000	kWh
10	0	0	5.00000	kWh

Current Integration

- As explained earlier, there are three measurement modes for measurement of current; RMS, MEAN and DC. Likewise, there are three types of current integration, corresponding to the three types of measurement. (Refer to Section 8.1 "Overview of Integrator Functions" (page 8-4).) When the measuring mode is DC, the polarity is also displayed. This feature is convenient for measuring battery charging/discharging.
- If the current measuring range is RMS or MEAN and the input current is below 0.3% of the rated value of the range, integration will be carried out with the input current considered to be "0".

8

8.2 Setting Integration Modes

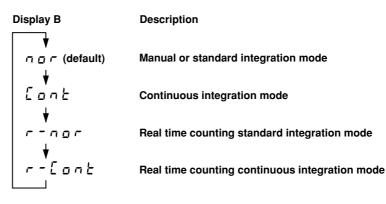
Setting Integration Mode and Integration Timer

Setting the Mode

1. Press the **MODE** key.

", $n \notin E \subseteq G$ " will be displayed on display A. The currently selected integration mode is displayed on display B. Pressing the \land key changes the mode in the following order, and pressing the \lor key changes it in the opposite direction.

FLICKER TEST FLICKER STARY STOP LIMT INITIAL HARMONICS ANALYZE SET UP	SAMPLE HOLD TRIG RATE NULL PEAK IK SCALING AVG LINE DATA TYPE IC	INTERFACE
INTEGRATOR START STOP SUM.+ RESET MODE TIMER	DATA TYPE IC	



After the desired integration mode has been selected, press the ENTER key.

2. If "r - nor" (real time counting standard integration mode) or "r - [on]" (real time counting continuous integration mode) is selected as integration mode, the following will be displayed on each display.

Display A	Display B	Display C	Display D
ר ה ם ר (Real time counting standard integration mode)	5£8~£ 5£0P	960 l0 l 960 l0 l	00.0000 00.0000
r - [همك (Real time counting	StRrt Stop	960101 960101	0 0 0 0 0 0 0 0 0 0 0 0

continuous integration mode)

Setting the Timer Preset Time

3. Press the **TIMER** key (**SHIFT + MODE**.)

The timer setting mode is now in operation. The time currently set will be displayed on display A, with the digit on the extreme left blinking, and the INTEG TIMER indicator LED will light up.

4. Set the desired time as follows.

Press the < or > key until the digit for which you wish to set a value is blinking, then press the < or > key to set the desired value. Refer to Section 8.1 "Overview of Integrator Functions" (page 8-6). (When using manual integration mode, set the time to "000.00".)

Maximum time allowed: 999 (hours) 59 (minutes)

5. When the desired time has been set, press the ENTER key. The TIMER indicator LED located below the MODE (TIMER) key will be lit, indicating that the time has been confirmed.

Display A

Display A

minutes

minutes

Ъ

hours

hours

Integration Using Real Time Counting Standard Integration Mode (r - n a r) or Real Time Counting Continuous Integration Mode $(r - \xi a r)$

When real time counting continuos mode is used, an error occurs if integration is started with the timer preset time set to "000.00".

Setting the Start and Stop Date and Time Setting the Start Date

- I. "5 ⊢ R ⊢ ⊢ " is displayed on display B and the start date currently set is displayed on display C. Use the ∧, ∨, < and > keys to set the desired start date.
 Refer to Section 8.1 "Overview of Integrator Functions" (page 8-6).
- 2. Press the **ENTER** key.

Setting the Start Time

- 3. The start time currently set is displayed on display D. Use the \land , \lor , < and > keys to set the desired start time.
- 4. Press the ENTER key.
 "5 ¿ p" is now displayed on display B.

Setting the Stop Date

- 5. The stop date currently set is displayed on display C. Use the \land , \lor , < and > keys to set the desired stop date.
- 6. Press the **ENTER** key.

Setting the Stop Time

- 7. The stop time currently set is displayed on display D. Use the \land , \lor , < and > keys to set the desired stop time.
- 8. Press the **ENTER** key.

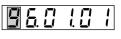
When both start and stop times have been set, set the timer preset time as described in "Setting the Timer Preset Time" on the previous page.

Note

- If the stop date or time is before the start date or time, an error code "E r r / 2" will be displayed. It is not
 possible to set a stop date or time that is before the start date or time.
- Years whose final two digits are less than "96" will be treated as 21st century years.

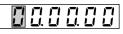
 99 → 1999	$95 \rightarrow 2095$ $96 \rightarrow 1996$ \vdots	
---------------	--	--

Display C

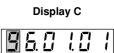


year month day

Display D



hours minutes second



Display D

8

8.3 Displaying Integrated Value

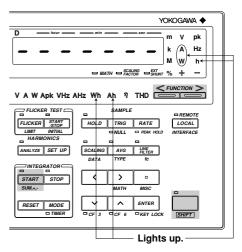
Function Setting

Operating the FUNCTION Key

Press the **FUNCTION** key below display A to light up the **INTEG TIME** indicator LED. Press the **FUNCTION** key below display D to select **Wh** or **Ah**. For details, refer to Section 4.3 " Selecting What to Display on Digital Displays "

Displaying Polarity of Integration

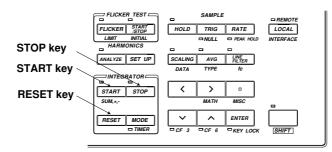
Polarity can be changed each time the **SUM**, +, - key (**SHIFT** + **START**) is pressed. If the function is **Ah** or **Wh**, selection of + or - causes the corresponding polarity indicator (at the right of Display D) to light up. (You can also change the polarity while a different function is selected, but the LED indicators will not light.)



Starting, Stopping and Resetting Integration

(page 4-9.)

The elapsed time of integration is displayed on display A, and the integrated value is displayed on display D.



Starting Integration

Press the **START** key.

Integration will start. Make sure that the START indicator LED is lit. In real time counting standard or continuous mode, the START indicator LED blinks, indicating that the instrument is in standby state. (Integration will start automatically when the start date and time is reached.) If the stop date and time has already passed, integration will not start even if the **START** key is pressed, and an error code "E - r + B" will be displayed.

Stopping Integration

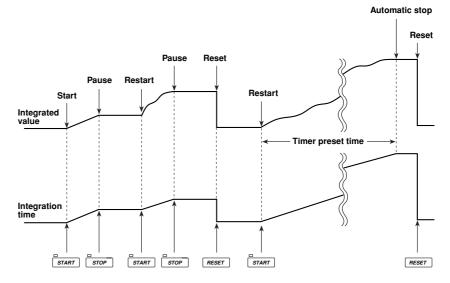
Press the **STOP** key.

- If the *STOP* key is pressed while integration is in progress, integration will be paused. The instrument holds the integration time and integrated value of the stop point until the *START* key is pressed again.
- The STOP indicator LED lights up when the STOP key is pressed.
- When the integrated power reaches the maximum, integration will stop and the instrument holds the integrated value and integration time.

Resetting Integration

Press the **RESET** key after integration has been stopped.

• The integrated value and integration time will be reset.



Integration Overflow Display

If the integrated value reaches the maximum (±999999 MWh or ±999999 MAh), integration will stop and the instrument will hold that value.

Holding the Integrated Value

Pressing the *HOLD* key during integration will light up the HOLD indicator LED and hold the integrated value of the time at which the *HOLD* key is pressed. To update the displayed value, press the *TRIG* key. For details, refer to Section 8.4 "Precautions Regarding Use of Integrator Function" (page 8-12.)

Display Content and Range

Display A	Display B	Display C	Display D
Elapsed time of integration or active power	Active power	Active power	Integrated value Maximum ±999999 MWh or ±9999999 MAh

Note

- Display A is valid when the function is set to "INTEG TIME" or "W" (active power). Otherwise, "----" will be displayed.
- Displays B and C are valid only when their function is set to "W" (active power). Otherwise, "----" will be displayed.
- "----" will be displayed on displays B and C for the first measurement after the START key is pressed.
- The previous measured value (not the latest measured value) will be displayed just after the *STOP* key is pressed.

Displaying the Polarity of the Integrated Value

Integrated active power sometimes decrease in the case of battery discharge. If the integrated power is negative, "-" will be displayed in front of the integrated value.

8.4 Precautions Regarding Use of Integrator Function

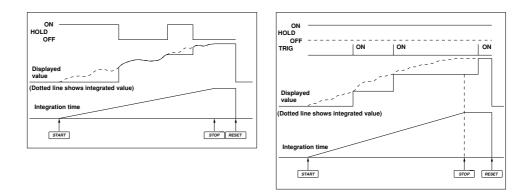
Integration When Display Hold is ON

When the *HOLD* key has been pressed to activate the display update hold function, i.e. when the HOLD indicator LED is lit, integrated values displayed and output through a communications interface are on hold, but integration is still carried out whether the display update hold function is ON or OFF. The SAMPLE indicator LED continues to blink.
As shown in Fig. (a), if integration is started
As shown in Fig. (b), if integration is stopped

while the display update hold function is ON, the displayed integrated value remains unchanged. However, as soon as the display update hold function is turned OFF or the **TRIG** key is pressed, the integrated value accumulated up to that moment will be displayed. As shown in Fig. (b), if integration is stopped while the display update hold function is ON, the displayed integrated value remains unchanged. However, as soon as the display update hold function is turned OFF or the *TRIG* key is pressed, the integrated value obtained when the *STOP* key was pressed will be displayed.

Fig. (a)

Fig. (b)



Backup During Power Failures

If there is a power failure while integration is in progress, the integrated value and integration time will be backed up.

- In this case, integration will remain stopped even if power is restored or the **START** key is pressed. To restart integration, first press the **RESET** key to cancel integration, then press the **START** key.
- When power is restored after a power failure, the integrated value and elapsed time of integration up to the time of the power failure will be displayed.

Panel Key Operation During Integration Mode

During integration mode, certain key operations are restricted so that settings are not accidentally changed when operating keys are pressed. The table below show these restrictions.

			Integration	in progress
Operation	n key (START LED)		n Integration state Lit Not lit	Integration paused Not lit Lit
		Notint	Not in	En
MODE	RMS,MEAN,DC	0	V : × A : ×	V : × A : ×
	AVG SCALING	0	× O	× O
SAMPLE	HOLD TRIG (display update hold ON) RATE	0 0 0	0 0 4	0 0 4
RANGE	VOLTAGE AUTO	0	×	×
	<, > CURRENT AUTO <, >	0	×	×
CF LINE FILTER fc		0 0 0	× × △	× × △
FILTER		0	0	0
DATA SETTING	SCALING (DATA)	0	0	0
	MODE (TIMER) ∧, ∨, <, > ENTER		In the case of the TIMER key, key operation is not possible, but the timer preset time can be displayed.	In the case of the TIMER key, key operation is not possible, but the timer preset time can be displayed.
FUNCTION (Displa FUNCTION (Displa		× O	× O	× O
WIRING SYSTEM	WIRING	0	0	0
INTEGRATOR	START STOP RESET	0 × 0	× O ×	O × O

× : Key operation is not possible.

O: Key operation is possible.

 \triangle : Confirmation only is possible

- Error code "*Err 13*, *42*, *44*, *45*" will appear on display D if any key that cannot be operated is pressed.
- It is not possible to reset the integrated value while integration is in progress. To reset the integrated value, press the *STOP* key to interrupt integration, then press the *RESET* key.
- To use keys whose operation is invalidated while integration is in progress, press the **STOP** key to interrupt integration, then press the **RESET** key to reset the displayed integrated value.
- If integration is started while auto range setting mode is active, the range setting mode will be switched to manual range setting mode, but the measuring range will remain unchanged.

Integrated Value when Instantaneous Measured Value Exceeds Measurement Limits

If the instantaneous measured value exceeds the measurement limits, computation is carried out as follows. In this case, it is not possible to obtain correct integrated values.

- If the instantaneous input exceeds 3.5 times the rated value of the measuring range when the crest factor is "3", the measured value is considered to be 3.5 times the rated value of the measuring range when computing the integrated value.
- If the instantaneous input exceeds 7 times the rated value of the measuring range when the crest factor is "6", the measured value is considered to be 7 times the rated value of the measuring range when computing the integrated value.

9.1 Operating the Harmonic Analysis Function (Optional)

To operate the harmonic analysis function from within a normal measurement operation, you have to set the harmonic analysis mode first, then make PLL source (input to be used as the fundamental frequency), display type and harmonic order settings.

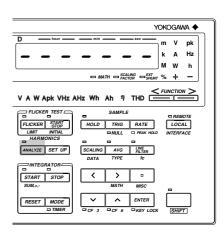
Setting the Harmonic Analysis Mode

Operating the ANALYZE key

Press the **ANALYZE** key. The ANALYZE indicator LED will light up, indicating that the harmonic analysis mode is activated.

To return to the normal measurement mode, press the **ANALYZE** key once more. The ANALYZE indicator LED will go out, indicating that the normal measurement mode is now active.

In the harmonic analysis mode, RMS mode is always selected as the measuring mode. Even if the mode is switched from the harmonic analysis mode to the normal measurement mode, RMS mode stays as the measuring mode.



Note .

- It is not possible to activate the harmonic analysis mode while integration is in progress (i.e. START indicator LED: lit) or integration is being interrupted (i.e. STOP indicator LED: lit). If such attempt is made, an error "*E r r ¦*]" will occur. In this case, press the *STOP* key (to interrupt integration) then *RESET* key, and finally press the *ANALYZE* key.
- It is not possible to start integration if the harmonic analysis mode is active. If such an attempt is made, an error "E r r 15" will occur.
- It is not possible to activate the harmonic analysis mode during flicker measurement (i.e. FLICKER indicator LED: lit). To activate the harmonic analysis mode, first you have to return to normal measurement. To do this, press the *START/STOP* key to stop flicker measurement, press the *INITIAL* (*SHIFT* + *START/STOP*) key to initialize the instrument, then press the *FLICKER* key. Finally, press the *ANALYZE* key to activate the harmonic analysis mode.
- The accuracy varies according to the selected crest factor. For a detailed description, refer to Chapter 16.

To carry out measurement in accordance with IEC 1000-3-2, set each item as follows. For a description of the setting method, refer to the following pages.

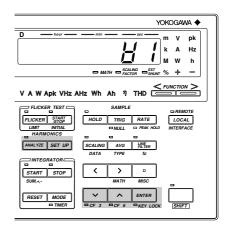
Harmonic	Analysis Window Width	Averaging	Anti-aliasing Filter	Analysis Order
Steady-state harmonic Fluctuating harmonic (within limit)	4, 8 or 16 4, 8 or 16	OFF or ON ON	ON ON	40 or higher 40 or higher
Fluctuating harmonic (likely outside limit)	16	ON	ON	40 or higher

Setting the PLL Source

For harmonic analysis, it is necessary to select the input to be used as the fundamental frequency (PLL source) for PLL synchronization. (PLL stands for Phase Locked Loop.)

- Press the SET UP key.
 Press the ∧ or ∨ key until "5 y n [" is displayed on display C.
- 2. Press the **ENTER** key.
- 3. Pressing the ∧ or ∨ key changes the PLL source displayed on display D in the following order, so select the desired source. (Default is ^H/₂)





4. Press the **ENTER** key.

Note

- If the fundamental frequency of PLL source cannot be measured due to fluctuations or distortions, it is not
 possible to obtain correct measurement results. In this case, it is suggested voltage with relatively small
 distortion be selected as the PLL source or turn the filter ON.
- If the amplitude of the input signal selected as the PLL source is smaller than the rated range value, PLL synchronization may sometimes fail. In this case, it is suggested a suitable measurement range be selected so that the input level exceeds 30% of the rated range value.
- If there is no input for the PLL source, " $F \leftarrow Q \not \in \sigma \sigma$ " will be displayed on display B.

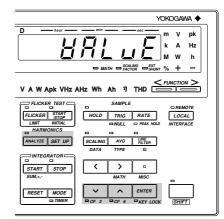
Setting the Display Type

The fundamental component and each harmonic component of voltage, current or active power is displayed on display B. They are displayed either as measured value or relative harmonic content, so it is necessary to select either measured value or relative harmonic content beforehand. This setting can be made on display D.

1. Press the **SET UP** key.

Press the \land or \lor key until " $d \neq 5$ " is displayed on display C.

- 2. Press the **ENTER** key.
- 3. Pressing the \land or \lor key changes the display type displayed on display D in the following order, so select the desired type. $\exists R \downarrow u \notin (displays measured value) \rightarrow$ $\lfloor u n \notin (displays relative harmonic content) \rightarrow \exists R \downarrow u \notin \cdots$



4. Press the **ENTER** key.

The equation used to calculate the harmonic content is given below.

Harmonic content =	Each harmonic component	× 100 (%)
	Fundamental component	× 100 (/8)

Note

- If relative harmonic content is selected, "- - - " will be displayed on display B if harmonic order 1 (fundamental) has been selected.
 - When " [_ _ _ L" is selected, the % LED on display B will light up.

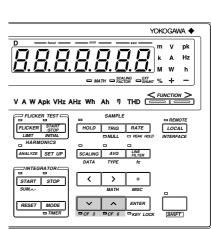
Setting the Harmonic Display Order

Display A is used to select the order of the harmonic data to be displayed on display B and C.

Operating the \land or \lor Key

Press the \land and \lor keys to select the order of the harmonic data to be displayed on display B or C. Orders from the 1st to the one set in "Setting the Upper limit of the Harmonic Order" (page 9-4) can be set (maximum order: 50th).

However, due to the fundamental frequency of the PLL source becoming large or from turning the anti-aliasing filter to ON, the Maximum analysis order changes, sometimes resulting in the upper limit of the harmonic order to become larger than the Maximum analysis order. In this case, if the display order is set to a value between the Maximum analysis order and the upper limit of the harmonic order, "- - - -" will be displayed on display B or C.



For details of the maximum order, refer to Section 16, "Specifications".

Note

 The FUNCTION key located below display A can be used to increase (ORDER UP) the harmonic order respectively. However, it is not possible to change harmonic order fast.

Setting the Upper Limit of the Harmonic Order

The upper limit of the harmonic order can be set as follows. This setting will be reflected in the equations used to calculate fundamental wave + harmonics and harmonic distortion for voltage, current and power.

Operating the SET UP Key

1. Press the **SET UP** key.

Press the \land or \lor key until " $\Box \cap d \in \Gamma$ " is displayed on display C.

- 2. Press the **ENTER** key.
- 3. Pressing the ∧ or ∨ key changes the harmonic order displayed on display D in the following order, so select the desired upper limit of the harmonic order.
 50 → 1 → 2 → 3 → ... → 49 and back to 50

	YOKOGAWA 🔶
D hour —	min v pk k A Hz M W h MATH SCARPS STATE
V A W Apk VHz A	Hz Wh Ah १ THD
FLICKER TEST	SAMPLE HOLD TRIO RATE UCAL UCAL INTERPACE SOLINO AVO THER DATA TYPE fc
SUM, +,-	
RESET MODE	CF 3 CF 6 KEY LOCK SHIFT

4. Press the **ENTER** key.

An order from 1st to 50th can be set.

If the maximum harmonic order determined by the anti-aliasing filter is smaller than the upper limit of the harmonic order, "----" will be displayed on display B or C for the harmonic display order exceeding the maximum harmonic order determined by the anti-aliasing filter. For details of the maximum order, refer to Section 16, "Specifications".

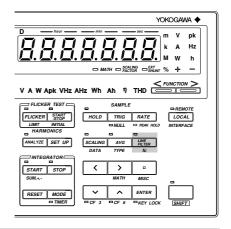
Setting the Anti-aliasing Filter

When waves are input continuously and converted to digital data using A/D converter, if a wave having a frequency of less than 1/2 of the sampling frequency is input, this wave is recognized as a wave in low-frequency band that does not exists. This symptom is known as aliasing. Aliasing causes various problems, including an increase in measurement error and improper measurement of the phase angle. To prevent this aliasing, an anti-aliasing filter is used.

Operating the LINE FILTER key

Press the **LINE FILTER** key once. The FILTER indicator LED will light up, indicating that the antialiasing filter is active.

To deactivate the filter, press the *LINE FILTER* key once more. The FILTER indicator LED will go out, indicating that the filter is not active any more. If the anti-aliasing filter is active, analysis accuracy and the maximum harmonic order change. For details, refer to Section 16, "Specifications".



Note

- Setting of the anti-aliasing filter is only possible in harmonic analysis mode. The anti-aliasing filter is not the same as the filter used in the normal measurement mode, and the ON/OFF state of each filter is maintained independently.
- · The anti-aliasing filter's cut-off frequency is fixed at 5.5 kHz.
- For details of the sampling frequency, refer to Section 16, "Specifications".

Measuring with Frequency Filter ON

Harmonic analysis may not function properly if the PLL source wave contains harmonics or noise. In this case, it is recommended that the frequency filter be turned ON to eliminate such harmonics or noise during harmonic analysis.

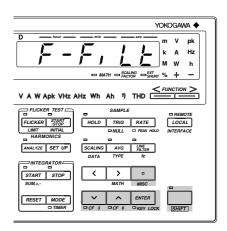
1. Press the **MISC** (**SHIFT** + \square) key.

Press the \land or \lor key until "F-F, \underline{L} " is displayed on display D.

2. Press the **ENTER** key.

"F - F, L =" will move to display C, and " $a \in F$ " on display D begins to blink.

- Press the ∧ or ∨ key to display "o ¬", then press the **ENTER** key.
- 4. To turn the frequency filter OFF, press the ∧ or ∨ key to display " □ ^F ^F " on display D, then press the **ENTER** key.

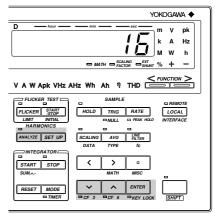


Setting the Harmonic Analysis Window Width

Set the number of waveforms whose data is to be used for harmonic analysis (fundamental input frequency: 40 to 70 Hz).

- Press the SET UP key.
 Press the ∧ or ∨ key until "U, d ⊢ H" is displayed on display C.
- 2. Press the **ENTER** key.
- Press the ∧ or ∨ key. The window width displayed on display D will change in the following order, so select the desired window width.

 $16 \rightarrow 8 \rightarrow 4 \rightarrow 2 \rightarrow 1 \rightarrow 16 \rightarrow \dots$ The default is 16.



4. Press the **ENTER** key.

Note .

"Errr'Lo" will be displayed on display D and "----" is displayed as the measurement result if the fundamental input frequency drops below 40 Hz when the window width has been set to "1" or it drops below 20 Hz when the window width has been set to "2".

Selecting What to Display on Digital Displays 9.2 (Optional)

Harmonic analysis results are displayed on displays A, B, C and D. The information to be displayed on each display can be selected with the **FUNCTION** key below the display.

Operating the FUNCTION Key

This key is used to set the function to be displayed. Some functions (those which are not shown below and on the following pages) cannot be set in harmonic analysis mode. If a function which cannot be set in harmonic analysis mode has been set in the normal measurement mode, V (voltage) will be selected automatically.

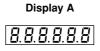
V (voltage) will be also selected automatically if the mode is switched from harmonic analysis mode back to normal measurement mode or if a function which cannot be set in the normal measurement mode has been set.

Default Function

When the mode is switched from normal measurement mode to harmonic analysis mode, settings made in normal measurement mode will be retained, except for filter setting. This also applies when the mode is switched from harmonic analysis mode to normal measurement mode.

Information on Each Display

For details, refer to the next pages.



· The harmonic order of the measured/analysis data displayed on display B or C is displayed.



```
• The fundamental
 component and
 each harmonic
 component of
 voltage, current and
 active power are
 displayed as
 measured value or
 relative harmonic
 content.
```

8.8.8.8.8.8 · The fundamental

Display C

- component and each harmonic component of voltage, current and active power are displayed as measured value are displayed.
- · The reactive power, apparent powr and power factor of the fundamental (1st harmonic) are displayed.
- The phase angle between the fundamental of voltage and current, and phase angle of each higher harmonic in relation to the fundamental of voltage or current are displayed.



- · The voltage, current and active power of fundamental + higher harmonics are displayed.
- · The fundamental frequency of the input set as the PLL source is displayed.
- · The harmonic distortion (THD) of voltage and current is displayed.

Display A

The harmonic order of the data displayed on display B or C is displayed. Orders from the 1st up to the upper limit of the harmonic order (maximum: 50th) can be displayed.



However, due to the fundamental frequency of the PLL source becoming large or from turning the anti-aliasing filter to ON, the Maximum analysis order changes, sometimes resulting in the upper limit of the harmonic order to become larger than the Maximum analysis order. In this case, if the display order is set to a value between the Maximum analysis order and the upper limit of the harmonic order, "- - - -" will be displayed on display B or C. For details of the maximum order, refer to Section 16, "Specifications" (page 16-1.)



For the order setting method, refer to Section 9.1 "Operating the Harmonic Analysis Function" (page 9-3.)

Display B

The following are displayed on display B.

 Fundamental component and each harmonic component of voltage corresponding to the harmonic order displayed on display A (as measured value or relative harmonic content)



- Fundamental component and each harmonic component of current corresponding to the harmonic order displayed on display A (as measured value or relative harmonic content)
- Fundamental component and each harmonic component of active power corresponding to the harmonic order displayed on display (as measured value or relative harmonic content)

Information displayed on display B changes in the following order.

Note -

For display type setting method, refer to Section 9.1 "Operating the Harmonic Analysis Function" (page 9-3.)

Display C

The following are displayed on display C.

• Fundamental component and each harmonic component of voltage corresponding to the harmonic order displayed on display A (as measured value)



- Fundamental component and each harmonic component of current corresponding to the harmonic order displayed on display A (as measured value)
- Fundamental component and each harmonic component of active power corresponding to the harmonic order displayed on display (as measured value)
- Reactive power of the fundamental (1st)
- Apparent power of the fundamental (1st)
- Power factor of the fundamental (1st)
- Phase angle between the fundamental of voltage and current
- · Phase angle of each higher harmonic in relation to the fundamental of voltage or current

9

Information displayed on display C changes in the following order. V (voltage) → A (current) → W (active power) → VA (apparent power) → var (reactive power) Adeg (phase angle relative to the fundamental of current) of voltage)

Note -

- For a description of how to operate the display for the phase angle, refer to Section 9.6 "Displaying the Phase Angle between the Fundamentals" (page 9-12) or Section 9.7 "Displaying the Phase Angle of Each Higher Harmonic in Relation to the Fundamental of Voltage or Current" (page 9-13.)
- When VA, var, PF or deg is selected, "- - -" will be displayed if an order other than 1st order is selected on display A.

Display D

The following are displayed on display D.

- Total rms value of voltage (regardless of the order displayed on display A)
- Total rms value of current (regardless of the order displayed on display A)



- Total rms value of active power (regardless of the order displayed on display A)
- · Fundamental frequency of the input selected as the PLL source
- · Harmonic distortion of voltage
- Harmonic distortion of current

Information displayed on display D changes in the following order.

V (voltage) → A (curre	ent) → W (active power) → VHz (voltage frequency)
ATHD	VTHD
(harmonic distortion of current)	- (harmonic distortion

Note _

- For computing equations for voltage, current and active power, refer to Section 9.4 "Displaying Fundamental + Higher Harmonics of Voltage, Current and Active Power" (page 9-10.)
- For computing equation for relative harmonic distortion, refer to Section 9.5 "Displaying the Harmonic Distortion (THD)" (page 9-11.)
- If VTHD or ATHD is selected, the % indicator LED will also light up to indicate that the data is displayed in units of %.

Sample Rate

Set the sample rate in the same way as for normal measurement operations.

9.3 Displaying Fundamental and Each Harmonic of Voltage, Current, Active Power, Apparent Power, Reactive Power and Power Factor as Measured Value or Relative Harmonic Content (Optional)

The fundamental component and each harmonic component of voltage, current and active power are displayed as measured value or relative harmonic content on display B; they are displayed as measured value on display C. In addition, the fundamental component of reactive power, apparent power and power factor is also displayed.

Function Setting

 Press the FUNCTION key below display B or C to select V (voltage), A (current) or W (active power) for display, or press the FUNCTION key below display C to select VA (apparent power), var (reactive power) or PF (power factor) for display.

For details, refer to Section 9.2 "Selecting What to Display on Digital Displays" (pages 9-7 and 9-8).

Setting the Harmonic Order

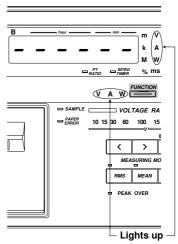
 Set the harmonic order.
 For details, refer to "Setting the Harmonic Order" (page 9-3).

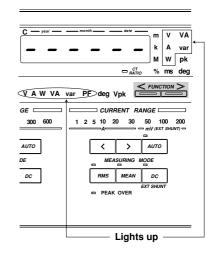
Setting the Display Type

3. Use display D to set whether data is to be displayed as measured value or relative harmonic content.

For details, refer to Section 9.1 "Operating the Harmonic Analysis Function" (page 9-3).

This function is applicable only to display B. Data is always displayed as measured values on display C, regardless of the display type set in this step.





Note

• The minus sign will be displayed for var (reactive power) if the voltage is behind the current.

 In case the displayed active power value becomes less than -99999 on display B and C, the minus sign will not be displayed. However, in the printout and regarding the communications output, the minus sign will be present.

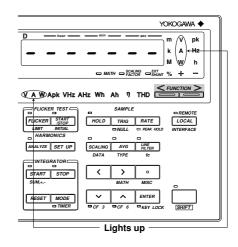
9.4 Displaying the Fundamental + Higher Harmonics of Voltage, Current and Active Power (Optional)

The fundamental and higher harmonics of voltage, current and active power are displayed on display D.

Function Setting

 Press the FUNCTION key below display D to select V (voltage), A (current) or W (active power) for display.

For details, refer to Section 9.2 "Selecting What to Display on Digital Displays" (page 9-8.)



Computing Equation

The fundamental + higher harmonics of voltage, current and active power are calculated using the following equation.

V (voltage) =
$$\sqrt{\sum_{k=1}^{n} (V_k)^2}$$
 A (current) = $\sqrt{\sum_{k=1}^{n} (A_k)^2}$ W (active power) = $\sum_{k=1}^{n} W_k$

Vk, Ak, Wk : Fundamental or harmonic component of voltage, current and active power

- k : Analysis order
 - : Maximum order. The maximum possible order varies according to the fundamental frequency of the input set as the PLL source and to whether the anti-aliasing filter is ON or OFF. If this maximum order is smaller than the preset order, the preset order will be used as the maximum order.

Note

n

• Total rms value (fundamental + harmonics) obtained in the harmonic analysis mode differs from that obtained in normal measurement mode. The total rms value in harmonic analysis mode is calculated from the fundamental component and the harmonics up to the maximum order as shown in the above equation.

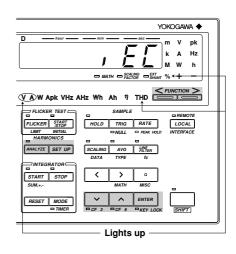
9.5 Displaying the Harmonic Distortion (THD) (Optional)

Harmonic distortion (THD) is displayed on display D.

Function Setting

 Press the *FUNCTION* key below display D to select VTHD (harmonic distortion of voltage) or ATHD (harmonic distortion of current).

For details, refer to Section 9.2 "Selecting What to Display on Digital Displays" (page 9-8).



Computing Equation

Harmonic distortion (THD) is calculated using the following equation.

- , E [: Calculates the ratio of the rms value of each component (from the 2nd to the nth) in relation to the fundamental (1st).
- <u>C</u> 5 <u>R</u>: Calculates the ratio of the rms value of each component (from the 2nd to the nth) in relation to the rms value of each component (from the 1st to nth).
 (n: Harmonic order set in "Setting the Harmonic Order")
 - 2. Press the **SET UP** key.

Press the \land or \lor key until " \vdash $\not\vdash$ $\not\vdash$ " is displayed on display C.

- 3. Press the **ENTER** key.
- 4. The currently selected computing equation will be displayed on display D. Press the \wedge or \vee key to select the desired equation (, $\xi \in$ or $\xi \in R$).
- 5. Press the **ENTER** key.

Computation equation

When
$$i \in \mathcal{E}$$
 is selected:

$$\left[\sqrt{\sum_{k=2}^{n}(C_k)^2}\right]/C_1$$

When $\begin{bmatrix} 5 \\ 7 \end{bmatrix}$ is selected:

$$\left[\sqrt{\sum_{k=2}^{n} (\mathbf{C}_{k})^{2}}\right] / \left[\sqrt{\sum_{k=1}^{n} (\mathbf{C}_{k})^{2}}\right]$$

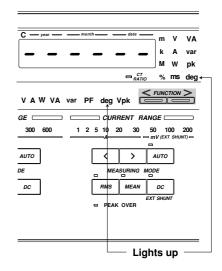
- C_1 : Fundamental (1st) of V (voltage) or A (current)
- Ck : Fundamental or harmonic component of V (voltage) or A (current)
- k : Analysis order
- n : Maximum order. The maximum order varies according to the fundamental frequency of the input set as the PLL source and to whether the anti-aliasing filter is ON or OFF. If this maximum order is smaller than the preset order, the preset order will be used as the maximum order.

9.6 Displaying the Phase Angle between the Fundamentals (Optional)

The phase angle between the fundamentals is displayed on display C.

Function Setting

1. Press the **FUNCTION** key below display C to select **deg (phase angle)**.



Setting the Harmonic Order (to the Fundamental)

2. Set the harmonic order displayed on display A to "1". This causes display C to display the phase angle between the fundamentals (V1 and A1).

For details, refer to Section 9.1 "Operating the Harmonic Analysis Function" (page 9-3).

Phase Angle Display Method

3. The phase angle will be displayed according to the method specified in 5.6, "Displaying the Computed Phase Angle" (page 5-7).

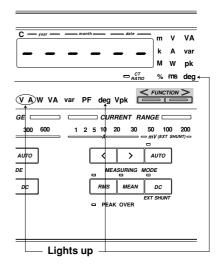
9.7 Displaying the Phase Angle of Each Higher Harmonic in Relation to the Fundamental of Voltage or Current (Optional)

The phase angle of each harmonic in relation to the fundamental of voltage or current is displayed on display C.

Function Setting

Press the *FUNCTION* key below display C to select Vdeg or Adeg (phase angle).

For details, refer to Section 9.2 "Selecting What to Display on Digital Displays" (page 9-7).



Setting the Harmonic Order

2. Press the \wedge or \vee key below display D to set the harmonic order to any value between "2" and the upper limit of the harmonic order.

For details, refer to Section 9.1 "Operating the Harmonic Analysis Function" (page 9-3). This sets which harmonic the phase angle refers to.

If the harmonic order is set to "1", the phase angle between the fundamentals of the same element will be displayed. In this case, the phase angle will be displayed in the phase angle display method set in "Setting Phase Angle Display Method" (page 5-7).

Display Method

Phase angle is displayed as follows based on the fundamental.

- When the harmonic is in front of the fundamental: 0.00 to 18000
- When the harmonic is behind the fundamental: 0.00 to 18000
- When both phases are the same:

Note

 The FUNCTION key located below display A can be used to increase (ORDER UP) the harmonic order respectively. However, it is not possible to change harmonic order fast.

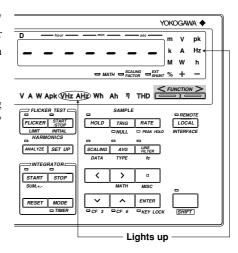
9.8 Displaying the Fundamental Frequency (Optional)

The fundamental frequency of the input selected as the PLL source is displayed on display D.

Function Setting

 Press the FUNCTION key below display D to select VHz (voltage frequency) or AHz (current frequency) which has been selected as the PLL source.

For details, refer to Section 9.2 "Selecting What to Display on Digital Displays" (page 9-8).



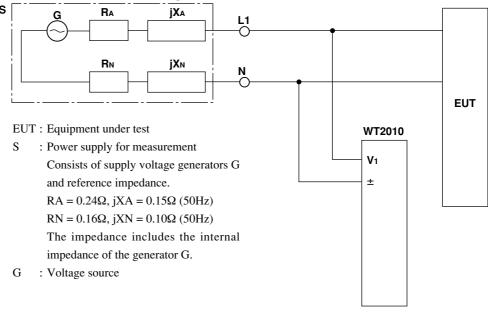
10.1 Using the Voltage Fluctuation/Flicker Measurement Functions (Optional)

This function enables measurement of voltage fluctuation and flicker, as well as display and printout of judgment results obtained by comparing the measured data to the specified limits, in accordance with IEC1000-3-3 (Limitation of voltage fluctuations and flicker for instruments with phase input current of 16 A or below). For a description of printing method, refer to Chapter 11 "Printing Using the Built-in Printer", and for a description of output method via a communication interface, refer to Chapter 14 "Using the Communications Functions".

With this instrument, voltage fluctuation is measured using the following methods.

- Direct voltage measurement method Relative steady-state voltage change Maximum relative voltage change
 Period during which relative voltage change is above the threshold level
- Direct flicker measurement method Short-term flicker value

Wiring Required for Measurement of Voltage Fluctuation/Flicker

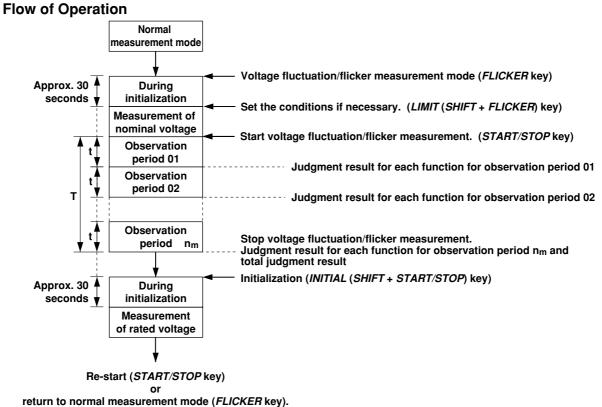


Note

Initialization is performed immediately after the measurement mode is switched from normal measurement to
voltage fluctuation/flicker measurement mode. Thus, make sure that wiring of the instrument is complete and
supply voltage for measurement is input to the terminal of the instrument before switching to voltage
fluctuation/flicker measurement mode.

If supply voltage for measurement is input to the terminal of the instrument after the mode has been switched to voltage fluctuation/flicker measurement mode, press the *INITIAL* (*SHIFT* + *START/STOP*) key to perform initialization. During initialization, make sure the supply voltage for measurement is constant.

- Set the measuring range so that the input is maintained at 50 to 110% of the measuring range during voltage fluctuation/flicker measurement. If the input exceeds 50 to 110% of the measuring range or peak over occurs during voltage fluctuation/flicker measurement, inaccurate measurement or judgment may result.
- The frequency of the input voltage is measured during initialization. If this frequency is not measured accurately, fluctuation/flicker measurements and determination may not be correct. If voltage is not applied to the element being initialized, the frequency cannot be measured accurately. Select the element to which voltage is being applied using the *ELEMENT* key below display (A, B, C or D possible), then press *SHIFT* + *START/STOP*(*INITIAL*) key to reinitialize.



- t : Determined by observation period for short-term flicker value (see page 10-10).
- n_m: Determined by the number of times measurement of short-term flicker value is to be performed (see page 10-10).
- T : Measurement time = t x n_m

To Improve Measurement Accuracy

Before starting voltage fluctuation/flicker measurement, make sure the instrument has been warmed up for at least two hours. Also make the following settings.

- After elapse of more than 5 minutes following input of the supply voltage for measurment to the voltage input terminal, press the *INITIAL* (*SHIFT* + *START/STOP*) key.
- Set the crest factor to "3".
- Turn the line filter OFF.

Note

• When measuring the voltage fluctuation or flicker of an instrument with large rush current, set the cut-off frequency to 5.5 kHz and set the line filter to ON. For the setting method refer to Section 4.1 "Setting Measuring Conditions" (page 4-1).

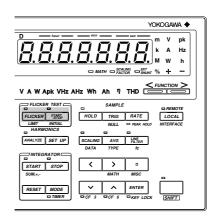
10.2 Operating the Voltage Fluctuation/Flicker Measurement Functions (Optional)

To switch the instrument from normal measurement to voltage fluctuation/flicker measurement, you need to switch the measurement mode to voltage fluctuation/flicker measurement mode then sets the limits to be used for judgment and observation periods.

Setting Voltage Fluctuation/Flicker Measurement Mode Operating the FLICKER Key

Pressing the **FLICKER** key causes the FLICKER indicator LED to light up, indicating that the instrument is in fluctuation/flicker measurement mode.

To return from voltage fluctuation/flicker measurement mode to normal measurement mode, press the **FLICKER** key during initialization (i.e. while the START/STOP indicator LED is blinking). This will cause the FLICKER indicator LED to go out, indicating that the instrument is in normal measurement mode.



Operating the START/STOP Key

In fluctuation/flicker measurement mode, fluctuation/flicker measurement is started and stopped alternately each time the *START/STOP* key is pressed. The FLICKER indicator LED lights up when fluctuation/flicker measurement is started, and it goes out when fluctuation/flicker measurement is stopped.

Pressing the **INITIAL** (**SHIFT** + **START/STOP**) key while fluctuation/flicker measurement is stopped will cause the FLICKER indicator LED to blink and ", n, k" to be displayed on display B, indicating that initialization is now under way.

When you want to re-start fluctuation/flicker measurement after it has been stopped, always carry out initialization.

START/STOP LED	State	START/STOP key	INITIAL (SHIFT+START/STOP) key
Blinking	Initialization	O Start	O Initialization
Continuously lit	Start	O Stop	× (Err25)
Not lit	Stop	× (Err22)	○ Initialization

Note .

- Switching to fluctuation/flicker measurement mode while integration is in progress (START indicator LED is lit) or while integration is stopped (STOP indicator LED is lit) is not allowed. If such an attempt is made, "£ r r {3" will occur. To switch fluctuation/flicker measurement mode in such cases, stop integration, press the *RESET* key, then press the *FLICKER* key.
- Starting integration during fluctuation/flicker measurement mode is not allowed. If such an attempt is made,
 "ξ - ζ ^Ω" will occur.
- Switching to voltage fluctuation/flicker measurement mode while harmonic analysis is in progress is not allowed. If such an attempt is made, "*E* ~ ~ *I E*" will occur. To switch to fluctuation/flicker measurement mode in such cases, press the *ANALYZE* key to return to normal measurement mode, then press the *FLICKER* key.
- Switching to harmonic analysis mode while voltage fluctuation/flicker measurement is in progress is not allowed. If such an attempt is made, " E ー ー ごい will occur. To switch to harmonic analysis mode in such cases, press the *FLICKER* key to return to normal measurement mode, then press the *ANALYZE* key.

Display Update Cycle

The display update cycle during fluctuation/flicker measurement mode is fixed at 2 seconds.

10.3 Setting Measuring Conditions (Optional)

For fluctuation/flicker measurement, measuring conditions must be set prior to start of measurement. Relative voltage change in relation to the rated voltage measured under fluctuation is measured. Moreover, short-term flicker value is measured and calculated for each observation period.

Setting the Nominal Voltage

Set the nominal voltage which is used as the reference for relative voltage change. Select " $\mathcal{A} \sqcup \mathcal{L} \Box$ " if you want to set the nominal voltage by measuring it, or select " $\mathcal{L} \mathcal{L}$ " if you want to use the existing value as the nominal voltage.

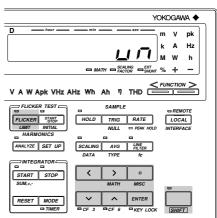
- *1*. Press the **LIMIT** (**SHIFT** + **FLICKER**) key. Press the \land or \lor key until " $_$ $_$ " is displayed on display D.
- 2. Press the **ENTER** key.
- *3*. The symbol displayed on display B will change in the following order, so select the desired symbol.

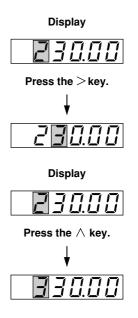
 $\mathcal{R}_{u} \succeq \sigma$ (measured value) $\rightarrow 5 \notin \xi$ (existing value) $\rightarrow \mathcal{R}_{u} \succeq \sigma$

4. Press the **ENTER** key.

If " $5 \notin E$ " is selected in step 3, proceed to step 5.

5. The currently selected existing nominal value is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the \wedge key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The existing nominal voltage can be set within the following range. Settable range : 0.01 to 999.99 (V) Default : 230.00 (V) After the desired value has been set, press the ENTER key.



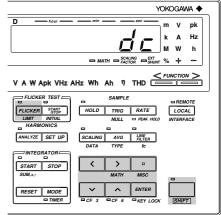


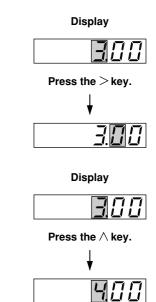
Setting the Limit for Relative Steady-state Voltage Change

- 1. Press the *LIMIT* (*SHIFT* + *FLICKER*) key.
 - Press the \wedge or \vee key until " $d \in$ " is displayed on display D.
- 2. Press the **ENTER** key.
- 3. Determine whether or not relative steadystate voltage change is to be judged. The symbol displayed on display B will change in the following order, so select the desired symbol. $\Box \neg$ (judged) $\rightarrow \Box F F$ (not judged) $\rightarrow \Box \neg$
- 4. Press the **ENTER** key. If " $\Box \neg$ " is selected in step 3, proceed to step 5.
- 5. The currently selected limit for relative steady-state voltage change is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the \wedge key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The limit can be set within the following

Settable range : 1.00 to 99.99 (%)

: 3.00 (%) After the desired limit has been set, press





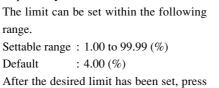
the ENTER key.

range.

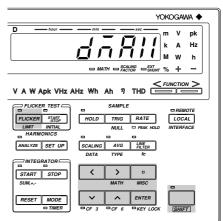
Default

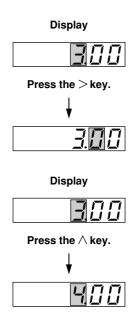
Setting the Limit for Maximum Relative Voltage Change

- 1. Press the LIMIT (SHIFT + FLICKER) key. Press the \wedge or \vee key until "d = R H" is displayed on display D.
- 2. Press the **ENTER** key.
- 3. Determine whether or not maximum relative voltage change is to be judged. The symbol displayed on display B will change in the following order, so select the desired symbol. $g \cap (judged) \rightarrow g \not\in F$ (not judged) $\rightarrow g \cap$
- Press the ENTER key.
 If "an" is selected in step 3, proceed to step 5.
- 5. The currently selected limit for maximum relative voltage change is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the ∧ key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the ∨ key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The limit can be set within the following



the **ENTER** key.





Setting the Limit for Period during which Relative Voltage Change Exceeds the Threshold Level during a Voltage Change and Setting the Threshold Level

- 1. Press the LIMIT (SHIFT + FLICKER) key.
 - Press the \wedge or \vee key until "dE" is displayed on display D.
- 2. Press the **ENTER** key.
- 3. Determine whether or not the period during which relative voltage change is above the threshold level is to be judged. The symbol displayed on display B will change in the following order, so select the desired symbol.

4. Press the **ENTER** key.

If " $\Box \neg$ " is selected in step 3, proceed to step 5.

5. The currently selected limit for the period during which relative voltage change is above the threshold level is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the ∧ key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the ∨ key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively.

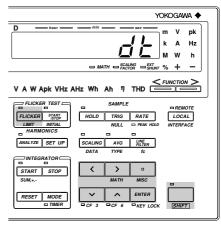
The limit can be set within the following range.

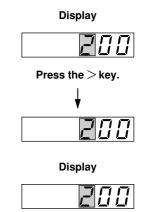
Settable range : 1 to 99999 (ms) Default : 200 (ms) After the desired limit has been set, press the **ENTER** key.

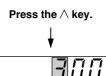
6. The currently selected threshold level is displayed on display D, with the digit on the extreme left blinking. You can set the desired threshold level in the same method

as step 5. The threshold level can be set within the following range. Settable range : 1.00 to 99.99 (%) Default : 3.00 (%)

After the desired threshold level has been set, press the **ENTER** key.

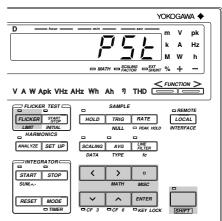


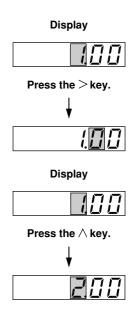




Setting the Limit for Short-term Flicker Value

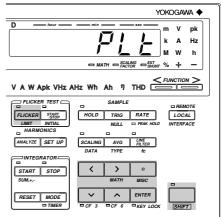
- 1. Press the LIMIT (SHIFT + FLICKER) key. Press the \land or \lor key until " $P \subseteq E$ " is displayed on display D.
- 2. Press the **ENTER** key.
- 3. Determine whether or not short-term flicker value is to be judged. The symbol displayed on display B will change in the following order, so select the desired symbol. a = n (judged) $\rightarrow a = F F$ (not judged) $\rightarrow a = n$
- 4. Press the ENTER key.
 If " a n" is selected in step 3, proceed to step 5.
- 5. The currently selected short-term flicker value is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the \wedge key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The short-term flicker value can be set within the following range. Settable range : 0.10 to 99.99 Default : 1.00 After the desired value has been set, press the ENTER key.

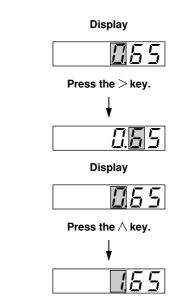




Setting the Limit for Long-term Flicker Value and the Constant used in the Equation

- 1. Press the LIMIT (SHIFT + FLICKER) key. Press the \land or \lor key until "PLE" is displayed on display D.
- 2. Press the **ENTER** key.
- 3. Determine whether or not long-term flicker value is to be judged. The symbol displayed on display B will change in the following order, so select the desired symbol. $a r (judged) \rightarrow a F F (not judged) \rightarrow a r$
- 4. Press the ENTER key.
 If "an" is selected in step 3, proceed to step 5.
- 5. The currently selected long-term flicker value is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the \wedge key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The long-term flicker value can be set within the following range. Settable range : 0.10 to 99.99 Default : 0.65 After the desired value has been set, press the ENTER key.





6. The currently selected constant used in the equation is displayed on display D, with the digit on the extreme left blinking. You can set the desired constant in the same method as step 5.

The constant can be set within the following range.

Settable range : 1 to 99

Default : 12

After the desired constant has been set, press the **ENTER** key.

Note

The equation used to calculate the long-term flicker value is shown below.

$$Plt = \sqrt[3]{\frac{\sum_{i=1}^{n_m} Psti^3}{\sum_{i=1}^{N} Psti^3}}$$

"nm" in the equation indicates the number of times measurement of short-term flicker value (Pst) is to be performed (see page 10-11).

The constant used in the equation is "N". If this constant is greater than the number of times measurement of short-term flicker value is to be performed, measurement of short-term flicker value will be performed the specified number of times, and non-measured short-term flicker value will be calculated as "Pst = 0".

This function is used in cases where the object to be measured stops automatically within the specified measurement time. In general, set the constant to the same value as the number of times measurement of short-term flicker value is to be performed

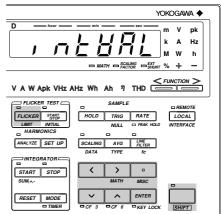
Setting the Observation Period for Short-term Flicker Value

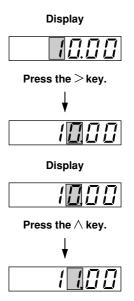
- 1. Press the LIMIT (SHIFT + FLICKER) key. Press the \land or \lor key until ", $\neg \models \forall \exists \downarrow$ " is displayed on display D.
- 2. Press the **ENTER** key.
- 3. The currently selected observation period for short-term flicker value is displayed on display D, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the ∧ key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the ∨ key changes the value in the opposite direction. However, seconds can be set only in even values. The blinking position can be shifted to the left or right by pressing the < or > key respectively.

The number of times can be set within the following range.

Settable range : 0 min 30 s to 15 min 00 s Default : 10 min 00 s

After the desired observation period has been set, press the **ENTER** key.



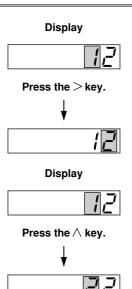


Setting the Number of Times Measurement of Short-term Flicker Value is to be Performed

- Press the LIMIT (SHIFT + FLICKER) key.
 Press the ∧ or ∨ key until "[□ u ∩ E" is displayed on display D.
- 2. Press the **ENTER** key.
- 3. The currently selected number of times measurement of short-term flicker value is to be performed is displayed on display D, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the \wedge key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively. The number of times can be set within the following range. Settable range: 1 to 99 Default : 12

After the desired value has been set, press the **ENTER** key.



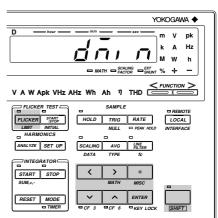


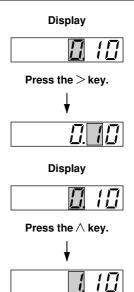
Note

- Measurement time for short-term flicker value is given below.
- Observation period for short-term flicker value x Number of times measurement of short-term flicker value is to be performed

Setting the Steady-state Range

- Set the allowable range for steady-state relative voltage change.
 - 1. Press the LIMIT (SHIFT + FLICKER) key. Press the \wedge or \vee key until " $d\bar{n} \cdot n$ " is displayed on display D.
 - 2. Press the **ENTER** key.
 - 3. The currently selected allowable range is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the ∧ key changes the value in the order 1, 2, 3, ... 9, 0 and back to 1. Pressing the ∨ key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively.





The allowable range can be set within the following range.

Settable range : 0.10 to 9.99 (%)

Default : 0.10 (%)

After the desired range has been set, press the **ENTER** key.

10.4 Displaying the Voltage Fluctuation and Flicker Values (Optional)

Initializing Voltage Fluctuation/Flicker Measurement and Measuring Nominal Voltage

Press the **FLICKER** key. Voltage fluctuation/flicker measurement mode will be activated and initialization is performed. ", σ , ξ " is displayed on display B during initialization. Measurement of nominal voltage (Un) is also performed during initialization.

The nominal voltage value will be displayed C and nominal voltage frequency on display D. They will be updated every 2 seconds.

Note

Initialization is performed immediately after the measurement mode is switched from normal measurement to
voltage fluctuation/flicker measurement mode. Thus, make sure that wiring of the instrument is complete and
supply voltage for measurement is input to the terminal of the instrument before switching to voltage
fluctuation/flicker measurement mode.

If supply voltage for measurement is input to the terminal of the instrument after the mode has been switched to voltage fluctuation/flicker measurement mode, press the *INITIAL* (*SHIFT* + *START/STOP*) key to perform initialization. During initialization, make sure the supply voltage for measurement is constant.

- The following operations can be performed during measurement of rated voltage.
 - Changing the measuring range (however, no current is displayed) \rightarrow Initialization is performed.
 - Changing the crest factor → Initialization is performed.
 - Turning the scaling function ON or OFF
 - Turning the line filter ON or OFF \rightarrow Initialization is performed.
 - Changing the cut-off frequency for the line filter → Initialization is performed.
 - Starting voltage fluctuation measurement using the START/STOP key (voltage fluctuation/flicker measurement)

Setting the Function for Voltage Fluctuation Measurement

When performing voltage fluctuation measurement, use the *FUNCTION* key located below display A to set the measured data to be displayed.

Operating the FUNCTION Key

Press the **FUNCTION** key below display A to set the function to be displayed during voltage fluctuation measurement. The function is switched in the following order each time the **FUNCTION** key is pressed.

Starting Voltage Fluctuation/Flicker Measurement

Press the **START/STOP** key.

For a detailed description, refer to Section 10.2 "Operating the Voltage Fluctuation/Flicker Measurement Functions".

Data Displayed during Measurement

During voltage fluctuation/flicker measurement, the following data is displayed as follows when the *FUNCTION* key located below display A is pressed.

Display A	Display B	Display C	Display D
 	None	Nominal voltage	Input voltage frequency
d = and observation period	Limit	Maximum value (up to now)	Elapsed time
$d \bar{a} \bar{R} H$ and observation period	d Limit	Maximum value (up to now)	Elapsed time
d = and observation period	Limit	Maximum value (up to now)	Elapsed time
$P \subseteq E$ and observation period	Limit	(no data)	Elapsed time
PLE	Limit	(no data)	Elapsed time
totRL	None	(no data)	Elapsed time

Maximum values which can be displayed during measurement are shown below.

dc : 999.99% df RH : 999.99% dE : 99999 ms P5E : 999.99 PLE : 999.99

"-- $_{\Box}F$ --" will be displayed if these maximum values are exceeded.

Note .

• "P5E" and "PLE" are not displayed until measurement is complete.

- "LoERL" is not displayed until judgment is complete.
- If instantaneous flicker value exceeds 6400 level during an observation period, "-- p L -- " will be displayed as the short-term flicker value (P 5 L) measured during that observation period and "F R, L" displayed as the judgment result for the short-term flicker value.

Setting the Observation Period

The observation period set for short-term flicker value is considered as one observation period, and the first observation period is displayed as " \Box l".

To increase the observation period for " $d \in$ ", " $d \in \mathcal{R}$!!", " $d \in$ " and " $\mathcal{P} \subseteq \mathcal{E}$ ", press the \wedge key. To decrease it, press the \vee key.

The elapsed time of observation period which finished a measurement will be displayed in the judgment result.

Note .

• If the *INITIAL* (*SHIFT* + *START/STOP*) key is pressed during display of judgment result, initialization will be performed and measurement of nominal voltage is started.

Stopping Voltage Fluctuation/Flicker Measurement

When measurement of short-term flicker value (Pst) has been performed the number of times specified in 10.3 "Setting Measuring Conditions, voltage fluctuation/flicker measurement will be stopped, and the judgment result is displayed. The START/STOP indicator LED will also go out. If the **START/STOP** key is pressed during voltage fluctuation/flicker measurement, the data measured up to the depression of the **START/STOP** key will be used to make judgment, and the judgment result is then displayed.

10.5 Displaying the Judgment Result (Optional)

The judgment result is displayed for the observation periods for which measurement has been completed or it is displayed when voltage fluctuation/flicker measurement is stopped. The judgment result for each function is displayed as follows when the *FUNCTION* key located below display A is pressed.

Display A	Display B	Display C	Display D
បក	None	Nominal voltage	Input voltage frequency
$d \subseteq$ and observation period	Limit	Maximum value (within the observation period)	Judgment result*1,*2
$d \bar{a} R H$ and observation period	Limit	Maximum value (within the observation period)	Judgment result ^{*1}
d = and observation period	Limit	Maximum value (within the observation period)	Judgment result*1
$P \subseteq E$ and observation period	Limit	Calculation result	Judgment result*1
PLE	Limit	Calculation result	Judgment result ^{*1}
totRL	None	Total judgment result ^{*3}	Elapsed time

- *1 For judgment result, "PR55" will be displayed if no voltage change has exceeded the specified limit, otherwise "FR12" will be displayed. For items which have been set to be not judged (i.e. "oFF"). "____" will be displayed.
- *2 If the display of display C of "d c" is " $u c d \xi F$ " (refer to next page), " $\xi c c c$ " is displayed.
- *3 If all the items which have been set to be judged are "PR55", the total judgment result will be "PR55".

Displaying the Observation Period

To increase the observation period for "dc", " $d\bar{c}R$!!", "dE" and "PSE", press the \wedge key. To decrease it, press the \vee key.

Note .

If the **INITIAL** (**SHIFT** + **START/STOP**) key is pressed during display of judgment result, initialization will be performed and measurement of nominal voltage is started.

10.6 Points to Note during Use of the Voltage Fluctuation/Flicker Measurement Function (Optional)

Limits Specified in IEC1000-3-3

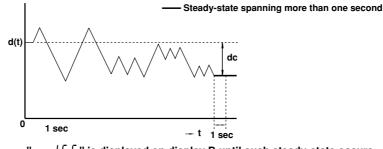
IEC1000-3-3 (Limitation of voltage fluctuations and flicker for instruments with phase input current of 16 A or below) specifies the limits as follows.

Relative steady-state voltage change	dc	3% or less
Maximum relative voltage change	dmax	4% or less
Total duration during which relative	d (t) 200 ms	200 ms or below
voltage change exceeds 3%		
Short-term flicker value	Pst	1.00 or less
Long-term flicker value	Plt	0.65 or less
Observation period	10 minutes	
Number of times measurement is performed	12	
Constant used in the equation	12	

Relative Steady-state Voltage Change (dc)

In IEC1000-3-3, relative steady-state voltage change (dc) is defined with assumption that steadystate exists more than twice.

This instrument assumes that a steady-state has existed once before measurement is started, and displays the measured relative steady-state voltage change (dc) if voltage fluctuation occurs more than once and then a steady-state continues for more than one second after the **START/STOP** key is pressed to start measurement. If no steady-state spanning more than one second exists, " $u r_1 d \xi F$ " will be displayed on display C until such steady-state occurs. If no voltage fluctuation occurs after measurement is started, "0" will be displayed as dc.

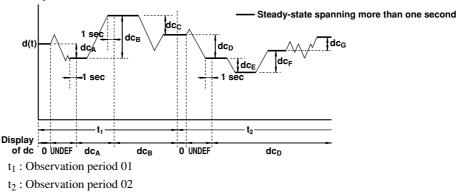


" $u = d \in F$ " is displayed on display B until such steady-state occurs. If a steady-state spanning more than one second occurs, the measured value will be displayed.

Display of dc, dmax and d (t) 200ms

dc, dmax and maximum d (t) $_{200ms}$ within each observation period are displayed.

Example of dc



Operating the Front Panel Keys during Voltage Fluctuation/Flicker Measurement Mode

During voltage fluctuation/flicker measurement mode, some front panel keys are disabled for functions which cannot be used or have no effect. A detailed description for such limitations is given below.

Function	Кеу	INITIAL LED: Blinking	START LED: Lit Steadily	STOP LED: Not Lit
	FLICKER	0	×	×
Flicker	LIMIT (SHIFT + FLICKER)	(Setting possible)	Δ	\bigtriangleup
THERE	START/STOP	0	0	×
	INITIAL	0	×	0
	(SHIFT + START/STOP)			
Range	VOLTAGE AUTO, $<$, $>$	O (×AUTO)	×	×
	CURRENT AUTO, < , >	O (×auto)	×	×
Measurement Mode	BMS/MAIN/DC	V: ×	V: ×	V: ×
Measurement Mode	AMS/MAIN/DC	A: ×	A: ×	A: ×
	HOLD	×	×	×
Sampling	TRIG	_	_	_
	RATE	Fixed at 2 seconds	Fixed at 2 seconds	Fixed at 2 seconds
	NULL (SHIFT+TRIG)	×	×	×
NULL Function	PEAK HOLD (SHIFT+RATE) ×	×	×
Line Filter	LINE FILTER	0	×	×
Cut-off Frequency	fc (SHIFT+LINE FILTER)	0	Δ	Δ
Averaging	AVG	×	×	×
Scaling	SCALING	0	×	×
Crest Factor	<i>CF3</i> (<i>SHIFT</i> + ∨) <i>CF6</i> (<i>SHIFT</i> + ∧)	0	×	×
TT	ANALYZE	×	×	×
Harmonic Analysis	SET UP	0	0	0
	START	×	×	×
Computation	STOP	×	×	×
Function	RESET	×	×	×
	MODE	0	0	0
Frequency Filter	F-FiLt	0	0	0
	(SHIFT + □ (MISC) + ∨ or ∧)			

 \times : Key operation is not possible.

 \bigcirc : Key operation is possible.

 \triangle : Confirmation only is possible

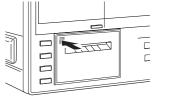
Pressing a key which cannot be used will display "E - - 22", "E - - 24", "E - - 25" or "E - - 25" on display D.

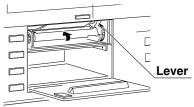
11.1 Loading a Roll Chart (Optional)

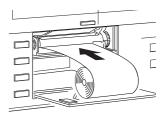
- *1*. Press the left upper corner of the printer cover to open the cover.
- 2. Lift the paper feed guide lever in the direction shown by the arrow to release the paper lock.
- 3. Insert the paper underneath the paper feed guide. Make sure that the paper is not skewed. Press the *FEED* key to feed the paper. (Make sure that the paper is fed in the direction as illustrated. If the paper is fed in the opposite direction, printing cannot be performed.)
- 4. Hold down the **FEED** key until approximately 10 cm of the paper comes out of the top of the guide.
- 5. Push the middle of the guide in the direction shown by the arrow to secure the paper.

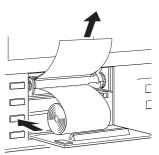
- 6. Place the paper inside the printer and pass the end of the paper through the slot in the printer cover.
- 7. Close the printer cover.

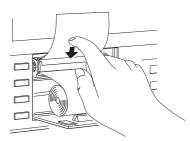
To cut the paper, just pull it upwards. If the printer cover is opened immediately after the paper is cut, press the *FEED* key to feed the paper until the end of the paper comes out through the slot in the printer cover.

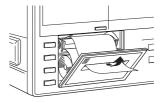


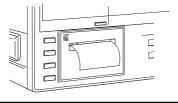












- Note
 - Never press the *FEED* key if the PAPER ERROR LED is lit, except when loading a roll chart into the printer, otherwise a breakdown may result.

11.2 Setting Printer Output Functions (Optional)

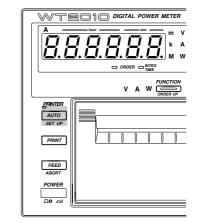
The setting method of the printer output functions differs from that of the communications output functions. For the setting method of the communications output functions, refer to Section 14, "Using the Communications Functions". For print examples, refer to Appendix 3, "Print Examples".

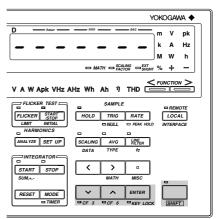
Selecting the Output Function Setting Menu

- *1*. Press the **SET UP** key (**SHIFT** + **AUTO**.)
 - " P_{r} , r_{r} ξ " will be displayed on display A. Press the \wedge or \vee key until", $\xi \xi \bar{r}$ " is displayed on display B.
- 2. Press the **ENTER** key.



- 3. Press the \wedge or \vee key to select the desired output function.
 - n or c : Used to select output items for normal measurement.
 - HRr : Used to select output items for harmonic analysis (optional).
 - $F \downarrow I \downarrow Used to select output items for flicker measurement (optional).$
- 4. Press the **ENTER** key.





Selecting Output Format

5. Press the \land or \lor key to select the desired output format.

Five output formats are available.

- $\exists F \downarrow \vdash i$: Default output items are selected. (Refer to this page and next pages.)
- $\exists F \downarrow \vdash 2$: Default output items are selected. (Refer to next pages.)
- $R \ge 1$: All the output items which can be set with the instrument are selected.
- 5 E L : Desired output items can be selected manually.
- $[L \in R_r]$: No output items are selected.
- 6. Press the **ENTER** key.

Output Items when " $\sigma \sigma c$ " is Selected as the Output Function and " $d F \lfloor b - c$ " is Selected on Display C:

- V1 Voltage
- A1 Current
- W1 Active power
- Hz Measured frequency

Output Items when "a a c" is Selected as the Output Function and " $d F \downarrow b - d$ " is Selected on Display C:

W1	Active power
Wh1	Watt-hour
Wh+1	Positive watt-hour
Wh-1	Negative watt-hour
Ah1	Ampere-hour
Ah+1	Positive ampere-hour
Ah-1	Negative ampere-hour
Hz	Measured frequency
HM	Elapsed time of integration

Output Items when " HB_{r} " is Selected as the Output Function and " $dFLE_{r}$ " is Selected on Display C:

V1	Total rms value of voltage and analysis value of each harmonic from 1st up to n*th
A1	Total rms value of current and analysis value of each harmonic from 1st up to n*th

- W1 Total rms value of active power and analysis value of each harmonic from 1st up to n*th
- VTHD1 Harmonic distortion of voltage
- ATHD1 Harmonic distortion of current
- $VCON1 \qquad Content of each harmonic (from 2nd up to n*th) of voltage$
- ACON1 Content of each harmonic (from 2nd up to n*th) of current
- WCON1 Content of each harmonic (from 2nd up to n*th) of active power
- Hz PLL source frequency

* "n" is the upper limit of the harmonic order.

Output Items when "H R =" is Selected as the Output Function and " $d F \downarrow E = 2$ " is Selected on Display C:

- DEG1 Phase angle between fundamentals
- VDEG1 Phase angle of voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st harmonic
- ADEG1 Phase angle of voltage of each harmonic from 2nd to n^{*}th in relation to current of the 1st harmonic
- Hz PLL source frequency
- * "n" is the upper limit of the harmonic order.

Output Items when "FL = L" is Selected as the Output Function and "dFLE = l" is Selected on Display C:

- CPF1 Cumulative probability function graph
- Judg1 Flicker meter judgment result table

Output Items when " $F \downarrow F \subseteq U$ " is Selected as the Output Function and " $dF \downarrow E - 2$ " is Selected on Display C:

Judg1 Flicker meter judgment result table

Output Items when " $5 \notin 1$ " is Selected on Display C:

If " $5 \notin L$ " is selected, the output item setting mode is activated. An output item will be displayed on display C, and display D can be used to determined whether the item is to be output or not.

Display B	Display C	Display D
ngr		

Setting Output Items and Elements

1. Press the \wedge or \vee key to select the desired output item.

Output Items which can be Selected: When " o o r" is Selected as the	
Output Function	

법(V)	R (A)	P (W)
₩ ₽ (VA)	HRr(var)	P F (PF)
<i>ጉ ዋ</i> (Frq)	ዎ ¦ _h (Wh)	ም አ ም (WhP)
ም ት ቫ (WhM)	ቭ ኯ(Ah)	ም ት
Rha(AhM)	d E L(deg)	HP(V peak)
A peak)	$\overline{A} R \ge H$ (computation etc.)	E (Elapsed time of integration)

Output Items which can be Selected: When $"\,{\it H\,R\,}_{\it C}\,"$ is Selected as the Output Function

$ \mathcal{H}(\mathbf{V}) \qquad \qquad \mathcal{P}(\mathbf{A}) $		P (W)	
$d \notin \mathcal{L}(deg)$ $\mathcal{L} - \mathcal{U}(Graph of voltage)$		[] - ℜ(Graph of current)	
[] - P(Graph of power)	\Box – \mathcal{R} d (Graph of current phase angle)		
[[- H(Graph of voltag	$\Box - \mathcal{R}$ (Graph of current content)		
$\begin{bmatrix} L & -P \\ (Graph of power content) \end{bmatrix}$			

Output Items which can be Selected: When "F \underline{L} , \underline{L} \underline{P} " is Selected as the Output Function

[P F (Cumulative probability function graph)

 $\Box \Box \Box \Box$ (Flicker meter judgment result table)

Note .

• If many output items are selected, it may take some time before the printer begins to print. In this case, reduce the number of output items or hold measurement.

2. Press the **ENTER** key.

" $\Box \cap$ " or " $\Box \not F \not F$ " on display D will begin to blink.

3. Press the \land or \lor key to select " $\Box \neg$ " or " $\Box F F$ ".

4. Press the **ENTER** key.

The digit on the extreme left on display C will begin to blink automatically, so set the desired output item (or element).

- 5. Repeat steps 1 to 4 until all the desired output items have been selected.
- 6. To exit in the middle of selection of output items, press the **AUTO (SET UP)** or **SHIFT** key.

|--|

•	The following frequency data	will be output.
	During normal measurement	: Frequency selected on display D or frequency of the function previously
		selected on display D
	During harmonic analysis	: Frequency of PLL source

11.3 Printing a Set-up Information List

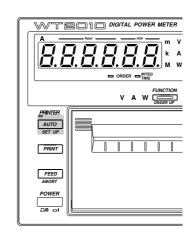
Set-up Information which can be Printed

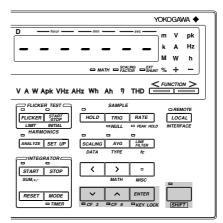
Set-up information which can be printed is given in Appendix 3.

The output format is the same as that used by the OS communications command, except that in the case of communications "END" is printed on the last line.

Print Set-up

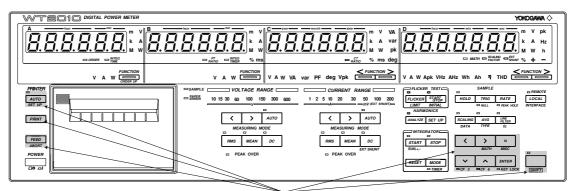
- *1*. Press the **SET UP** key (**SHIFT** + **AUTO**.) Press the \land or \lor key until " P_{\Box} ' is displayed on display B.
- Press the ENTER key to start printing. When printing is complete. Measurement will be resumed.





11.4 Printing Measured Values in Manual or Auto Print Mode (Optional)

Keys used for Printing



These keys are used.

Printing Measured Values in Manual Print Mode

Procedure

- 1. Press the **PRINT** key.
 - The printer will begin to print out measured values.
 - The **PRINT** key is also valid in auto print mode.

Note

 If many output items are selected, it may take some time before the printer starts to print after the **PRINT** key is pressed.

Printing during flicker measurement (optional)

- Printing is not possible even if the **PRINT** key is pressed during measurement of rated voltage. "E r r 2 "" will occur.
- Printing is not possible even if the *PRINT* key is pressed during measurement of fluctuating voltage (if the time required for one measurement of short-term flicker value has not yet elapsed). "E - 2 G" will occur.
- A cumulative probability function graph regarding the previous measurement time of short-term flicker value will be output if the *PRINT* key is pressed during measurement of fluctuating voltage (if the time required for one measurement of short-term flicker value has already elapsed).
- A cumulative probability function graph and flicker meter judgment result table regarding the previous
 measurement time of short-term flicker value will be output if the *PRINT* key is pressed during display of the
 judgment result (if the time calculated by multiplying the time required for each measurement of short-term
 flicker value by the number of times measurement is carried out has already elapsed).

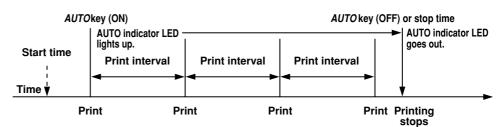
Printing Measured Values in Auto Print Mode

In auto print mode, measured values are printed out automatically at the specified print intervals. They can be printed out in the following three modes.

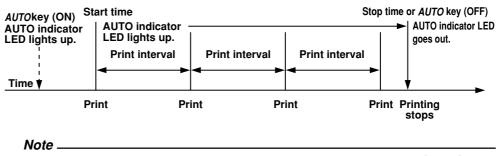
Timer synchronous print	: Prints measured values according to the preset auto print
	start/stop time.
Integration synchronous print	: Prints measured values in synchronization with integration.
Flicker synchronous print (optional)	: Prints measured values at the specified short-term flicker
	intervals when flicker measurement (optional) is in
	progress.

Print timing charts for the **AUTO** key (during timer synchronous print mode) and for a preset start/ stop time are given below.

Print timing when print start time passes before depression of the AUTO key



Print timing when print start time passes after depression of the AUTO key



 If the preset stop time has already passed when the AUTO key is turned ON, error code "Err !?" will be displayed.

1. Press the SET UP key (SHIFT + AUTO.)

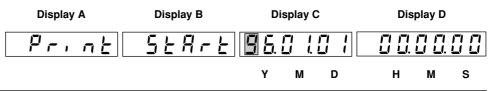
" $P \leftarrow n \leftarrow E$ " will be displayed on display A. Press the \wedge or \vee key until " $5 \dashv n \in E$ " is displayed on display B.

2. Press the **ENTER** key.

Setting the Timer Synchronous Print Mode (Auto Print Start/Stop Time)

- 3. Press the \wedge or \vee key until "*E*, $\overline{\alpha} \in \overline{\beta}$ " is displayed on display C.
- 4. Press the **ENTER** key.
- 5. "5 Ł R r Ł" will be displayed on display B, and the currently selected print output start date is displayed on display C, with the digit on the extreme left blinking. You can change the value at the blinking digit. Pressing the ∧ key changes the value in the order 1, 2, 3 ... 9, 0 and back to 1. Pressing the ∨ key changes the value in the opposite direction. The blinking position can be shifted to the left or right by pressing the < or > key respectively.

After the desired start date has been set, press the **ENTER** key.



- 6. The currently selected print output start time will be displayed on display D, with the digit on the extreme left blinking. Set the start time in the same way as step 5. After the desired start time has been set, press the **ENTER** key.
- 7. "5 Ł o P" will be displayed on display B, and the currently selected print output stop date is displayed on display C, with the digit on the extreme left blinking. Set the stop date in the same way as step 5.

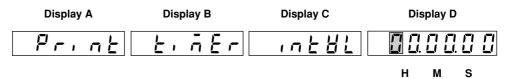
After the desired stop date has been set, press the **ENTER** key.

8. The currently selected print output stop time will be displayed on display D, with the digit on the extreme left blinking. Set the stop time in the same way as step 5. After the desired start time has been set, press the **ENTER** key.

Setting the Print Interval

In auto print mode, measured values are printed out automatically at intervals. Set the print interval as follows.

9. ", $\pi \notin \exists \downarrow$ " is displayed on display C, and the currently selected print interval is displayed on display D, with the digit on the extreme left blinking.



Set the print interval in the same way as step 5.

Allowable minimum interval : 10 s (Error code " $\mathcal{E} \leftarrow \mathcal{E}$ " will be displayed if a value below 10 s is set.)

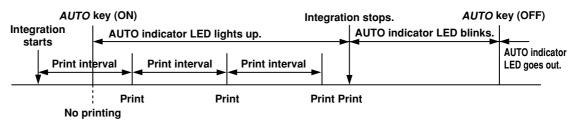
Allowable maximum interval : 99 h 59 min 59 s

After the print interval has been set, press the **ENTER** key.

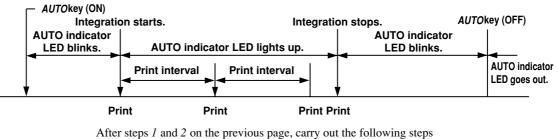
Measured values will be printed automatically as described in "Executing Auto Print" in the next page.

Setting the Integration Synchronous Print Mode

Print timing when integration starts before depression of the AUTO key



Print timing when integration starts after depression of the AUTO key

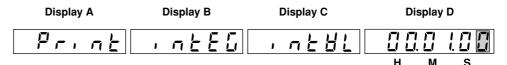


and z on the previous page, early out the following steps

3. Press the \wedge or \vee key until ", $\neg \models \models \sqsubseteq$ " is displayed on display C.

4. Press the **ENTER** key.

5. ", $\neg \in HL$ " will be displayed on display C, and the currently selected print interval is displayed on display D, with the digit on the extreme left blinking.



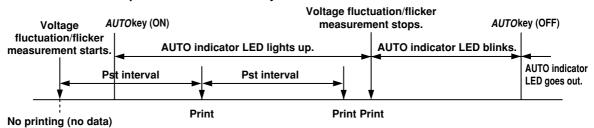
You can change the value at the blinking digit. Pressing the \land key changes the value in the order 1, 2, 3 ... 9, 0 and back to 1. Pressing the \lor key changes the value in the opposite direction.

Allowable minimum interval : 10 s (Error code " $E \leftarrow c \in 2$ " will be displayed if a value below 10 s is set.)

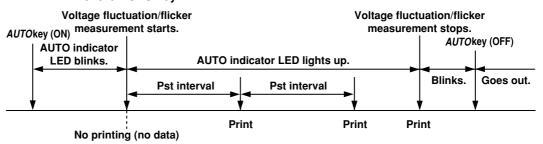
Allowable maximum interval : 99 h 59 min 59 s

After the print interval has been set, press the **ENTER** key. Follow the procedure given on the next page to execute auto print.

Setting the Flicker Synchronous Print Mode Print timing when voltage fluctuation/flicker measurement starts before depression of the AUTO key



Print timing when voltage fluctuation/flicker measurement starts after depression of the *AUTO* key



3. Press the \land or \lor key until "*F* \downarrow , \sqsubseteq \biguplus " is displayed on display C. After steps 1 and 2 on page 11-8, carry out the following steps.

4. Press the **ENTER** key.

Measured values will be printed automatically as described below.

Executing Auto Print

1. Press the **AUTO** key.

The AUTO indicator LED will light up, indicating that the auto print function is ready. Auto printing will be executed according to the settings made. Pressing the **AUTO** key will cause the LED to go out.

Note.

• If the mode is switched from normal measurement mode to harmonic analysis mode while printing is in progress, the printer will stop and auto print mode is also canceled.

Stopping Print Out

To stop printing while printing is in progress, press the **ABORT** key (**SHIFT** + **FEED**).

12.1 External Input/Output Signals (Remote Control, D/A Output)

Use of external input/output signals enables remote control of the instrument as well as output of analog signals from the D/A converter (optional).

Signal Input/Output Function

The remote control/analog output connector can be used for the following purposes.

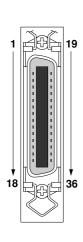
- To start, stop and reset integration (*INTEGRATOR START*, *STOP* and *RESET* keys)
 - \rightarrow Refer to Section "12.2 Remote Control" (page 12-2.)
- To hold and update displayed data (HOLD and TRIG keys)

 \rightarrow Refer to Section "12.2 Remote Control" (page 12-2).

- To output measured/computed data as an analog signal
 - \rightarrow Refer to Section "12.3 D/A Output (Optional)" (page 12-4).

Pin Assignment

The table below shows the pin assignment of the remote control/analog output connector.



 Pin No.	Signal Name	Pin No.	Signal Name
1	DIG GND	19	DIG GND
2	EXT HOLD (input)	20	EXT TRIG (input)
3	EXT START (input)	21	EXT STOP (input)
4	EXT RESET (input)	22	INTEG BUSY (output)
5	EXT PRINT (input)	23	FLICKER BUSY (output)
6	N.C.	24	N.C.
7	N.C.	25	N.C.
8	N.C.	26	N.C.
9	N.C.	27	N.C.
10	D/A GND	28	D/A GND
11	D/A GND	29	D/A GND
12	CH1 (output)	30	CH2 (output)
13	CH3 (output)	31	CH4 (output)
14	CH5 (output)	32	CH6 (output)
15	CH7 (output)	33	CH8 (output)
16	CH9 (output)	34	CH10 (output)
17	CH11 (output)	35	CH12 (output)
18	CH13 (output)	36	CH14 (output)

Note -

• For the location of the connector, refer to Section 1.4 "Part Descriptions and Functions" (page 1-6.)

The GND pins (pins 1 and 19) and D/A GND pins (pins 10, 11, 28 and 29) are connected internally to the case.
For remote control, refer to Section 12.2, "Remote Control" (page 12-2.)

For remote control, refer to Section 12.2, "Remote Control (page 12-2.)
 For D/A outputs, refer to Section 12.3 "D/A Output (Optional)" (page 12-4.)

- The connectors used in this function have protective covers. When the covers are removed or when using connectors, the voltage ratings across the measuring input and the ground become as follows:
 - Voltage across A, ±(V and A side) input terminals and ground 400 Vrms max. Voltage across V terminal and ground 600 Vrms max.

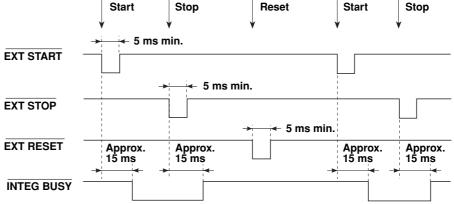
Put the protective cover on the connector when this function is not used.

Never short-circuit the D/A output terminals or apply any external voltage to them, otherwise damage to the instrument may result.

12.2 Remote Control

Controlling Integration



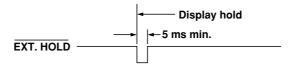


As shown in the timing chart, the INTEG BUSY output signal level goes low while integration is in progress. This signal can be used to monitor integration etc.

Holding Display Data Update and Updating Display Data

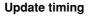
Holding Display Data Update (same function as HOLD key)

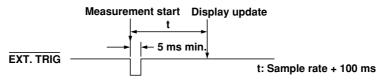
To hold the display data update, apply the EXT HOLD signal according to the timing chart below.



Updating Display Data (same function as TRIG key)

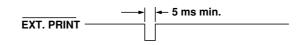
Applying an $\overline{\text{EXT TRIG}}$ signal when the display data is on hold updates the display data.





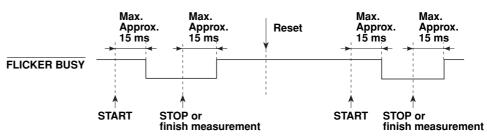
Printing Measured Values to the Built-in Printer (Optional)

To print measured values to the built-in printer, apply the EXT PRINT signal according to the timing chart below.

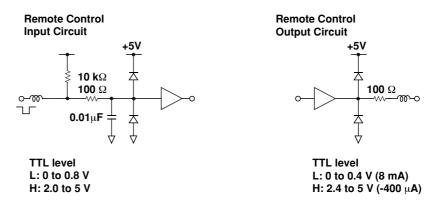


FLICKER BUSY Signal

As shown in the bellow timing chart, the FLICKER BUSY output signal level goes low while fluctuation measurement is in progress. This signal can be used to monitor fluctuation measurement etc.



Remote Control Circuit





• Never apply a voltage exceeding the TTL level to the EXT.HOLD, EXT.TRIG and EXT.PRINT pins, otherwise damage to the instrument will result.

Note

For the pin assignment, refer to Section 12.1 "External Input/Output Signals (Remote Control and D/A Output Signals)

12.3 D/A Output (Optional)

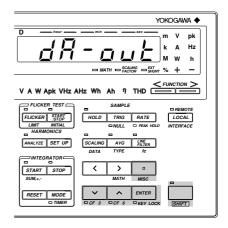
Setting D/A Output

Measured/computed data or harmonic analysis data (analog signal) can be output from the D/A output terminals of the external input/output connector on the rear panel. Up to 14 items (14 channels) can be output.

Selecting the D/A Output Setting Menu

- 1. Press the **MISC** key (**SHIFT** + \Box .) Press the \land or \lor key to display
 - " $\exists R \Box \cup E$ " on display D.
- Press the ENTER key. The currently selected output function will be displayed on display B.
 Default setting : "nor" (output function

for normal measurement)



Selecting Output Function

- 3. Press the \wedge or \vee key to select the desired output function.
 - $\neg \Box \neg$: Used to select output items for normal measurement.
 - ${\it HR}$ ${\it r}~$: Used to select output items for harmonic analysis (optional).
- 4. Press the **ENTER** key.

Selecting Output Format

The output format currently selected is displayed on display C.

5. Press the \land or \lor key to select the desired output format.

The following three output formats are available. For a description of each output item, refer to the following pages.

- $dF \downarrow E l$: Default output items are selected. (Refer to next pages.)
- $d \not\in L \not\in -2$: Default output items are selected. (Refer to next pages.)
- 5 *E L* : Desired output items can be selected manually.
- 6. Press the **ENTER** key.

If " 5ξ ' " is selected, the D/A output channel setting screen is displayed on display C, and the D/A output item and element setting screen is displayed on display D.

• When " ¬ □ ¬ " (normal measurement) is selected as the output function:

Display C	Display D
ch l	<u> </u>

• When " $H \not \exists r$ " (harmonic analysis) is selected as the output function:



• If "5 E L" has been selected, carry out the steps given on page 12-7.

Output Items when " $\neg \Box \neg$ " is Selected as the Output Function and " $d \not\in \underline{L} \not\in$ - :" is Selected on Display C:

Output Channel	Output Item	
ch1	V1	Voltage
ch2	_	_
ch3	_	
ch4	_	
ch5	A1	Current
ch6	_	—
ch7	_	—
ch8	_	_
ch9	W1	Active power
ch10	_	—
ch11	_	—
ch12	_	—
ch13	Measured value on display C	
ch14	Measured value on display D	

Output Items when " $\neg \Box \neg \neg \neg \neg \neg$ " is Selected as the Output Function and " $d F \downarrow E - 2$ " is Selected on Display C:

Output Chann	el Output Item	
ch1	W1	Active power
ch2	—	—
ch3	—	—
ch4	_	—
ch5	Wh1	watt-hour
ch6	—	—
ch7	_	_
ch8	_	_
ch9	Ah1	ampere-hour
ch10	_	_
ch11	_	_
ch12	—	—
ch13	Hz	Measured frequency
ch14	HM	Elapsed time of integration

Output Items when "H B =" is Selected as the Output Function and " $d F \downarrow E = 1$ " is Selected on Display C:

Output Cha	annel Outp	ut Item	
ch1	A1	1st	1st harmonic component data of current
ch2	A1	2nd	2nd harmonic component data of current
ch3	A1	3rd	3rd harmonic component data of current
ch4	A1	4th	4th harmonic component data of current
ch5	A1	5th	5th harmonic component data of current
ch6	A1	6th	6th harmonic component data of current
ch7	A1	7th	7th harmonic component data of current
ch8	A1	8th	8th harmonic component data of current
ch9	A1	9th	9th harmonic component data of current
ch10	A1	10th	10th harmonic component data of current
ch11	A1	11th	11th harmonic component data of current
ch12	A1	12th	12th harmonic component data of current
ch13	A1	13th	13th harmonic component data of current
ch14	Hz		PLL source frequency

Note -

_

 If the upper limit of the harmonic order is 12th or below, harmonic component data up to the upper limit of the harmonic order only will be output. "0V" (no data) will be output for the harmonic component data exceeding the upper limit of the harmonic order.

Output Items when "H R =" is Selected as the Output Function and " $d F \downarrow E = 2$ " is Selected on Display C:

Output Channel	Outp	ut Item	
ch1	A1	1st	1st harmonic component data of current of element 1
ch2	A1	3rd	3rd harmonic component data of current of element 1
ch3	A1	5th	5th harmonic component data of current of element 1
ch4	A1	7th	7th harmonic component data of current of element 1
ch5	_		
ch6			
ch7	_		
ch8			
ch9			
ch10	_		
ch11			
ch12			
ch13	DEG	1	Phase angle between fundamentals
ch14	Hz		PLL source frequency

Note _

 If the upper limit of the harmonic order is 6th or below, harmonic component data up to the upper limit of the harmonic order only will be output. "OV" (no data) will be output for the harmonic component data exceeding the upper limit of the harmonic order.

Selecting the Output Item and Element when " $5 \xi \xi$ " is Selected on Display C Selecting the D/A Output Channel

- 5. Press the \land or \lor key to select the desired output channel.
- 6. Press the **ENTER** key.

Selecting the Output Item and Element

7. Press the \land or \lor key to select the desired output item.

Output Items which can be Selected: When " $\sigma \circ c$ " is Selected as the Output Function

년(V)	P (A)	P (W)
₩ 🖁 (VA)	₩ # ~ (var)	P F (PF)
F - 9(Frq)	ም ե(Wh)	ዎ ¦ _P (WhP)
Phi (WhM)	A H(Ah)	月 日 P(AhP)
Filh a (AhM)	d E G(deg)	HP(V peak)
P(A peak)	$\overline{A} \ \overline{B} \ \underline{E} \ H$ (Computation)	<i>L</i> (Elapsed time of integration)

Output Items which can be Selected: When " HB_{c} " is Selected as the Output Function

₩(V)	P (A)	P (W)
HR(VA)	₩ <i>₽</i> - (var)	P F (PF)
F - 9(Frequency *)	∃ E [(Phase angle)	H H d (Distortion of voltage)
$R \vdash H d$ (Distortion of current)	Content of voltage)	R [_ r (Content of current)
P [و م (Content of power)	$\exists d \in \mathcal{L}$ (Phase angle of voltage)	<i>R</i> <i>d E G</i> (Phase angle of current)

* PLL source frequency

8. Press the **ENTER** key.

If " $\neg \sigma \sigma \tau$ " has been selected, carry out from step 11 on the following page.

Setting the Order

10. If "H = r " is selected as the output format, select the desired order on display D.

Press the \land or \lor key to select the order within the following range.

Allowable range: 0 to 50

It is possible to select "0" for V, A and W only. If "0" is selected, the total rms value will be output.

After the desired order has been selected, press the **ENTER** key.

- 11. The next D/A output channel no. will begin to blink automatically.
- 12.Repeat steps 5 to 9 to set the desired output items and element for each channel.

Quitting Setting Mode

13. To exit from setting mode, follow the procedure below.

After all 14 channels have been set, " $E \cap d$ " is displayed in the channel setting screen (display B or C). To quit setting mode, press the **ENTER** key. To continue making settings, press the \wedge or \vee key to select the desired channel no.

To exit from setting mode in the middle of making settings, press the \Box (*MISC*) or *SHIFT* key.

Note

- When " A > B > H" (computation) is selected, 0 V is output from the D/A converter.
- If the scaling value has been set for voltage, current and power, a voltage of 5.0 V (full scale) will be output from the D/A converter when the rated value is input.
 - The following frequency data will be output from the D/A converter.
 - During normal measurement : Frequency selected on display D or frequency of the function previously selected on display D

During harmonic analysis : Frequency of PLL source

Setting Rated Integration Time when Outputting Integrated Values from the D/A Converter

1. Press the **MISC** key (**SHIFT** + \Box).

Press the \land or \lor key to display ", $\vdash \sqsubseteq - \vdash$ " on display D.

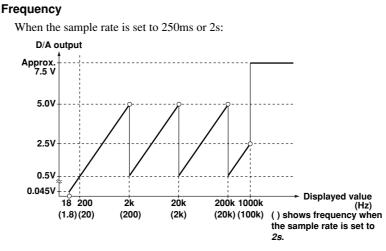
2. Press the **ENTER** key.

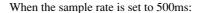
The rated integration time currently set will be displayed on display B. Set the desired time using the \land , \lor , <and > keys. Minimum time allowed : 1 min

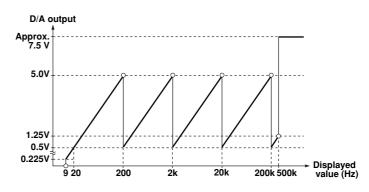
Maximum time allowed : 999 h 59 min

3. When the rated integration time has been set, press the **ENTER** key.

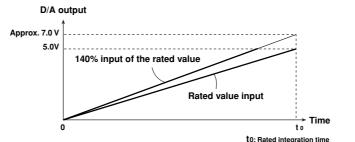
Output Items and D/A Output Voltage

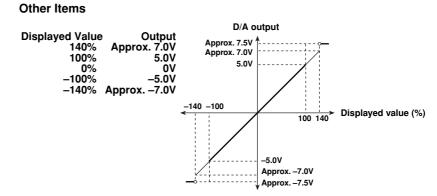






Integrated Value





- The maximum output level is ± 5.0 V for power factor (PF) and phase angle (deg). However, the output will be approx. ± 7.5 V if there is an error.
- If the selected phase angle display method is for 0° to 360°, the output will be between 0 V and +5 V. If the method is for phase lag 180° to phase lead 180°, the output will be between -5.0 V and +5.0 V. The output will be approx. 7.5 V if there is a phase angle error.
- For THD (optional) and content (optional), +5 V will be output when they are 100%.

13.1 Storing, Recalling and Initializing Set-up Information

Storing

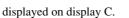
Press the MISC key (SHIFT + □.)
 Press the ∧ or ∨ key until "5 ½ ₀ r £" appears on display D.

2. Press the **ENTER** key.

" $F \in E$!" will be displayed on display B.

3. Press the ∧ or ∨ key to select the file no. of the built-in memory where the set-up information is to be stored. Files from FILE1 to FILE4 are available in

the built-in memory. The state of the selected file will be



VOKOGAWA

If any set-up information already exists in the selected file, the storage date will be displayed. If not, " $F \sim \xi \xi$ " will be displayed.

4. Press the **ENTER** key.

The current set-up information will be stored into the file selected in step 3. If any set-up information already exists in the file, the information will be replaced by the current information. Note that the old information will be deleted.

Note

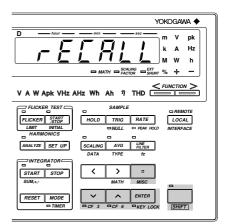
• If the power is turned OFF during storage of the set-up information, not only the file to which the set-up information is being stored will be damaged, but also other files may be initialized.

Recall

- Press the MISC key (SHIFT + □).
 Press the ∧ or ∨ key until " E [R L L " appears on display D.
- 2. Press the ENTER key.
 "F , L E !" will be displayed on display B.
- 3. Press the ∧ or ∨ key to select the file no. of the built-in memory where the set-up information is to be recalled. The state of the selected file will be

displayed on display C.

If any set-up information already exists in the selected file, the storage date will be displayed. If not, "F = E E" will be displayed.



4. Press the **ENTER** key.

The set-up information currently stored in the file selected in step 3 will be recalled. If there is no set-up information in that file, " $\xi \leftarrow \tau \exists \Box$ " error code will be displayed on display D.

Note

- If the power is turned OFF during recalling of the set-up information, " E E" will occur when the power is turned ON again, possibly causing the instrument to be initialized.
- If an attempt is made to recall a file containing voltage fluctuation/flicker measurement data during harmonic analysis, " £ ~ ~ ! £ " will occur.
- If an attempt is made to recall a file containing harmonic analysis data during voltage fluctuation/flicker measurement, " E ー ー 2 []" will occur.

Initialization

1. Press the **MISC** key (**SHIFT** + \Box). Press the \land or \lor key until " $\neg \xi \xi \xi \xi$ " appears on display D.

2. Press the **ENTER** key.

" $r \notin 5 \notin E$ " will shift to display C, and " $n \square$ " begins to blink on display D. If you do not want to initialize the set-up information, press the **ENTER** key.

3. To initialize the set-up information, press the \land or \lor key until " $\exists \xi 5$ " appears, then press the **ENTER** key.

The set-up information will be initialized. All set-up information will be set as shown on page 2-6.

	YOKOGAWA 🔶
D hour —	min min m V pk k A Hz
	MATH DECAUNG DEXT % +
V A W Apk VHz A	หม Wh Ah ๆ THD
FLICKER TEST FLICKER START LIMT INTAL HARMONICS	
ANALYZE SET UP	SCALING AVG LINE DATA TYPE fc
SUM,+,- RESET MODE	MATH MISC

Note

- · All measurement data will be lost when initialization is carried out.
- If the power is turned OFF during initialization, " E - E []" may occur when the power is turned ON again, possibly causing the instrument to be initialized.

13.2 Key Lock Function

The key lock function is provided to prevent key operations during measurement. Operation of all panel keys except the **POWER** and **SHIFT** keys will be disabled.

Enabling Key Lock Function

Press the *KEY LOCK* key (*SHIFT* + *ENTER*). The KEY LOCK indicator LED will light up.

Disabling Key Lock Function

Press the **KEY LOCK** key (**SHIFT** + **ENTER**) when the KEY LOCK indicator LED is lit. The LED will go out.

	YOKOGAWA 🔶
	m V pk
	k A Hz
	M W h
MATH CALING CALING	NT % + -
VAW Apk VHzAHzWhAh १ THD 🖸	
FLICKER TEST SAMPLE	
FLICKER START HOLD TRIG RATE	LOCAL
	LD INTERFACE
ANALYZE SET UP SCALING AVG HITER	l I
DATA TYPE fc	
	1
START STOP	
SUM,+,- MATH MISC	•
RESET MODE Y A ENTER	
TIMER CF 3 CF 6 KEY LOC	CK SHIFT

13.3 Backup Function for Set-up Information

The instrument is equipped with a lithium battery to provide battery backup for the set-up information in case of power failure. The battery lasts for approximately ten years (page 2-5.) The following set-up information can be backed up.

Date Time Voltage ranges, auto range ON/OFF Current ranges, auto range ON/OFF Measurement voltage and current modes Sample rate External shunt Data hold Line filter ON/OFF, cut-off frequency Scaling ON/OFF Scaling constant Averaging ON/OFF Averaging type Attenuation constant Function selected for each display Peak hold ON/OFF peak hold Function Frequency filter ON/OFF NULL function ON/OFF Crest factor Phase angle display format MATH settings Key lock Communication output mode Communication output function ON/OFF Communication output type Communications command Delimiter Presence/absence of header Output interval during talk-only (When equipped with a GP-IB interface) GP-IB address Handshake mode (When equipped with a RS-232-C interface) Data format Baud rate Integration mode Integration timer preset time Integration start/stop time Integrated value Elapsed time of integration Integration polarity setting Harmonic analysis ON/OFF PLL source Harmonic analysis display format Harmonic analysis display order When the harmonic analysis function (optional) is incorporated Upper limit of the harmonic order setting THD computing method Anti-aliasing filter ON/OFF Harmonic analysis window width Print mode Print interval When a built-in printer (optional) is incorporated Print start/stop time Print synchronization Print output function ON/OFF D/A output function (normal) D/A output function (harmonic analysis) When the D/A output function (optional) is incorporated Rated integration time for D/A outputs Flicker measurement ON/OFF Input method for nominal voltage, voltage value when an existing value is to be used Judgment ON/OFF and limits for relative steady-state voltage change dc, maximum When the flicker relative voltage change dmax and the period d(t) 200ms during which relative measurement function voltage change exceeds the threshold level during a voltage change (optional) is incorporated Judgment ON/OFF and limits for short-term flicker value and long-term flicker value Constant for the long-term flicker value equation, time required for measurement of short-term flicker value, number of times measurement is carried out

Steady-state range

14.1 Selecting the Output Items

Output items can be selected from the controller (computer) or panel. The communications function is used to output data to a listener-only device such as a printer.

Procedure

Selecting the Output Item Setting Menu

- *1*. Press the **MISC** key (**SHIFT** + \Box). Press the \wedge or \vee key until " $[\Box - \Box \cup E"$ " is displayed on display D.
- 2. Press the **ENTER** key. The currently selected output function will be displayed on display B. Default setting : " $\neg \neg \neg \neg$ " (output function

for normal measurement) **Selecting Output Function**

- 3. Press the \wedge or \vee key to select the desired output function.
- pk Hz h V A W Apk VHz AHz Wh Ah ๆ THD LICKER_TEST SAMPLE START STOP

YOKOGAWA 🔶

- nar : Used to select output items for normal measurement (normal measurement or integration measurement).
- : Used to select output items for harmonic analysis (optional). HRr
- $F \downarrow F \downarrow F$: Used to select output items for flicker measurement (optional).
- $\Box E \square P E$: Used to select the output data format (ASCII or binary).
- 4. Press the ENTER key.

Selecting Output Format

The output format currently selected is displayed on display C.

- 5. Press the \wedge or \vee key to select the desired output format.
 - The following output formats are available. For details, refer to the following pages.
 - $dF_{L}E l$: Default items are output.
 - $dF \downarrow E 2$: Default items are output.
 - RLL : All items are output.
 - SEL : Desired items can be selected manually.
 - $\begin{bmatrix} L \in R \\ \end{bmatrix}$: No items are output.
 - 85[.. : Items are output in ASCII format (available only when " $a - E \exists P E$ " is selected in step 3)
 - $b \in A \cap Y$: Items are output in binary format (available only when "a = E Y P E" is selected in step 3)
- 6. Press the **ENTER** key.

If " $5 \notin 1$ " is selected in step 5, the output item and element setting menu will be displayed on display C, and the output ON/OFF state is displayed on display D.

Selecting the Output Item and Element when "5 & 1 " is Selected on Display C

- 7. The currently set output item and element are displayed on display C. Press the \land or \lor key to select the desired item.
- 8. Press the > key. Now, an element can be selected. Press the \wedge or \vee key to select the desired element.
 - Elements Which can be Selected:

1 : Element 1

9. Press the **ENTER** key.

The data displayed on display D begins to blink automatically.

Press the \land or \lor key to select whether or not the selected item is to be output.

10.Repeat steps 7 to 9 until all the desired output items have been selected.

Quitting Setting Mode

11. To exit from setting mode, press the **MISC** or **SHIFT** key.

Description of Output Items

Selectable Output Items when "a a c" is Selected as the Output Function and " $d F \downarrow b c$ - /" is Selected on Display C:

- V1 Voltage
- A1 Current
- W1 Active power
- Hz Measured frequency

Selectable Output Items when " $\neg \Box c$ " is Selected as the Output Function and " $dF \downarrow c - c$ " is Selected on Display C:

W1	Active power
Wh1	Watt-hour
Wh+1	Positive watt-hour
Wh-1	Negative watt-hour
Ah1	Ampere-hour
Ah+1	Positive ampere-hour
Ah-1	Negative ampere-hour
Hz	Measured frequency
HM	Elapsed time of integration

Selectable Output Items when " HR_{r} " is Selected as the Output Function and " $dF \downarrow \xi - i$ " is Selected on Display C:

V1	Total rms value of voltage and analysis value of each harmonic from 1st up to n*th	
A1	Total rms value of current and analysis value of each harmonic from 1st up to n [*] th	
W1	Total active power and analysis value of each harmonic from 1st up to the n [*] th	
VTHD1	Harmonic distortion of voltage	
ATHD1	Harmonic distortion of current	
VCON1	Content of each harmonic (from 2nd up to n*th) of voltage	
ACON1	Content of each harmonic (from 2nd up to n*th) of current	
WCON1	Content of each harmonic (from 2nd up to n [*] th) of active power	
Hz	PLL source frequency	
* "n" is the upper limit of the harmonic order		

* "n" is the upper limit of the harmonic order.

Selectable Output Items when " HR_{c} " is Selected as the Output Function and "dFLE - 2" is Selected on Display C:

- DEG1 Phase angle between fundamentals
- DGV1 Phase angle of voltage of each harmonic from 2nd to n^{*}th in relation to voltage of the 1st harmonic
- DGA1 Phase angle of voltage of each harmonic from 2nd to n^{*}th in relation to current of the 1st harmonic

Hz PLL source frequency

* "n" is the upper limit of the harmonic order.

Selectable Output Items when "F ${\tt L}$, ${\tt L}$ ${\tt H}$ is Selected as the Output Function and

"dFLE-1	" is Selected on	Display C:
---------	------------------	------------

Un1	Nominal voltage
dc1	Relative steady-state voltage change
dmax1	Maximum relative voltage change
dt1	Period during which relative voltage change is above the threshold level
Pst1	Short-term flicker value
Plt1	Long-term flicker value
Total1	Total judgment result
VHz1	Input voltage frequency
time1	Elapsed time

Selectable Output Items when " $F \downarrow , [\downarrow]$ " is Selected as the Output Function and

"dFLE-d"	is Selected on Display C:
dc1	Relative steady-state voltage change
dmax1	Maximum relative voltage change
dt1	Period during which relative voltage change is above the threshold level
Pst1	Short-term flicker value
Plt1	Long-term flicker value
Total1	Total judgment result
time1	Elapsed time

List of Selectable Output Items

When " $\sigma \circ \sigma$ " is Selected as the Output Function:

법 (V)	A (A)	/ (W)
H R (VA)	Н Я г (var)	P F (PF)
Frquency)	Ph(Wh)	P h P (WhP)
Phi (WhM)	h (Ah)	A h P (AhP)
AhM)	d E L (deg)	HP (V peak)
A peak)	$\vec{h} \not\in H$ (Computation)	E (Elapsed time of integration)

When " $H \Re r$ " is Selected as the Output Function

Н (V)	P (A)	P (W)
Н Я (VA)	<u>Н</u> Я г (var)	P F (PF)
F - 9 (Frequency [*])	d E [(Phase angle)	H H d (Distortion of voltage)
유 는 뷰 쉽 (Distortion of current)	H [🗗 न (Content of voltage)	ר (Content of current)
ר (Content of power)	H H E G (Phase angle of voltage)	$R \leq E$ (Phase angle of current)

* PLL source frequency

When " $F \downarrow \downarrow \downarrow \Box U$ " is Selected as the Output Function

- $\Box = (Rated voltage)$ $\Box \subseteq (Relative steady-state voltage change)$
- $d \bar{d}$ (Maximum relative voltage change)
- d' (Period during which relative voltage change is above the threshold level)
- P5 L (Short-term flicker value) PLL (Long-term flicker value) LoLL (Total judgment result)
- $\frac{1}{2}H \stackrel{?}{=} (\text{Input voltage frequency}) \stackrel{L}{\leftarrow} \stackrel{r}{\leftarrow} \stackrel{L}{\in} (\text{Elapsed time})$

Note

- If many output items are selected, it may take some time before they are output depending on the state of the
 instrument (sample rate, harmonic analysis, printing). In this case, reduce the number of output items or hold
 measurement.
- If you want to output data at high speed, select the binary format.

14.2 Using the GP-IB Interface

The instrument is equipped with a GP-IB interface in accordance with your preference. This interface permits remote control from a controller such as a personal computer, and output of various data.

Overview of the GP-IB Interface

The table below shows functions that are available in each mode.

Mode	Function	
Addressable mode (mode A and mode B)	Listener	 Functions performed by front panel key operations (except for <i>LOCAL</i> key and power ON/OFF) Measured/computed data output request Panel set-up information output request Error code output request
	Talker	 Measured/computed data output Panel set-up information output Error code output Status byte output
Talk-only mode	Talker	Measured/computed data output

Addressable Mode A

Measured data is output when an "OD" (measured data output request command) is received. This mode enables transmission of measured data at a specified time.

Addressable Mode B

This mode does not require a measured data query command. When measured data is requested by the controller (personal computer etc.), the data is output as the display is updated when measurement is completed. Therefore, if an attempt is made to transmit measured data at intervals shorter than the display intervals, the controller is forced to wait until the next display interval.

488.2 Mode

Protocol commands complying to IEEE St'd 488.2-1987 can be used.

Talk-only Mode

This mode does not require a controller. Measured data is output at certain intervals. The interval can be set to any length. This mode is useful when the instrument is connected to a listener-only device such as a printer.

GP-IB Interface Specifications

Electrical and mechanical specifications : Conforms to IEEE Std 488-1978 (JIS C 1901-1987)Functional specifications: refer to the table blow.Code: ISO (ASCII) codeAddress setting: listener and talker addresses 0 to 31 or talk-only can be
selected using the front panel keys.Remote mode clear: remote mode can be cleared by pressing the LOCAL key on
the front panel. However, this is not possible if Local Lockout
has been set by the controller.

Function Subset Na		Description		
Source handshaking	SH1	Full source handshake capability		
Acceptor handshaking	AH1	Full acceptor handshake capability		
Talker	T5	Basic talker capability, serial polling, untalk on MLA (My Listen Address), talk-only capability		
Listener	L4	Basic listener capability, unlisten on MTA (My Talk Address), no listen-only capability		
Service request	SR1	Full service request capability		
Remote local	RL1	Full remote/local capability		
Parallel poll	PP0	No parallel polling capability		
Device clear	DC1	Full device clear capability		
Device trigger	DT1	Full device trigger capability		
Controller	C0	No controller function		

Response to Interface Messages

IFC (Interface Clear)

Cancels (unaddresses) talker and listener.

REN (Remote Enable)

Transfers the instrument from local control to remote control.

GTL (Go To Local)

Transfers the instrument from remote control to local control.

SDC (Selective Device Clear), DCL (Device Clear)

Clears GP-IB input/output buffer, and resets an error. The set-up information and measurement state are not affected.

DCL is applicable to all devices on the bus, whilst DSC is applicable only to designated devices.

GET (Group Execute Trigger)

Same function as the TRIG key.

LLO (Local Lockout)

Invalidates the *LOCAL* key on the front panel to inhibit transfer from remote control to local control.

Switching between Remote and Local Mode

When Transferred from Local to Remote Mode

The REMOTE indicator LED will light up. All front panel keys except the *LOCAL* key cannot be operated any more. Set-up information entered in local mode is retained.

When Transferred from Remote to Local Mode

The REMOTE indicator LED will go out. All front panel keys can be operated. Set-up information entered in remote mode is retained.

Valid Keys for Remote Control

Pressing the *LOCAL* key in remote control transfers the instrument to local control. However, this is not possible if Local Lockout has been set by the controller.



• The connectors used in this function have protective covers. When the covers are removed or when using connectors, the voltage ratings across the measuring input and the ground become as follows:

Voltage across A, ±(V and A side) input terminals and ground 400 Vrms max. Voltage across V terminal and ground 600 Vrms max.

Put the protective cover on the connector when this function is not used.

Setting the Address/Addressable Mode

Procedure

Setting the Addressable/Talk-only Mode

Press the **LOCAL** key to display the mode setting screen on display B. Pressing the \land or \lor key changes the mode in the order of " $\Re ddr$ \Re " \rightarrow " $\Re ddr$ b" \rightarrow " $E an L \Im$ " \rightarrow " $\Im \Re dr$ \Im " and back to " $\Re ddr$ \Re ".

Select the desired mode, then press the **ENTER** key.

Setting the Address

If addressable mode (AddrA, AddrB or 488.2) is selected, the address setting screen will be displayed on display D.

Press the \land , \lor , < or > key to select the desired address, then press the **ENTER** key.

Setting the Output Interval (when talk-only mode is selected)

If talk-only mode (tonly) is selected, the output interval setting screen will be displayed on display D.

Press the \land , \lor , < or > key to set the desired interval (in units of hour, minute and second), then press the **ENTER** key.

Setting the Sending Terminator (when mode except for 488.2 is selected)

When the address or output interval is set, the sending terminator setting screen will be displayed on display D.

Pressing the \land or \lor key changes the terminator in the order of $[\neg F \downarrow F \rightarrow \downarrow F \rightarrow \downarrow F \rightarrow \downarrow G$, and back to $[\neg F \downarrow F$. Select the desired terminator, then press the **ENTER** key.

Note

 For 488.2 mode (command specified in IEEE488.2-1987), the sending terminator is fixed to LF. Thus, the sending terminator setting screen will not be displayed if 488.2 is selected.

Description

Setting the Mode

For details, refer to page 14-4.

Setting the Address

A particular address is assigned to each device connected to the GP-IB interface so that each device can be recognized by every device. Therefore, an address must be assigned to this instrument when it is connected to a personal computer.

Setting range : 0 to 30 Default setting : 1

Setting the Output Interval

If talk-only mode is selected, it is necessary to set the intervals at which data is to be output. Setting range : 00.00.00 (0 h 0 min 0 s) to 99.59.59 (99 h 59 min 59 s) Default setting : 00.00.00

If the output interval is set to 00.00.00, data will be output at every sample rate.

Terminator

- When this instrument is used as a listener
- Use "CR+LF", "LF" or "EOI" as the receiving terminator.
- When this instrument is used as a talker

Use "CR+LF+EOI", "LF" or "EOI" as the sending terminator. The default setting is "CR+LF+EOI".

Using an IEEE488.2-1987 Command

Select "4882" in the mode setting screen. For a description of each command, refer to Appendix 2.

Note .

[•] It is not possible for this instrument to receive data if only the "CR" terminator is sent from the controller. It is also not possible to set "CR" as the terminator which is to be sent from this instrument.

14.3 Using the RS-232-C Interface

The instrument is equipped with an RS-232-C interface in accordance with your preference. This interface permits remote control from a controller such as a personal computer, and output of various data.

Overview of the RS-232-C Interface

The table below shows functions that are available in each mode.

Mode	Function	
Normal mode	Reception	 Functions performed using front panel key operations (except for <i>LOCAL</i> key and power ON/OFF)
		 Measured/computed data output request Panel set-up information output request Error code output request
	Transmission	 Measured/computed data output Panel set-up information output Error code output Status byte output
Talk-only mode	Transmission	Measured/computed data output

Normal Mode

This mode is equivalent to addressable mode A of the GP-IB interface function, and enables reception of commands and transmission of measured data. Measured data is output on reception of the OD command.

488.2 Mode

The command being use at GP-IB complying to the IEEE St'd 488.2-1987 standard can be received.

Talk-only Mode

There is no mode that is equivalent to the addressable mode B of the GP-IB interface function with this instrument.

RS-232-C Interface Specifications

Electrical characteristics	Conforms to EIA RS-232-C.
Connection	Point-to-point
Communications	Full-duplex
Synchronization	Start-stop system
Baud Rate	75, 150, 300, 600, 1200, 2400, 4800 and 9600
Start Bit	1 bit
Data Length (Word Length)	7 or 8 bits
Parity	Even, odd or no parity
Stop Bit	1 or 2 bits
Hardware Handshaking	User can select whether CA and CB signals will always be True, or be used for control.
Software Handshaking	User can select whether to control only transmission or both transmission and reception using X-on and X-off signals. X-on: ASCII 11H X-off: ASCII 13H
Receive Buffer Size	256 bytes

• The connectors used in this function have protective covers. When the covers are removed or when using connectors, the voltage ratings across the measuring input and the ground become as follows:

Voltage across A, ±(V and A side) input terminals and ground 400 Vrms max. Voltage across V terminal and ground 600 Vrms max.

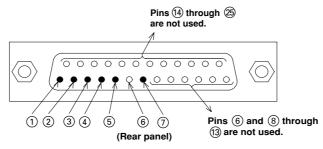
Put the protective cover on the connector when this function is not used.

Connecting the RS-232-C Interface Cable

When connecting this instrument to a personal computer, make sure that the handshaking method, data transmission rate and data format selected for the instrument match those selected for the computer. Also make sure that the correct interface cable is used.

Connector and Signal Names

Numbers in the figure represent pin nos.



RS-232-C connector: DBSP-JB25S or equivalent

1	AA (GND; Protective Ground)	Grounded to the case of this instrument.
2	BA (TXD; Transmitted Data)	Data transmitted to personal computer
		Signal direction: Output
3	BB (BXD; Received Data)	Data received from personal computer
		Signal direction: Input
4	CA (RTS; Request to Send)	Signal used to handshake when receiving data from personal
		computer
		Signal direction: Output
5	CB (CTS; Clear to Send)	Signal used to handshake when transmitting data to personal
		computer
		Signal direction: Input
7	AB (GND; Signal Ground)	Ground for signals

Note.

• Pins 6 and 8 through 25 are not used.

Signal Direction

The figure below shows the direction of the signals used by the RS-232-C interface.

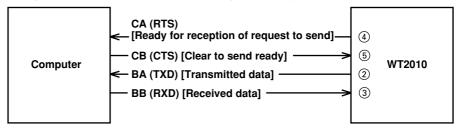


Table of RS-232-C Standard Signals and their JIS and CCITT Abbreviations

Pin No.	Abbreviations			Nama		
(25-pin connector)	RS-232-C	CCITT	JIS	Name		
1	AA(GND)	101	FG	Protective ground		
7	AB(GND)	102	SG	Signal ground		
2	BA(TXD)	103	SD	Transmitted data		
3	BB(RXD)	104	RD	Received data		
4	CA(RTS)	105	RS	Request to send		
5	CB(CTS)	106	CS	Clear to send		
6	CC(DSR)	107	DR	Data set ready		
20	CD(DTR)	108/2	ER	Data terminal ready		
22	CE(RI)	125	CI	Ring indicator		
8	CF(DCD)	109	CD	Data channel received carrier detect		
21	CG(-)	110	SQD	Data signal quality detect		
23	CH/CI(-)	111	SRS	Data signal rate select		
24/15	DA/DB(TXC)	113/114	ST1/ST2	Transmitter signal element timing		
17	DD(RXC)	115	RT	Receiver signal element timing		
14	SBA(-)	118	BSD	Secondary transmitted data		
16	SBB(-)	119	BRD	Secondary received data		
19	SCA(-)	120	BRS	Secondary request to send		
13	SCB(-)	121	BCS	Secondary clear to send		
12	SCF(-)	122	BCD	Secondary received carrier detect		

Table

* Circles indicate pins used for the RS-232-C interface of this instrument.

Setting Communications Mode, Handshake Mode, Data Format and Baud Rate Procedure

Selecting the Item

Press the **LOCAL** key to display the item setting screen on display B. Pressing the \land or \lor key changes the item in the order of "h R n d" \rightarrow " $F \circ r$ " \rightarrow " $b - r R \vdash E$ " \rightarrow " $E \vdash r n$ " \rightarrow " $\bar{r} \circ d \in$ " and back to "h R n d".

Select the desired item, then press the **ENTER** key to confirm the selection.

Setting the Normal/Talk-Only Mode

If "MODE" is selected and confirmed, the mode setting screen will be displayed on display D. The mode changes in the order of " $\neg \neg \neg \neg$ " $\vdash \neg \neg \downarrow \Box \neg \Box \Box \Box$ " \rightarrow " $\vdash \Box \neg \Box \Box \Box$ " and back to " $\neg \neg \neg \neg$ ". Select the desired mode using the \land , \lor , < and > keys, then press the **ENTER** key.

Setting the Handshake Mode, Data Format, Baud Rate and Sending Terminator

If "HAND" is selected and confirmed, the handshake mode setting screen will be displayed on display D. Press the \land or \lor key to select the desired handshake mode, then press the **ENTER** key. The format setting screen will be displayed on display D.

Set the data format, baud rate and sending terminator by the same method the handshake mode is selected.

Setting the Output Interval (when talk-only mode is selected)

If talk-only mode is selected in the normal/talk-only mode setting screen, the output interval setting screen will be displayed on display D.

Press the \wedge , \vee , < or > key to set the desired interval (in units of hour, minute and second), then press the **ENTER** key.

Description

Setting the Mode

For details, refer to page 14-7.

Handshaking

To use an RS-232-C interface to transfer data between this instrument and a computer, it is necessary to use certain procedures by mutual agreement to ensure the proper transfer of data. These procedures are called "handshaking." Various handshaking systems are available depending on the computer to be used; the same handshaking system must be used for both computer and this instrument.

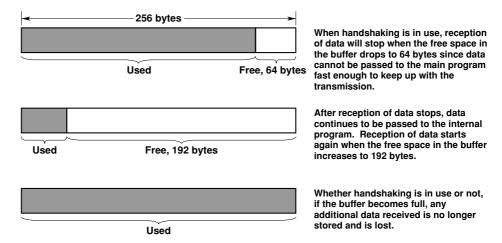
This instrument allows you to choose any handshaking mode from the following four using the panel keys.

	Data sending control			Data receiving control		
	(Control method when sending data to computer)			(Control method when receiving data from computer)		
Mode	Software handshake	Hardware handshake		Software handshake	Hardware handshake	
e selection no.	Sending stops when X-off is received, and sending is resumed when X-on is received.	Sending stops when CB (CTS) is False, and sending is resumed when CB is True.	No handshake	X-off is sent when received data buffer becomes 3/4- full, and X-on is sent when received data buffer becomes 1/4-full.	CA (RTS) is set to False when received data buffer becomes 3/4-full, and is set to True when received data buffer becomes 1/4-full.	No handshake
0			0			0
1	0			0		
2	0				0	
3		0			0	

Handshaking System Combinations (A circle indicates that the function is available.)

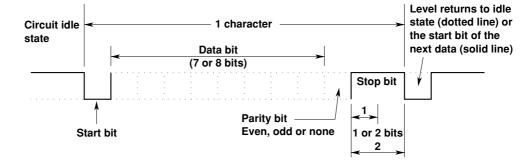
Precautions Regarding Data Receiving Control

When handshaking is used to control received data, data may still be sent from the computer even if the free space in the receive buffer drops below 64 bytes. In this case, after the receive buffer becomes full, the excess data will be lost, whether handshaking is in use or not. Data storage to the buffer will begin again when there is free space in the buffer.



Data Format

The RS-232-C interface of this instrument performs communications using start-stop synchronization. In start-stop synchronization, one character is transmitted at a time. Each character consists of a start bit, data bits, a parity bit, and a stop bit. (Refer to the figure below.)



Data combinations are given below.

Preset value	Start bit	Data length	Parity	Stop bit
0	1	8	No	1
1	1	7	Odd	1
2	1	7	Even	1
3	1	7	No	2

Baud Rate

The baud rate can be selected from 75, 150, 300, 600, 1200, 2400, 4800 or 9600.

Setting the Output Interval

If talk-only mode is selected, it is necessary to set the intervals at which data is to be output. Setting range : 00.00.00 (0 h 0 min 0 s) to 99.59.59 (99 h 59 min 59 s) Default setting : 00.00.00

If the output interval is set to 00.00.00, data will be output at every sample rate.

Terminator

"CR+LF" or "LF" can be used as the terminator. The receiving terminator can be selected from "CR+LF", "LF" or "CR".

Using an IEEE488.2-1987 Command

Select "4BB2" in the mode setting screen. For a description of each command, refer to Appendix 2.

Commands

The interface message function of the GP-IB interface is assigned to the following commands at the RS-232-C interface.

<ESC>S

Equivalent to GP-IB's serial poll function. Status byte is output when the S command is received following reception of the <ESC> code (1BH).

<ESC>R

Equivalent to GP-IB's remote/local control function. The instrument is placed in remote status and panel keys become invalid when the R command is received following reception of the <ESC> code (1BH). Press the LOCAL key to exit from the remote status.

<ESC>L

Equivalent to GP-IB's remote/local control function. When the instrument is in remote status, the instrument will be placed in local status when the L command is received following reception of the <ESC> code (1BH).

<ESC>C

Equivalent to GP-IB's device clear function. The communication devices of this instrument are initialized when the C command is received following reception of the <ESC> code (1BH).

Note .

• Error code 390 may be displayed depending on the state of the instrument. In this case, decrease the baud rate.

15.1 Calibration and Corrective Actions in Cases where Hardware Fails

Calibration

To maintain high measurement accuracy, the instrument should be calibrated every three months. We recommend that calibration of the instrument is not carried out by your power meter calibration facility. Calibration should always be carried out by YOKOGAWA. For details, contact YOKOGAWA or your YOKOGAWA sales representative.

Apparent Hardware Failure - Check these Things First!

If the instrument does not operate properly even if the actions given in the table below are performed, contact YOKOGAWA or your YOKOGAWA sales representative. When contacting them, tell them the ROM version no. displayed on display B on power-up.

Symptom	What to Check	Reference Pages
Nothing is displayed when the power is turned ON.	 Is the power cord securely connected to the power connector of the instrument and the AC outlet? Is the power voltage within the allowed range? Has the fuse blown?	2-4,2-5
Displayed data is odd.	 Are the ambient temperature and humidity within the allowed range? Is there noise? Are measurement leads connected correctly? Is the line filter off? 	2-2,3-1, 3-2,4-1
Keys do not function.	 Is the KEY LOCK indicator LED off? Is the REMOTE indicator LED off?	1-5,13-3, 14-5
Instrument cannot be controlled via GP-IB interface.	 Does the GP-IB address specified in the program match the address set up in the instrument? Does the interface meet the IEEE Standard 488-1978 electrical and mechanical requirements? 	14-4,14-6
Instrument cannot be controlled via RS-232-C interface.	• Are the instrument and controller using the same communications settings?	14-7,14-8

15.2 Error Codes and Corrective Actions

Error Codes for Operation and Measurement

Error Code	Description	Corrective Action	Reference Pages
11	Received command not used by the instrument	Check for error in the command sent.	Appendix
12	Parameter value specified is outside allowed range.	Correct the value.	_
13	Attempt made to execute a key operation or received a communications command, while integration was running or was interrupted, that cannot be executed or received in such a state.	Check whether integration is in progress or is interrupted.	8-13, Appendix
14	Attempt made to switch to auto range mode while the external shunt range is selected.		
15	Attempt made to execute a command or key operation that was protected.	Check whether the command or key operation is correct.	Appendix
16	Attempt made to execute a key operation or received a communications command, while harmonic analysis was being performed or was interrupted, that can not be executed or received in such state.	Check whether harmonic analysis is in progress.	_
17	Stop time had passed when auto print mode is turned ON.	Correct the stop time. The stop time must be after the current time.	11-8
18	Date/time cannot be set properly.		_
20	Attempt made to execute a key operation or a communications command while flicker measurement is in progress, that cannot be executed in such a state.		10-17
21	Attempted to start fluctuation measurement while initialization prior to fluctuation measurement is performed (i.e. while "init" is displayed on display B).	Start fluctuation measurement after confirm the initialization is finished (i.e. display on display B goes out).	10-3
22	Attempted to start flicker measurement while flicker measurement is already in progress.		10-3
23	There is no flicker output data to be printed.		_
24	Attempted to stop flicker measurement even though flicker measurement was not in progress.		10-3
25	Attempted to switch to measurement of nominal voltage (initial state) while flicker measurement is in progress.		10-3
26	Attempted to return to normal measurement while measurement of nominal voltage (initial state) is not in progress.		10-3
30	No data stored in the selected set-up information file.	Select a file in which set-up information has been stored.	13-1
41	 Attempt made to start integration while there is an overflow condition. Attempt made to start integration after integration time has reached timer preset value. 	Reset integration.	8-11
42	Attempt made to start integration while integration is in progress.		8-10
43	Measurement stopped due to overflow during integration or due to a power failure.		8-11
44	Attempt made to stop integration even though integration was not in progress.		8-11
45	Attempt made to reset integration even though integration was not in progress or integration mode was not selected.		8-11
46	Attempt made to start integration while measurement of peak overflow was in progress or during an overrange condition.		8-10
47	Attempt made to start integration in continuous integration mode when integration timer preset time was set to "0".	Set a correct preset time.	8-8, 8-9
48	Attempt made to start integration in real time counting integration mode when the stop time had already passed.	Set a correct start/stop time.	8-9
51	Measurement data overflow occurred. "- \Box L -" is displayed.		1-4
52	Voltage peak overflow occurred. PEAK OVER indicator LED lights up.		1-4
53	Current peak overflow occurred. PEAK OVER indicator LED lights up.		1-4
54	Power factor exceeded "2" during measurement of power factor.		_
55	" $P \not\models \not\models \neg \neg$ " was displayed at the end of power factor computation during measurement of phase angle.		1-4, 5-6
56	Input level was too low or below measurement range during measurement of frequency. " $\mathcal{E} r r - \mathcal{L} \sigma$ " is displayed.		6-1
57	Measured frequency was above the measurement range. " $E H$, " is displayed.		6-1
58	Computation overflow occurred. " $\Box F$ " is displayed.		1-4, 7-8
89	Printer's buffer memory was full.	Make sure that the roll chart is set in place.	11-1

Error Codes Regarding Self Diagnosis

Error Code	Description	Corrective Action
60	Set-up information backup data failure (Set-up information	is set to factory default.)
61	EPROM (input element 1) failure	Service required.
64	EPROM (D/A board) failure	Service required
65	Sampling clock (input element 1) failure	Service required
69	Lithium battery voltage drop	Service required
70	Communications interface board not installed.	Service required
71, 72	DSP communications failure	Service required
73	Printer communications failure	Service required
74	Printer communications failure (ROM failure)	Service required
75	DSP program RAM failure	Service required
79	ROM checksum error	Service required
80	RAM read/write check error	Service required
81	DSP data RAM failure	Service required
84	DSP dual port RAM failure	Service required
87	Printer RAM failure	Service required
90	Incorrect board combination	Service required

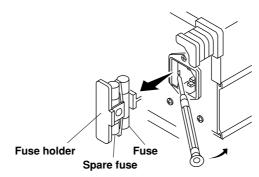
Note -

If the instrument still does not operate properly even if the actions given above are performed, or if a self
diagnostic error code is displayed, turn the power ON while holding down the *ENTER* key. In this case, the setup information will be set to the default settings (page 2-6.)

15.3 Replacing the Power Supply Fuse

Fuse Position and Replacement Method

The power supply fuse is installed inside the fuse holder located next to the power connector as illustrated below



Fuse Ratings

Max. rated voltage	Max. rated current	Туре	Approved standard	Part No.
250 V	5 A	Time lag	UL/VDE	A1353EF

- The fuse used must be of the specified rating in order to prevent a fire hazard. Never use a fuse of any other rating, and never short-circuit the fuse holder to bypass the fuse.
- Do not operate the instrument if you have any reason to suspect any defect or problem with the fuse.

Not	te					
•	nearest YOKOGAW	A representative listed	ed by the user. If you b d on the back cover of uments produced after ur nearest YOKOGAW.	this manua the middle	al. The ratings of the f of October 1997, how	uses used ever, don't
	Location	Max rated voltage	Max. rated current	Type	Approved standard	Part No
	Voltage input board	5	100 mA	Time lag	UL/VDE	A1341EF
	voltage input board	250 V	TUUTIIA	Time lag	UL/VDE	A1341EF

Replacing the Fuse

- 1. Turn the power switch OFF.
- 2. Disconnect the power cord from the power connector of the instrument.
- 3. Place the tip of a flat-blade screwdriver into the slot of the fuse holder, and move the screwdriver in the direction of the arrow to remove the fuse holder.
- 4. Remove the blown fuse.
- 5. Insert a new fuse into the holder, then install the holder in place.

15.4 Recommended Parts for Replacement

The 3-year warranty applies only to the main unit of this instrument (starting from the day of delivery) and doesn't cover any other items nor expendable items (items which wear out). In order to use the instrument over a prolonged period of time, we recommend periodic replacement. Contact your nearest Yokogawa sales representative for replacement parts. Addresses may be found on the back cover of this manual.

Parts mane	Replacement interval
Built-in printer	after printing 200 rolls (parts No. B9293UA) continuously

16.1 Specifications

Input

Item	Voltage V	Current A	
Input circuit type	Floating input		
	Resistive voltage divider	Shunt input	
Rated inputs (range rms)	10/15/30/60/100/150/ 300/600V Direct input 1/2/5/10/20/30 A External shunt input: 50 m/100 m/200 mV		
Input impedance	Input resistance Approx. 2 MΩ Input capacitance Approx. 15 pF	Direct input: Approx. 6 m Ω + approx. 0.07 μ H External shunt input: Approx. 100 k Ω `	
Frequency range	DC and 2 H	z to 500 kHz	
Instantaneous maximum allowable input for 1s	The peak voltage is 2500 V, or the RMS value is 3 times the range, whichever is less.	The peak current is 90 A, or the RMS value is 50 A, whichever is less. External input: The peak value is 20 times the range or less.	
Continuous maximum allowable input	The peak voltage is 1400 V, or the RMS value is 2.5 times the range, whichever is less.		
Continuous max. common mode voltage (at 50/60 Hz)			
Common mode rejection ratio at 600 Vrms between	Voltage input terminals shorted, current input terminals opened: Better than -80 dB (±0.01% of rdg or less)		
input terminals and case (50/60 Hz input)	Reference value: 200 kHz max ±((0.18 x f)/(range rating))% of rdg or less (Unit of f: kHz)	Reference value: 200 kHz max ±((0.03 x f)/(range rating))% of rdg or less (Unit of f: kHz)	
Input terminals	Binding posts	Large binding posts External shunt input: BNC	
A/D converter	Simultaneous conversior Resolution: 16 bits Maximum conversion rat	n of voltage and current inputs e: 104 kHz	
Overload input detection	Alarm lamp lights at appr (approx. 700% of range v	ox. 350% of the input range when crest factor is 6)	
Range switching	The range can be switched manually, automatically, or by communication control.		
Auto range switching	Range up: When the measured value exceeds 110% of the rated value, or when the peak value exceeds 350% of the peak value Range down: When the measured value becomes less than 30% of the rated value		
Measurement mode switching	The mode can be set and current measurement cire	d also for each voltage and cuit.	

Display Functions

=				
Display: Display contents	7-segment LED (light emitting diode) 5: 4 displays			
Display	Display contents	Display resolution		
A	V, A, W	V, A, W: 50000		
В	V, A, W	Wh, Ah: 500000		
С	V, A, W, VA, var, PF, deg, Vpk	Hz: 199999		
D	B 1,7, 1,7,9, 1,7,1 B , 11 E , 11 E , 11 E			
	Wh, Ah, η (MATH)			
* In case of equ	ipped with harmonic analysis function			
Display update	A, W, VA, var, pk, Hz, h, deg, % rate:Select from 0.25 sec, 0.5 sec and 2.0 sec. on;:Selectable to hold item as follows Vpk and Apk can be held at maximum value Measurement value of V, A, W, VA, var, Vpk, Ap maximum value.			
Response time:	Maximum of twice the display update rate (The time taken for the display to fall within t final value when the filter is OFF and an abri from 0 to 100% of the range, or from 100% t	upt change is made		
Display scaling				
(Significant dig	jits: Selected automatically according to the sign voltage and current range.	ificant digits in the		
Setting range: Set values:				
Display averaç Method:	 One of the following two types can be select Exponential averaging Moving averaging For exponential averaging, the attenuation Constant can be selected, and for moving av average number, N, can be set to 8, 16, 32, For harmonic mark measurements For exponential avaraging the attenuator Constant is 5.625 when the frequency of the 55 Hz or more but less than 66 Hz, and is 4. (when the data length = 8192). 	veraging, the 64, 128 or 256. PLL sync source is		
MATH function When the DISPLAY D function is made η (efficiency), you measure the input crest factor and also select the function displays the results of performing arithmetic calculations (+ on the measurement results of DISPLAY A and B.				

Accuracy

Item		Voltage/current	Power	
Conditions Humidity 30 to 75% RH Supply voltage Specified V ±5% Input waveform	Temperature $23 \pm 3^{\circ}C$ except 600V, 100/20A/ 30A rang	$45Hz \le f \le 66Hz \pm (0.03\% of rdg+0.03\% of rng)$	$\begin{array}{l} 45\text{Hz} \leq f \leq 66\text{Hz} \\ \pm (0.04\%\text{of rdg+0.04\%\text{of}} \\ \text{rng}) \end{array}$	
Sine wave In-phase voltage 0 V Power factor Cos $\phi = 1$ Line filter OFF Crest factor 3 Scaling OFF 6-month accuracy The unit of f in the accuracy formula is kHz	Tempera- ture 23 ± 5°C	$\begin{array}{l} \label{eq:2.1} \text{DC:} \\ \pm (0.04\% of rdg+0.08\% of rdg) \\ \text{2Hz} \leq f < 30 \text{Hz} \\ \pm (0.1\% of rdg+0.2\% of rdg) \\ 30 \text{Hz} \leq f \leq 10 \text{Hz} \\ \pm (0.03\% of rdg+0.05\% of rdg) \\ 1 \text{kHz} < f \leq 10 \text{kHz} \\ \pm (0.02\% of rdg+0.05\% of rdg) \\ 10 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.018 \ X (t-10)\% of rdg) \\ 10 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.018 \ X (t-10)\% of rdg) \\ 10 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.018 \ X (t-10)\% of rdg) \\ 10 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.03\% of rdg) \\ 20 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.03 \ X (t-10)\% of rdg+1.0\% of rdg) \\ 10 \text{kHz} < f \leq 50 \text{kHz} \\ \pm (0.33 \ X (t-50)\% of rdg) \\ 2 \text{Hz} \leq f < 10 \text{Hz} \text{ and} \\ more than 200 \text{ kHz} \text{ is the} \\ design value. \\ 10 \text{ the display update rate is} \\ 10 \text{ Hz} or more -> \text{ MID} \\ 10 \text{ the display update is 2} \\ \text{Hz} or more -> \text{SLOW} \\ \end{array}$	$\begin{array}{l} \text{DC:} \\ \pm (0.08\% \text{ f dg}+0.12\% \text{ f mg}) \\ \pm 2\text{Hz} \leq f < 30\text{Hz} \\ \pm (0.2\% \text{ of rdg}+0.5\% \text{ of mg}) \\ 30\text{Hz} \leq f \leq 1\text{ kHz} \\ \pm (0.05\% \text{ of rdg}+0.05\% \text{ of mg}) \\ 1\text{kHz} < f \leq 10\text{ kHz} \\ \pm (0.05\% \text{ of rdg}+0.25\% \text{ of rmg}) \\ 10\text{kHz} < f \leq 50\text{ kHz} \\ \pm (0.05\% \text{ of rdg}+0.25\% \text{ of rmg}) \\ 10\text{kHz} < f \leq 10\text{ kHz} \\ \pm (0.04\% \text{ of rmg}) \\ 50\text{ kHz} < f \leq 100\text{ kHz} \\ \pm (0.05\% \text{ of rmg}) \\ 100\text{ kHz} < f \leq 100\text{ kHz} \\ \pm (0.11 (f-100)\% \text{ of rmg}) \\ 2\text{ Hz} \leq f < 10\text{ Hz} \text{ and more} \\ \text{th a constraint} \\ 10\text{ th a constraint} \\ 10\text{ Hz} \text{ or more} > \text{ MID} \\ 1\text{ the display update rate is} \\ 10\text{ Hz} \text{ or more} > \text{SLOW} \\ \end{array}$	
Effect of power factor The ϕ is the phase angle between the voltage and current, and the f is the frequency.		-	When $\cos\phi = 0$: add ±0.1% of mg to 45Hz \leq 1 \leq 66Hz, add ±0.15% of mg to 66 Hz < 1 \leq 440Hz. As reference data, add ±(0.15 + 0.15 X f kHz)% of mg, up to 300kHz max. When 1 > cos ϕ > 0: add the product of tan ϕ and the effect on $\cos\phi = 0$.	
Effective input rar	nge	Between 10 and 110% of the rated input value (The accuracy when the input is between 110 and 130% is 1.5 times the read value error.)		
Accuracy of crest	factor of 6	1.5 times the range error of a crest factor of 3 (accuracy when the above temperature is $23 \pm 5^{\circ}$ C)		
Temperature coe	fficient	\pm 0.02% of rag/°C between 5 and 18°C and between 28 and 40°C		
Data update rate		0.25s, 0.5s, 2.0s		
Line filter function		Measurement can be performed with low pass filte inserted into the input circuit and the frequency measurement circuit. A cutoff frequency (fc) can be selected from 500 H and 5.5 kHz.		
Accuracy when the line filter is ON		For fc/10 or less: Add ±1% of rng to the accuracy when the filter is OFF.	For fc/10 or less: Add ±2% of rng to the accuracy when the filter is OFF.	
One year's accuracy		Read value error (6 months' accuracy) + Range erro (6 months' accuracy) x 1.5 Calibration period is one year.		
Detection accurate leading phase/lag		±5 deg (20 Hz to 10 kHz) for sinusoidal voltage and current inputs, crest factor of 3, and at least 50% of range rating		
Measurement lower limit frequency		Display update rate; Measurement lower limit frequency 250 ms 20 Hz or higher 500 ms 10 Hz or higher 2 sec 2 Hz or higher		

Frequency Measurement Function

Measurement input: V1, A1	
Magazina manter at had. Designed and the stand	

Measurement method: Reciprocal method Measurement frequency range:

lency range	
Depends ι	pon the display update rate as shown below (auto
range).	
250ms:	2 k/20 k/200 k/1000 kHz
500ms:	200/2 k/20 k/200 k/500 kHz
25:	20/200/2 k/20 k/100 kHz
199999	
250ms:	18.00 Hz
500ms:	9.000 Hz
25:	18000 Hz
±0.05% of	rdg
 When the rating 	voltage and current are both at least 30% of the range
	e crest factor is 3 and the frequency is at least 20% of num frequency range
	Iz or less, when the filter is ON
	Depends L range). 250ms: 250ms: 25: 199999 250ms: 25: ±0.05% of • When the rating • When the the minim

1 Specifications

Computing Functions

	Active Power (W)	Apparent power (VA)	Reactive power (var)	Power factor (PF)	Phase angle (deg)
Calculation formula	w	$VA = V \times A$	$\sqrt{(VA)^2 - W^2}$	W VA	$\cos^{-1}(\frac{W}{VA})$
Calculation range	The rated value depends upon the V and A ranges.	The rated value depends upon the V and A ranges.	Same as the apparent power (var > 0)	-1-0-1	LEAD 180 - 0 LAG 180 or 0 - 360
Maximum displayor display resolution	50000	50000	50000	±1.0000	0.01
Calculation accuracy (with respect to the calculation value from the measurement value)		±0.001% of the rated value (VA)	±0.001% of the rated value (VA)	±0.0001	±0.005° with respect to the calculation from the power factor

Note 1: The apparent power (VA), reactive power (var), power factor (PF), and phase angle (deg) measurement in this instrument are computed digitally from the voltage, current and active power. If the input is non-sinusoidal, the measured values may differ from those obtained with instruments employing different measurement principles.
 Note 2: When the Current or Voltage value is less than 0.3% of range, the VA and var will be displayed 0, and PF/deg will be displayed as Error.
 Note 3: Regarding the detected accuracy of the Lead and Lag,both voltage and current of the rated input are specified at 50% or more for sinusoidal waveforms set at crest factor 3.

the fated input are specified at 50% of more for sinusoidal waveforms set at crest factor 3.
 The detected Lead/Lag accuracy is ±5 degree over the frequency range 20 Hz to 10 kHz.
 Note 4: When the phase angle display shows an angle smaller than 5 degree at 0° and 180°, the accuracy is not specified.

Integration Functions

Maximum display:	500000			
	According to the displayed value, the resolution will be changed.			
Frequency range:	DC to 50 kHz			
Modes:	Standard Integration Mode (timer mode)			
	Continuous Integration Mode (repeat mode)			
	Manual Integration Mode			
Timer:	When the timer is set, Integration will be stopped automatically.			
	Setting range : 000 h: 00min to 999 h: 59 min (000 h: 00min will be shown when			
	manual integration mode is selected.)			
Display:	Display A shows : Elapsed time			
-1	Display B/C shows : Watt			
	Display D shows : Watt, Wh, Ah, Hz			
Output:	For the output of the printer, communication and D/A, fourteen free selectable items from the above can be set. However, only the measured data of the frequency which has been previously set will be output.			
Count Overflow:	If integration count overflows the maximum displayable value, integration stops and the elapsed time is held on the display.			
Real Time Counting:	The integration time can be controlled REAL TIME.			
Accuracy:	±(display accuracy + 0.05% of rdg)			
Timer accuracy:	±0.005%			
Remote Control:	Start, stop and reset can be remotely controlled by external contact signals.			

Communication Functions

Communication Specifications (GP-IB & RS-232-C) GP-IB

	Electrical and mechanical specifications: EEE Std 488-1978 (JIS C 1901-1987) Functional specifications: SH1, AH1, T5, L4, SR1, PR0, DC1, DT1, C0				
	Protocol:	IEEE St'd 488.2-1987			
	Code used: ISO (ASCII) code				
	Address: set.	0 to 30 talker/listener addresses can be			
RS-232-C					
Transmission mode: Baud Rate:	Start Stop Synchronization 75, 150, 300, 600, 1200, 2400, 4800, 9600 bps				

External Control

Signal:	EXT-HOLD, EXT-TRIG, EXT-PRINT, EXT-START, EXT- STOP, EXT-RESET, INTEG-BUSY, FLICKER-BUSY					
Input:	TTL level negative pulses					
Printer (optional)						
· ·	ting For normal measurement:					
Contents of print	Printing of numerical values - All items					
	(Can be set freely, however is set in common with the communication output.)					
E a la la suma a la la sum	a busine for an attended to a strain a st					

For narmonic analysis function (optional).			
	Printing of numerical values - V, A, W, VA, var, PF, deg		
	Bar graphs - V, A, W, deg		
For flicker measurement f	unction (optional):		
	At end of 1 observation period - dc, dmax, d(t) 200 ms, Pst and evaluation criteria, evaluation results and total accuracy function (CPF) graph for each parameter At end of all observation periods - Plt, Overall evaluation		
Printing method:	Thermal line dot printing		

D/A Output (optional)

14 items (can be set for each channel)
12 bits
±(display accuracy + 0.2% of rng)
±5 V FS with respect to each rated value (max. approx. ±7.5 V)
± 1 mA
±0.05% of rng/°C
Same as update rate of main unit

Harmonic analysis function (optional)

			(-1				
Type: PLL sync method Measurement frequency: The fundamental frequency rang Display resolution: 50000				ge is 10	Hz to 4	40 Hz.	
		atata an	ما السمة سم				
Harmonics to be m Analysis items:		-state and armonic I					voltago
Analysis items.		urrent, ac					
							rtion, each
		ic conter					
							onic and the
		ental wa					
Sampling rate/w	indow width/analy	sis order	:				
	Depend	is on the	input fre	equency	as follo	ws whe	en the PLL
	sync me	ethod is ı	used.				
	Compliant	Windo	w widt	h with r	enect		
Fundamental	Sampling frequency		ength (r				Maximum
frequency	[Hz]	8192	4096	2048	1024	512	analysis order
10≦f<20	f×2048	4	4096	2048	1024	- 512	
		-			-		50(50)
20≦f<40 40≦f<70	f×1024 f×512	8	4	2	1	- 1	50(50)
			-				50(50)
70≦f<130	f×256	32	16	8	4	2	50(25)
130≦f<250	f×128	64	32	16	8	4	50(13)
250≦f≦440	f×64	128	64	32	16	8	25(9)
$\begin{array}{llllllllllllllllllllllllllllllllllll$				n the line angle $\leq f < 40 Hz$ $\leq f \leq 2.5 kHz$ $< f \leq 3.5 kHz$ specificatior			
 is satisfied when the instrument is operated in 23±5°C.) The above accuracy is stipulated when the input for each analysis order is no more than 110% of the rated value. If the input range exceeds 110%, add range error x 2. When the crest factor is 6, add range error x 1 to the above crest factor = 3 accuracy. The input range is the range in which the "peak overloa display LED" does not light. (within about ±350% of the measurement range) However, it must be within the maximum allowable inpur range. 							

range.
When the data length = 1024 or the fundamental frequency is less than 40 Hz, add range error x 3.

Flicker measurement (optional)

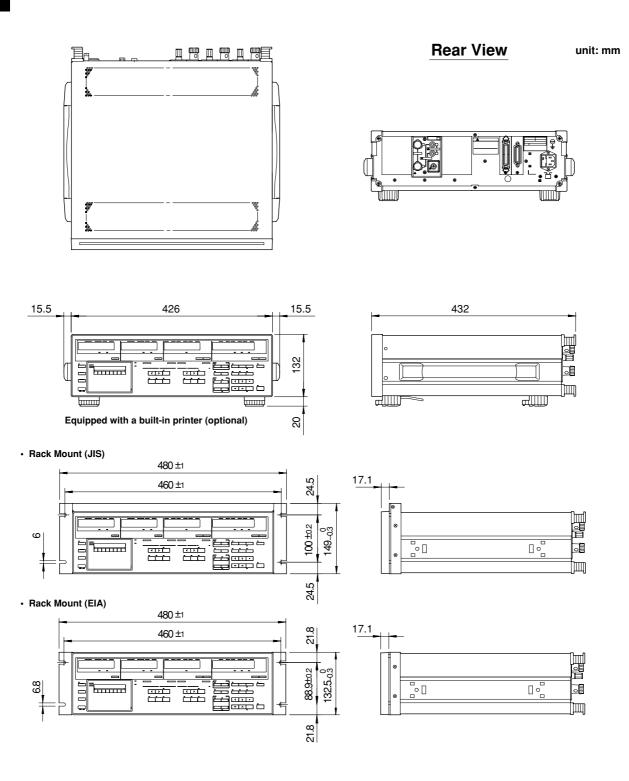
	· · · · ·
Measurement items:	dc Relative steady-state voltage change dmax Maximum relative voltage change d(t) _{20me} Term within the voltage change during which the threshold level is exceeded Regarding the above items, the maximum value is displayed within 1 observation term Pst Short-term flicker indicator Ptl Long-term flicker indicator
Flicker scale:	0.01 to 6400 PU (20%) is divided logarithmically into 1024
There searce.	parts.
1 observation term:	30 seconds to 15 minutes
	Number of observation term: 1 to 99
Display update:	2 seconds (dc, dmax, d(t) _{200 ms})
	At the end of each observation (Pst)
Steady-state condition:	The relative voltage change can be set between 0.10 and 9.99% (0.01% steps).
Printer output:	See the printer item.
Accuracy:	Half-wave RMS value: $\pm 0.1\%$ of rdg $\pm 0.1\%$ of rng (45 Hz \leq f \leq 66 Hz)
dc, dmax, d(t) _{200 ms} :	In accordance with IEC1000-3-3.
Pst, Plt:	$\pm 5\%$ when Pst = 1
	The above accuracy applies to the following conditions. • After warm-up of at least 2 hours.
	 Subsequent ambient temperature change is no more than ±1°C.
	• The input voltage is 50% to 110% of the range rating.

General specifications

Working temperature range: Storage temperature:				
Working humidity range:	20 to 80% RH (no condensation)			
Operating altitude	2010 80% 2000 m or			
	Approx. 30			
Warmup time:				
Insulation resistance:		MW at 500 V DC		
		each input terminal and case, I		
		nal, between each input termi	nal and power	
		een case and power plug)		
Withstand voltage:		50/60 Hz for one minute		
	(between each input terminal, between each input terminal			
	and power			
		50/60 Hz for one minute		
		each input terminal and case)		
		50/60 Hz for one minute		
	(between c	ase and power plug)		
Power supply:	Setting	Alloweble Voltage range	Frequency	
	100 V	90 to 110 V	48 to 63 Hz	
	115 V	100 to 132 V	48 to 63 Hz	
	200 V	180 to 220 V	48 to 63 Hz	
	230 V	198 to 284 V	48 to 63 Hz	
Power consumption:	120 VA ma	IX.		
Accuracy of internal clock:		seconds in one month		
Vibration conditions:	Sweep tes	t 2-way sweep from 8 to 150	Hz in all 3	
		or 1 minute each		
		est Frequency 16.7 Hz, ampl	itude of 4 mm in	
		ons for 2 hours each		
Impact conditions:		Acceleration 490 m/s ² , in all	3 directions	
impact contaitioner		est Free-fall test Height 100		
	each of 4 s		, 0.100 0.1	
External dimensions:		6 (W) x 132 (H) x 400 (D) mm	1	
Weight:	Approx. 11			
Accessories:	Power cord: UL/CSA, VDE, SAA or BS standard x 1 pcs.			
Fuse:	2 pcs, including a spare one			
Remote control connector:	A1005JD x			
		B9384LK One for each elem	ont	
External shunt input com				
	rubber of b	er (when /B5 is added): B929	30A 2 10115)	
Emission [*]				
E111551011		Standard:EN55011-Group1, 0		
		lass A product for industrial er		
		nvironment, this product may		
		e in which cause the user may	vue required to	
		iate measures.		
	Cable Con			
	Measuring			
		e the wires between source a		
		nd to separate the input signal		
		nm between each phase and r	neutral line.	
	External In			
	To use s	hielded wires		
Immunity		Standard:EN50082-2:1995		
		ity Under Immunity Condition		
		ng Input : ±10% of range max		
	DA Outp	ut : ±40% of range max		
	Testing (Condition		
		e : rage 100V Input, 100V/50	Hz	
		t : range 1A Input, 1A/50Hz		
Safety standard*		Standard : EN61010		
		age Category II		
		degree 2		
* Applies to products ma		fter Jan. 1997 having the CE	Mark. For all	
		nearest YOKOGAWA represe		
on the back cover of th		incursor i oncourter represe		

on the back cover of this manual.





Unless otherwise specified, tolerance is $\pm 3\%$. (However, tolerance is ± 0.3 mm when below 10 mm.)

Appendix 1.1 List of Communications Commands

	Command	Action
Wiring system	WR m (WiRing)	Sets wiring system.
Voltage range	RV m1,m2 (Range Voltage)	Sets voltage range.
	AV m1,m2 (Auto Voltage range)	Sets voltage auto range.
Current range	RA m1,m2 (Range current(A))	Sets current range.
	AA m1,m2 (Auto current(A) range)	Sets current auto range.
	SA m1,m2 (Shunt Ampere)	Sets external shunt current value.
Measurement mode	MV m1,m2 (rms/Mean/dc Voltage)	Sets RMS/MEAN/DC mode for voltage measurement.
	MA m1,m2 (rms/Mean/dc current(A))	Sets RMS/MEAN/DC mode for current measurement.
Peak hold	KH m (peaK Hold)	Sets peak hold ON or OFF.
	KF m (peaK hold Function)	Sets the peak hold function.
Frequency filter	QF m1,m2 (freQuency Filter)	Sets source for which frequency measurement is
T		to be performed.
Line filter	FL m (Filter)	Sets line filter ON or OFF.
	FC m (FiLter Cut off frequency)	Sets cut-off frequency.
Crest factor	CF m (Crest Factor)	Sets crest factor 3 or 6.
NULL function	NL m (NuLl function)	Sets the NULL function.
Display update interval	SI m (Sampling Interval)	Sets sample rate.
Hold Trigger	HD m (sampling HolD) E or ST or <get></get>	Holds display and output data.
Trigger Display	DA m (Display A function)	Trigger Selects function to be displayed on display A.
Display	DB m (Display B function)	Selects function to be displayed on display A. Selects function to be displayed on display B.
	DC m (Display C function)	Selects function to be displayed on display B. Selects function to be displayed on display C.
	DD m (Display D function)	Selects function to be displayed on display C. Selects function to be displayed on display D.
	EA m (Element display A)	Selects element to be displayed on display D.
	EB m (Element display B)	Selects element to be displayed on display <i>R</i> .
	EC m (Element display C)	Selects element to be displayed on display <i>D</i> .
	ED m (Element display D)	Selects element to be displayed on display C. Selects element to be displayed on display D.
Phase angle display	DG m (DeGree)	Sets phase angle display format.
Scaling	SC m (SCaling)	Sets scaling function ON or OFF.
0	KV m1,m2 (K*Voltage)	Sets scaling constant.
	KA m1,m2 (K*Ampere)	Sets scaling constant.
	KWm1,m2 (K*Wattage)	Sets scaling constant.
Averaging	AG m (AveraGing)	Sets averaging function ON or OFF.
	AT m (Averaging Type)	Selects exponential averaging or moving averaging.
	AC m (Averaging Coefficient)	Sets attenuation constant or averaging number.
MATH	MT m (MaThematics)	Sets computing equation.
Integration	IS (Integrate Start)	Starts integration.
	IP (Integrate stoP)	Stops integration.
	IR (Integrate Reset)	Resets integrated value.
	IC m (Integrate Continuous)	Sets integration mode.
	TM m1,m2 (integrate TiMer)	Sets integration timer preset time.
	IT m1/m2/m3/m4/m5/m6,m7/m8/m9/	/m10/m11/m12
	(Integrate real Time)	Sets integration start time and stop time.
	IL m (Integrate poLarity)	Sets integration polarity.
Other	DT m1,m2,m3 (DaTe)	Sets date.
	TI m1,m2,m3 (TIme)	Sets time.
Set-up information	SL m (panel Setting Load)	Recall set-up information.
	SS m (panel Setting Save)	Store set-up information.
	RC (Reset Command)	Initializes set-up information.
Communications	CM m (Communication coMmand)	Sets command group to be used.
communications	OD (Output Data)	Requests output of measured data.
	OF m1,m2 (Output Function)	Sets output items.
	OF m1,m2 (Output Function) OFD m (Output Function Default)	Sets default output items.
	OFD m (Output Function Default) OS (Output panel Setting)	Requests output of set-up information.
	OE (Output Error code)	Requests output of set-up information. Requests output of error code.
	H m (Header)	Sets header for measured data.
	TO m (Type of Output data)	Sets type of output format.
	DL m (DeLimiter)	Selects output data delimiter.
	IM m (Interrupt Mask)	Sets status byte interrupt cause mask.

For detailed description of each command, refer to the Appendix 1.2.

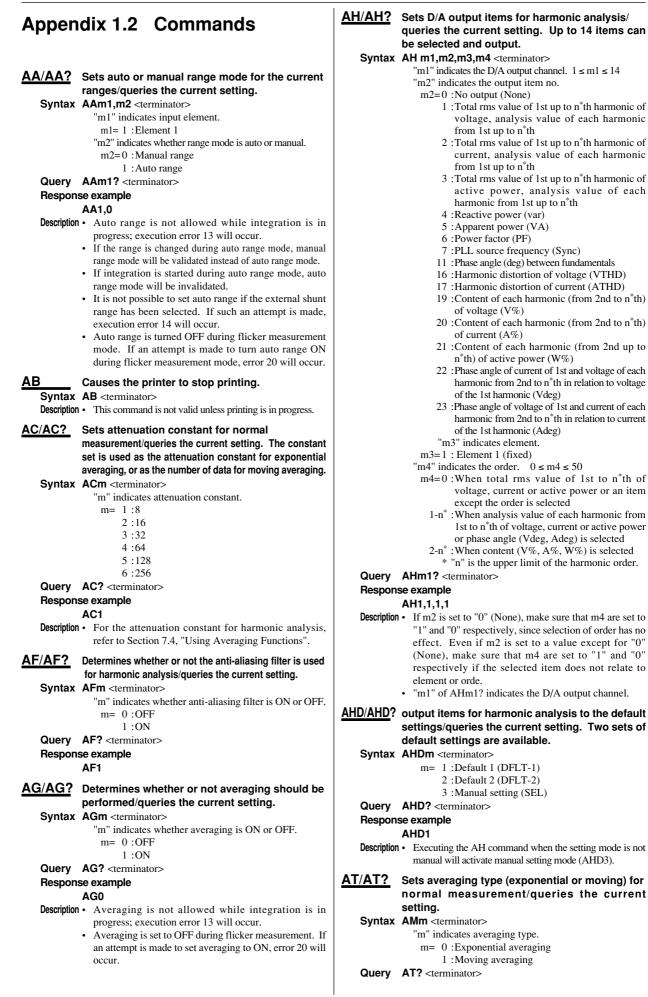
Note .

• If commands relating to options are used on instruments which do not have the options installed, "Error 11" is displayed. Also, there are no responses to inquiries.

• For the ESC commands of the RS-232-C interface, refer to page 14-12.

Optional Commands

	Command	Action
Harmonic analysis	HA m (Harmonics Analize)	Sets harmonic analysis ON or OFF.
	HO m (Harmonics Order)	Sets maximum order.
	PS m (Pll Source)	Sets PLL source.
	AF m (Anti-aliasing Filter)	Sets anti-aliasing filter ON or OFF.
	DH m (Display for Harmonics)	Sets display format for harmonic analysis.
	DF m (Distortion Formula)	Sets distortion equation
	HW m (Harmonics Window width)	Sets the window width for harmonic analysis.
	OR m (harmonics ORder)	Sets order of harmonic to be displayed.
	OH m1,m2	Sets output items for harmonic analysis.
	(Output Harmonic function)	
	OHD m	Sets output items to default settings for
	(Output Harmonics Default)	harmonic analysis.
Printer	PO (Print Out)	Requests print out.
Tinter	FD m (paper FeeD)	Requests paper feed.
		* * *
	AB (print ABort)	Requests print abort.
	PR m (PRinter)	Sets auto print mode ON or OFF.
	PY m (Print sYnchronous mode)	Sets print synchronous method.
	PI m1,m2,m3 (Print Interval)	Sets print interval for auto print.
	PT m1/m2/m3/m4/m5/m6, m7/m8/m9	
	(Print real Time)	Sets auto print START/STOP time.
	PF m1,m2 (Print Function)	Sets print items for normal measurement.
	PFD m (Print Function Default)	Sets print items to default settings for normal measureme
	PH m1,m2 (Print Harmonics)	Sets print items for harmonic analysis.
	PHD m (Print Harmonics Default)	Sets print items to default settings for harmonic analysis
	PK m1,m2 (Print flicKer)	Sets print items for flicker measurement.
	PKD (Print flicKer Default)	Sets print items to default settings for flicker measureme
	PP (Print Panel setting)	Prints out set-up information.
DA		Sets D/A output items for normal measurement.
DA	OA m1,m2,m3 (Output Analog)	*
	OAD m (Output Analog Default)	Sets D/A output items to default settings
	AH m1,m2,m3,m4	for normal measurement.
	(Analog Harmonics)	Sets D/A output items for harmonic analysis.
	AHD m	
	(Analog Harmonics Default)	Sets D/A output items to default settings
		for harmonic analysis.
	RT m1,m2 (integrate Rated Time)	Sets rated time for integration.
Flicker	FK m (FlicKer)	Sets flicker measurement ON or OFF.
	FS (Flicker Start)	Starts measurement of voltage fluctuation.
		e
	FP (Flicker stoP)	Stops measurement of voltage fluctuation.
	FN (Flicker iNitial)	Resets measurement of voltage fluctuation.
	FDA m (Flicker Display A function)	Function to be displayed during flicker measureme
	FEA m (Flicker Element display A)	Element to be displayed during flicker measureme
	FNO m (Flicker period NO.)	Sets the flicker observation period no. for flicker measureme
	UNO m (UN setting mOde)	Sets the acquisition method for nominal voltage U
	UNL m (UN setting voLtage)	Sets the existing value for nominal voltage Un.
	DCO m (DC judging On/off)	Sets judgment ON or OFF for relative steady-state voltage change
	DCL m (DC judging Limit)	Sets the judging limit for relative steady-state voltage change
	DXO m (DmaX judging On/off)	Sets judgment ON or OFF for maximum relative voltage change dn
	DXL m (Dmax judging Limit)	Sets the judging limit for maximum relative voltage change dr
	DTO m (DT judging On/off)	Sets judgment ON or OFF for the period d (t) 200 ms during wh
		voltage exceeds the threshold level within one voltage change.
	DTL m1 m2 (DT indaing Limit)	Sets the judging limit for the period d (t) $_{200 \text{ ms}}$ duri
	DTL m1,m2 (DT judging Limit)	
		which voltage exceeds the threshold level within o
		voltage change.
	PSO m (PSt judging On/off)	Sets judgment ON or OFF for short-term flicker value I
	PSL m (PSt judging Limit)	Sets the judging limit for short-term flicker value I
	PLO m (PLt judging On/off)	Sets judgment ON or OFF for long-term flicker value
	PLL m (PLt judging Limit)	Sets the judging limit for long-term flicker value I
	PLN m (PLt N value)	Sets N value for long-term flicker value Plt.
	FI m1,m2 (Flicker pst Interval)	Sets the time required for each measurement
		short-term flicker value Pst.
	FM m (Flicker Measuring count)	Sets the number of times measurement of short-te flicker value Pst is to be performed.
		THE WALLS IN IN THE DELIGITIED
	DNL m (Dm/Nindaine L' - 10)	
	DNL m (DmiN judging Limit)	Sets the steady-state range dimin.
	FE m (Flicker Element)	Sets the steady-state range dimin. Sets the element for which flicker measurement is to be perform
	FE m (Flicker Element) OJ m (Output Judging data)	Sets the steady-state range dimin. Sets the element for which flicker measurement is to be perform Requests output of flicker judgment result data.
	FE m (Flicker Element)	Sets the steady-state range dimin. Sets the element for which flicker measurement is to be perform Requests output of flicker judgment result data.
	FE m (Flicker Element) OJ m (Output Judging data)	Sets the steady-state range dimin. Sets the element for which flicker measurement is to be perform Requests output of flicker judgment result data. Requests output of CPF (cumulative probability function) da
	FE m (Flicker Element) OJ m (Output Judging data) CPF (output CPF data)	Sets the steady-state range dimin. Sets the element for which flicker measurement is to be perform



Response example

AT0

Description • Exponential averaging is always used as averaging method for harmonic analysis.

AV/AV? Sets auto or manual range mode/queries the current setting.

- Syntax AVm1,m2 <terminator>
 - "m1" indicates input element.
 - m1=1 :Element 1
 - "m2" indicates whether range mode is auto or manual. m2=0 : Manual range
 - m2=0 : Manual rang
- 1 : Auto range Query AVm1? <terminator>

Response example

AV1,0

- **Description** Auto range is not allowed while integration is in progress; execution error 13 will occur.
 - If the range is changed during auto range mode, manual range mode will be validated instead of auto range mode.
 - If integration is started during auto range mode, auto range mode will be invalidated.
 - Auto range is turned OFF during flicker measurement mode. If an attempt is made to turn auto range ON during flicker measurement mode, error 20 will occur.

<u>CF/CF?</u> Sets the crest factor/queries the current setting. Syntax CFm <terminator>

- ntax CFm <terminator>
 - "m" indicates the crest factor.
 - m= 1 :Crest factor 3 6 :Crest factor 6
- Query CF? <terminator>

Response example

CF3

- Description It is not possible change the crest factor while
 - integration is in progress: execution error 13 will occur.
 Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20.

<u>CM/CM</u>? Selects command/output format group/queries the current setting.

Syntax CMn <terminator>

- "m" indicates command/output format group used.
- m= 0:2531 command/output format group (collective setting of scaling constants)
 - 1 :2531 command/output format group (elementby-element setting of scaling constants)
 - 2 :2533E command/output format group
 - 3 :WT2010 command/output format group
- Query CM? <terminator>

Response example

CM3

Description • For the command/output format which differs from that used for this instrument in case CM0, CM1 or CM2 is selected, refer to Appendix 1.5 and 1.6.

CPF Requests communications output of CPF (cumulative probability function) data obtained during the previous observation period.

Syntax CPF m <terminator>

"m" indicates element.

- m= 1 :Element 1
- **Description** This command can be executed only during measurement of voltage fluctuation or display of judgment result. Otherwise, execution error 20 will occur (since there is no data to be output).
 - CPF data will be output in binary format, irrespective of whether the TO command is set for binary or ASCII. For a detailed description, refer to Appendix 1.4 "Data Output Format".

DA/DA? Sets the function for display A/queries the current setting. Syntax DAm <terminator>

"m" indicates one of the following functions.

- m= 1 :Voltage
 - 2 : Current
 - 3 : Power
 - 15 : Elapsed time of integration (INTEG-TIME)

Query DA? <terminator> Response example

DA1

- **Description** Since the order of harmonic is displayed on display A during harmonic analysis, the displayed content will remain unchanged even if a function is selected. This setting becomes effective when normal measurement mode is activated.
 - In the flicker measurement mode, the FDA command is used to set the display function, since only the flicker measurement related content is displayed. Use of the DA command to set the display function is not allowed; error 20 will occur.

DB/DB? Sets the function for display B/queries the current setting.

- Syntax DBm <terminator>
 - "m" indicates one of the following functions.
 - During normal measurement
 - m=1: Voltage(V)
 - 2 : Current (A)
 - 3 : Power (W)During harmonic analysis
 - m= 1: Analysis value (V) or content (V%) of each
 - harmonic of voltage 2 : Analysis value (A) or content (A%) of each harmonic of current
 - 3 : Analysis value (W) or content (W%) of each harmonic of active power

Query DB? <terminator>

Response example

DB2

- **Description** It is determined by the display format for harmonic analysis (selected by DH command) whether analysis value or content of each harmonic of voltage/current/power is displayed during harmonic analysis.
 - This command cannot be used in the flicker measurement mode; error 20 will occur.

DC/DC? Sets the function for display C/queries the current setting.

- Syntax DCm <terminator>
 - "m" indicates one of the following functions.
 - During normal measurement
 - m= 1 :Voltage (V)
 - 2 :Current (A)
 - 3 :Power (W)
 - 4 :Reactive power (var)
 - 5 :Apparent power (VA)
 - 6 :Power factor (PF)
 - 11 :Phase angle (deg)
 - 12 :Voltage peak (V peak)
 - During harmonic analysis
 - m= 1 : Analysis value (V) of each harmonic of voltage
 - 2 :Analysis value (A) of each harmonic of current
 - 3 :Analysis value (W) of each harmonic of active power
 - 4 :Reactive power (var)
 - 5 : Apparent power (VA)
 - 6 :Power factor (PF)
 - 11 : Phase angle (deg) between fundamentals
 - 22 :Phase angle of current of 1st and voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st harmonic (Vdeg)
 - 23 :Phase angle of voltage of 1st and current of each harmonic from 2nd to n*th in relation to current of the 1st harmonic (Adeg)
 - * "n" is the upper limit of the harmonic order.

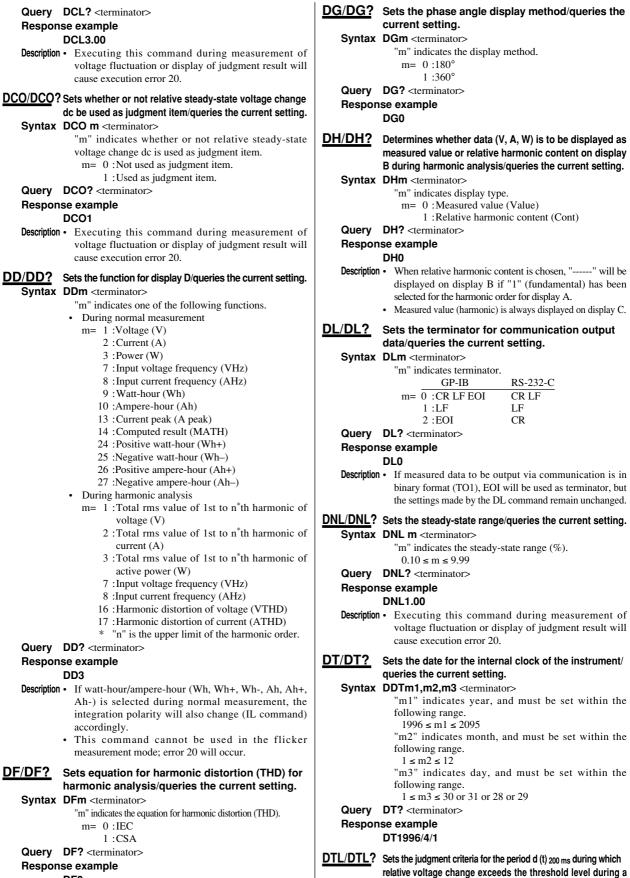
Query DC? <terminator>

Response example DC3

- . .. DC
- **Description** This command cannot be used in the flicker measurement mode; error 20 will occur.

DCL/DCL? Sets the limit for relative steady-state voltage change dc/queries the current setting.

- Syntax DCL m <terminator>
 - "m" indicates the limit (%). 1.00 ≤ m ≤ 99.99



- DF0
- Description For details of equation for harmonic distortion, refer to page 9-11.

Appendix

Appendix 1 Communications Commands 1

voltage change as well as sets the threshold level/queries the

"m1" indicates the judgment criteria (ms) for the total period d (t) (200 ms) during which relative voltage change exceeds the threshold level during a voltage

current setting.

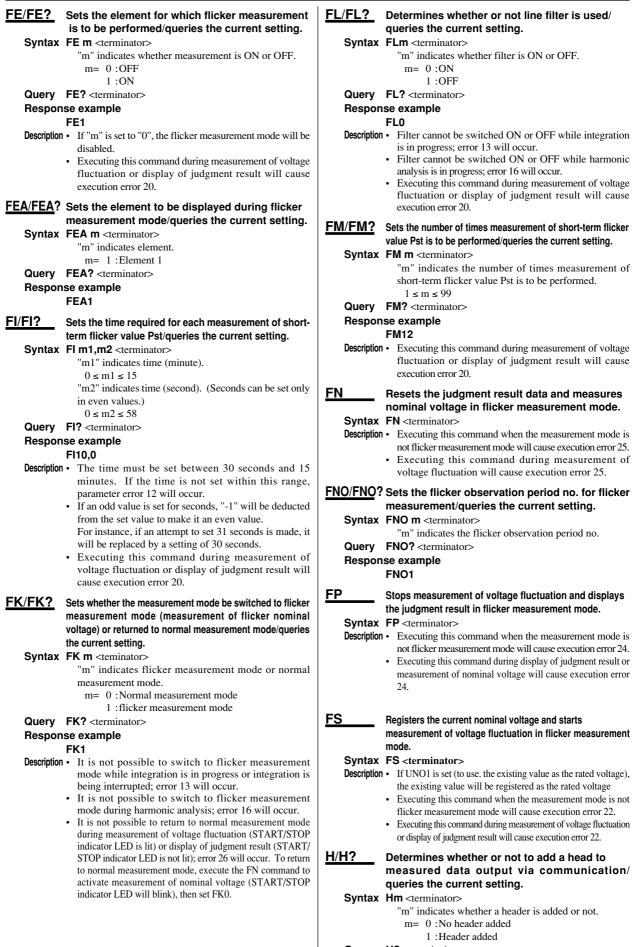
change.

 $1 \leq m1 \leq 99999$

Syntax DTL m1,m2 <terminator>

Appendix 1.2 Commands

"m2" indicates the threshold level (%). 1.00 ≤ m2 ≤ 99.99 Query DTL? <terminator> Response example DTL200,300 Description • Executing this command during measurement of voltage fluctuation or display of judgment result will cause execution error 20. DTO/DTO? Sets whether or not the period d (t) 200 ms during which relative voltage change exceeds the threshold level during a voltage change be used as judgment item/queries the current setting. Syntax DTO m <terminator> "m" indicates whether or not the period is used as judgment item.</terminator></terminator>	EC/EC? Sets the element for display C/queries the current setting. Syntax ECm <terminator> "m" indicates element. m= 1 :Element 1 Query EC? <terminator> Response example EC1 Description • This command cannot be used in the flicker measurement mode; error 20 will occur. ED/ED? Sets the element for display D/queries the current setting. Syntax EDm <terminator> "m" indicates element. m= 1 :Element 1 Query ED? <terminator> "Butter in the flock of the set of th</terminator></terminator></terminator></terminator>
 m= 0 :Not used as judgment item. 1 :Used as judgment item. Query DTO? <terminator></terminator> Response example DTO1 Description • Executing this command during measurement of 	 ED1 Description • If computed result (MATH) is displayed on display D, changing the element for display D is not allowed; execution error 15 will occur. This command cannot be used in the flicker measurement mode; error 20 will occur.
voltage fluctuation or display of judgment result will cause execution error 20. <u>DXL/DXL</u> ? Sets the limit for the maximum relative voltage change dmax/queries the current setting. Syntax DXL m <terminator></terminator>	E,ST, <interface get="" message=""> Generates a trigger. Syntax E <terminator> ST <terminator> <interface get="" message=""> Description • This command is valid only during sample hold mode.</interface></terminator></terminator></interface>
"m" indicates the limit (%). 1.00 ≤ m ≤ 99.99 Query DXL? <terminator> Response example DXL4.00 Description • Executing this command during measurement of</terminator>	FC/FC? Sets the line filter cut-off frequency/queries the current setting. Syntax FCm <terminator> "m" indicates the line filter cut-off frequency (Fc). m= 0 :0.500 kHz</terminator>
voltage fluctuation or display of judgment result will cause execution error 20. <u>DXO/DXO</u> ? Sets whether or not the maximum relative voltage change	1 :5.500 kHz Query FC? <terminator> Response example FC0</terminator>
dmax be used as judgment item/queries the current setting. Syntax DXO m <terminator> "m" indicates whether or not the maximum relative voltage change is used as judgment item. m= 0 :Not used as judgment item. 1 :Used as judgment item. Query DXO? <terminator></terminator></terminator>	 Description • It is not possible set the cut-off frequency during integration: execution error 13 will occur. • It is not possible change the cut-off frequency during harmonic analysis: execution error 16 will occur. • Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20.
Response example DXO1 Description • Executing this command during measurement of voltage fluctuation or display of judgment result will cause execution error 20.	FD Feeds print paper. Syntax FDm <terminator> "m" indicates number of lines to be feed, and must be within the following range. 1 ≤ m ≤ 20</terminator>
EA/EA? Sets the element for display A/queries the current setting. Syntax EAm <terminator> "m" indicates element. m= 1 :Element 1</terminator>	Response example FD1 Description • When paper feed is carried out by pressing the FEED key, one line is fed each time the key is pressed.
Query EA? <terminator> Response example EA1 Description • If elapsed time of integration (INTEG-TIME) is</terminator>	<u>FDA/FDA</u> ? Sets the function to be displayed during flicker measurement mode/queries the current setting. Syntax FDA m <terminator> "m" indicates the function. m=.1. Warmingt values of Up)</terminator>
 displayed on display A, the setting of any element is not allowed; execution error 15 will occur. In the flicker measurement mode, the FEA command is used to set the display element, since only the flicker measurement related content is displayed. Using the EA command to set the display function is not allowed; error 20 will occur. EB/EB? Sets the element for display B/queries the current setting. Syntax EBm <terminator></terminator> 	m= 1 :Nominal voltage (Un) 2 :Relative steady-state voltage change (dc) 3 :Maximum relative voltage change (dmax) 4 :Period d (t) 200 ms during which voltage change is above the threshold level 5 :Short-term flicker value (Pst) 6 :Long-term flicker value (Plt) 7 :Total judgment result (Total) Query FDA? <terminator></terminator>
"m" indicates element. m= 1 :Element 1 Query EB? <terminator> Response example EB1 Description • This command cannot be used in the flicker measurement mode; error 20 will occur.</terminator>	Response example FDA1



Response example

Appendix 1.2 Commands

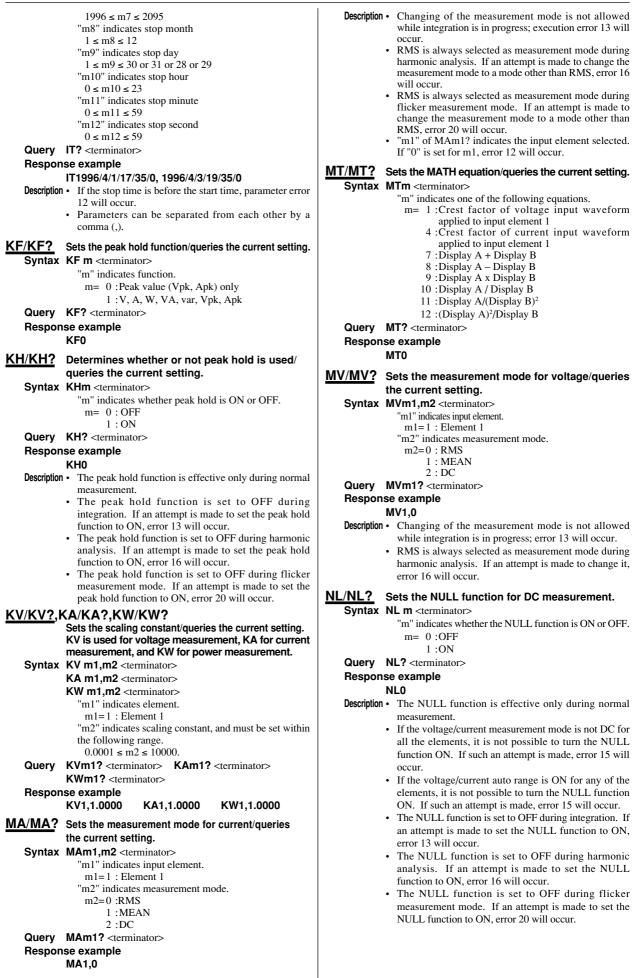
	Description	• If measured data to be output via communication is in binary format (TO1), no header will be added, but the settings made by the H command remain unchanged.		that the timer preset time is set to a value larger than "0".If timer integration is to be carried out in normal integration mode, set the timer preset time to any desired value.
<u>HA</u>		Determines whether to set the harmonic analysis mode or return to the normal measurement mode/queries the current setting.	<u>IL/IL?</u>	Sets the polarity for integrated result displayed when watt-hour or ampere-hour is selected on
		HAm <terminator></terminator>		display D/queries the current setting.
	o y max	"m" indicates whether the mode is harmonic analysis	Syntax	llm <terminator></terminator>
		mode or normal measurement mode.		"m" indicates the polarity. m = 0 : SUM (Where A h is displayed)
		m= 0 :Normal measurement mode		m= 0 : SUM (Wh or Ah is displayed) 1 :+ (Wh+ or Ah+ is displayed)
	Querv	1 :Harmonic analysis mode HA? <terminator></terminator>		2: - (Wh- or Ah- is displayed)
	•	se example	Query	IL? <terminator></terminator>
		HA1	Respor	nse example
	Description	• It is not possible to activate the harmonic analysis		ILO
		mode while integration is in progress or integration is	IM/IM?	Specifies which causes will be allowed to
		being interrupted; execution error 13 will occur.It is not possible to switch to harmonic analysis mode during		generate a status byte/queries the current setting.
		flicker measurement mode; execution error 20 will occur.	Syntax	IMm <terminator></terminator>
п	/HD?			"m" indicates the cause, and must be set within the
пυ		Determines whether or not output data should be updated/queries the current setting.		following range. $0 \le m \le 15$ m= 1 : Computation end
		HDm <terminator></terminator>		2 : Integration Flicker end
	oyntax	"m" indicates whether measured data (display and output) is		4 : Syntax error
		not updated or updated at every display update interval.	_	8 : OVER
		 m= 0 :Updates the data at each sampling rate. 1 :Hold 		IM? <terminator></terminator>
	Querv	HD? <terminator></terminator>	Respor	nse example
		se example	Description	IM15 n • If more than one of these causes is to be allowed, set
		HD0	Description	"m" to the sum of their individual "m" values. For
uл		Sate the maximum ander far hormonic analysis/		instance, if all causes are to be allowed, set "m" to 15
		Sets the maximum order for harmonic analysis/ queries the current setting.		(=1+2+4+8).
		HOm <terminator></terminator>	IP	Stops integration.
		"m" indicates the maximum order, and must be set		IP <terminator></terminator>
		within the following range.	Description	n • If an attempt is made to stop integration when integration has
	Quary	$1 \le m \le 50$ HO? <terminator></terminator>		already been interrupted (stopped), execution error 44 will occur.
	-	se example	IR	Resets integrated result.
	nespon	HO50		IR <terminator></terminator>
	Description	• If the set maximum order is smaller than that displayed on	Description	 If an attempt is made to reset the integrated result while integration is in progress, execution error 45 will occur.
		display A (set by the OR command for harmonic analysis),	10	
		the same order as the maximum order will be displayed.	<u>IS</u>	Starts integration.
ΗW		Sets the window width for harmonic analysis/		IS <terminator> n • If an attempt is made to start integration when</terminator>
		queries the current setting.	Decemption	integration is already in progress, execution error 42
	Syntax	HW m <terminator></terminator>		will occur.
		"m" indicates the analysis window width (the number of periods when the fundamental frequency is 40 to 70 Hz).		• If a voltage or current peak overflow, or overrange
		m= 0:16		takes place when an attempt is made to start integration, execution error 46 will occur, and
		1:8		integration, execution error 40 will occur, and integration will not be started.
		2 :4 3 :2		• It is not possible to use the integration function during
		4:1		harmonic analysis mode. If an attempt is made to start,
	-	HW? <terminator></terminator>		stop or reset integration, execution error 16 will occur.It is not possible to use the integration function during
	Respon	se example		flicker measurement mode. If an attempt is made to
		HW0		start, stop or reset integration, execution error 20 will
		Sets the integration mode/queries the current setting.		occur.
	Syntax	ICm <terminator></terminator>	<u>IT/IT?</u>	Sets the integration start time and stop time/
		"m" indicates one of the following integration modes.		queries the current settings.
		 m= 0 :Normal integration mode 1 :Continuous integration mode 	Syntax	ITm1/m2/m3/m4/m5/m6,m7/m8/m9/m10/m11/
		2 :Real time counting standard integration mode		m12 <terminator> "m1" indicates start year</terminator>
		3 :Real time counting continuous integration mode		$1996 \le m1 \le 2095$
	-	IC? <terminator></terminator>		"m2" indicates start month
	-	se example ICO		$1 \le m2 \le 12$ "m3" indicates start day
		Changing of the integration mode is not allowed while		$1 \le m3 \le 30$ or 31 or 28 or 29
		integration is in progress; execution error 13 will occur.		"m4" indicates start hour
		• If real time counting integration mode (normal or		$0 \le m4 \le 23$
		continuous) is used, set both the start time and stop time to times after the current time. Executing the IS		"m5" indicates start minute $0 \le m5 \le 59$
		command after both the start time and stop time have		"m6" indicates start second
		been set will place the instrument in standby state.		$0 \le m6 \le 59$
		• If continuous integration mode is selected, make sure		"m7" indicates stop year

egration.

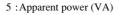
- ttempt is made to start integration when ion is already in progress, execution error 42 ur.
 - tage or current peak overflow, or overrange lace when an attempt is made to start tion, execution error 46 will occur, and ion will not be started.
 - possible to use the integration function during ic analysis mode. If an attempt is made to start, reset integration, execution error 16 will occur.
 - possible to use the integration function during measurement mode. If an attempt is made to op or reset integration, execution error 20 will

integration start time and stop time/ he current settings.

2/m3/m4/m5/m6,m7/m8/m9/m10/m11/



<u>)A/OA?</u>	Up to 14 measure	ems/queries the current settings. d data can be selected and output		017	Stop time had passed when aut print mode was activated.
. .		rom the D/A converter.		018 020	Date/time cannot be set properly.
Syntax	OAm1,m2,m3 <te "m1" indicates I within the follow</te 	D/A output channel, and must be set		020	Attempt made to execute command while flicke measurement is in progress, that
	$1 \le m1 \le 14$	ing range.			cannot be executed in such a state.
	"m2" indicates ou	itput item no.		021	Attempted to start flicke
	m2=0 :No outp				measurement while initializatio
	1 :Voltage				prior to flicker measurement
	2 :Current 3 :Power (performed (i.e. while "init" i
		e power (var)			displayed on display B)
		nt power (VA)		022	Attempted to start flicke
	6 :Power f				measurement while flicke
	7 :Frequer				measurement is already in progres
	9 : Watt-ho			023	There is no flicker output data to b
	10 : Ampere 11 : Phase a				printed.
		e peak (Vpk)		024	Attempted to stop flicke
		peak (Apk)			measurement even though flicke
		ted result (MATH)		025	measurement was not in progress.
		time of integration (INTEG-TIME)		025	Attempted to switch t
		e watt-hour (Wh+)			measurement of rated voltag (initial state) while flicke
		e watt-hour (Wh–) e ampere-hour (Ah+)			measurement is in progress.
		e ampere-hour (Ah–)		026	Attempted to return to norma
		indicates element.		020	measurement while measurement
	m3=1 :Elemen				rated voltage (initial state) is not
Query	OAm1? <terminate< td=""><td>or></td><td></td><td></td><td>progress.</td></terminate<>	or>			progress.
Respon	se example			030	File data failure
•	OA1,1,1			041	ttempted to start integration whe
Description		puted result) is selected for "m2", the		041	integration had been stopped due
	D/A output will b				an irregularity.
	-			042	Attempt made to start integration
AD/OAD?		ut items/queries the current s		•	during integration.
		of default settings are available.		043	Measurement stopped due
		tion can also be performed using a			overflow during integration or du
	key operation.				to a power failure.
Syntax	OADm <terminator< td=""><td>></td><td></td><td>044</td><td>Attempt made to stop integration</td></terminator<>	>		044	Attempt made to stop integration
	"m" indicates def	ault no.			while integration was interrupted.
	m= 1 :Default			045	Attempt made to reset integratio
		2 (DFLT-2)			while integration was in progress.
•		l setting (SEL)		046	Attempt made to start integratio
•	OAD? <terminator:< td=""><td>></td><td></td><td></td><td>when peak overflow was detected.</td></terminator:<>	>			when peak overflow was detected.
Respon	se example			047	Attempt made to start integration
.	OAD1				when integration timer preset tin
Description		ode (OAD3) is validated automatically		0.40	was set to "0".
	"1" (default 1) or "2	mand is executed if "m" has been set to		048	Attempt made to start integratio
		cted, items displayed on displays C and			after the stop time had alread
		s those output on channels 13 and 14.		051	passed.
		output items (for channels 13 and 14)		051	Measurement data overflo occurred. "-oL" is displayed
		items on displays C and D are changed.		052	Voltage peak overflow occurred
	e			052	Current peak overflow occurred
D	• •	of measured data.		054	Power factor exceeded "2". "PFEr
•	OD <terminator></terminator>			004	is displayed.
Description		B interface, the OD command should be		055	"degErr" was displayed.
	•	sable mode A. If the OD command is used		056	Frequency input level was too lo
		e B, execution error 11 will occur. Setting		050	or below measurement range
	the addressable mod	de should be done using a key operation.			"ErrLo" is displayed.
E	Requests output of	error codes via communications.		057	Frequency was above th
	OE <terminator></terminator>				measurement range. "ErrHi,"
-	se example				displayed.
пезроп	•			058	Computation overflow occurre
	ERR011 <terminat< td=""><td></td><td></td><td></td><td>"oF" is displayed.</td></terminat<>				"oF" is displayed.
	Error code	Description		059	PLL sync error during harmon
	011	Command error			analysis. "FrqEr" is displayed.
	012	Parameter error	05/050		
	013	Attempted to change settings which	<u>OF/OF?</u>		output items for normal measurement
		cannot be change while integration			current settings. To set whether or n
		was in progress.			output is possible, and the item for the
	014			selected element w	rill be output.
	014	Attempt made to switch to auto			
	014	range mode while the external shunt	Syntax	OFm1,m2 <termin< td=""><td>nator></td></termin<>	nator>
		range mode while the external shunt range is selected.	Syntax		
	014 015	range mode while the external shunt range is selected. Attempted to execute a command	Syntax	OFm1,m2 <termi< td=""><td>output item no.</td></termi<>	output item no.
	015	range mode while the external shunt range is selected. Attempted to execute a command that was protected.	Syntax	OFm1,m2 <termin "m1" indicates of</termin 	output item no. e (V)
		range mode while the external shunt range is selected. Attempted to execute a command	Syntax	OFm1,m2 <termin "m1" indicates of m1=1 :Voltag</termin 	putput item no. ge (V) ut (A)



- 6 :Power factor (PF)
- 7 :Frequency (Frq)
- 9 :Watt-hour
- 10 : Ampere-hour (Ah)
- 11 : Phase angle (deg)
- 12 : Voltage peak (Vpk)
- 13 :Current peak (Apk)
- 14 :Computed result (MATH)
- 15 :Elapsed time of integration (INTEG-TIME)
- 24 : Positive watt-hour (Wh+)
- 25 :Negative watt-hour (Wh-)
- 26 :Positive ampere-hour (Ah+)
- 27 :Negative ampere-hour (Ah-)
- "m2" indicates ON or OFF.
- m2=0 :OFF
 - 1 :ON
- Query OFm1? <terminator>
- Response example

OF1.1

<u>OFD/OFD</u>? Initializes communication output items for normal measurement/queries the current settings. Four sets of default setting are available.

- Syntax OFDm <terminator>
 - "m" indicates default no.
 - m= 0 : All items are OFF. (CLEAR)
 - 1 :Default 1 (DFLT-1)
 - 2 :Default 2 (DFLT-2)
 - 3 : All items are ON. (ALL)
 - 4 : Manual setting (SEL) (Response only when a
 - query is made)
- Query OFD? <terminator>

Response example

OFD1

- **Description** Manual setting mode (OFD4) is validated automatically when the OF command is executed if "m" is set to a value except for "4" (manual setting). Thus, m=4 (manual setting) is effective only for response to a query, and setting OFD4 will not cause an error, but has no effect.
- <u>OH/OH?</u> Sets communication output items for harmonic analysis/ queries the current settings. It is possible to set whether or not the selected item is output, and the item for the selected element will be output.
 - Syntax OHm1,m2 <terminator>
 - "m1" indicates output item no.
 - m2=0 :No output (None)
 - m1=1 :Total rms value of 1st up to n*th harmonic of voltage, analysis value of each harmonic from 1st up to n*th
 - 2 :Total rms value of 1st up to n*th harmonic of current, analysis value of each harmonic from 1st up to n*th
 - 3 :Total rms value of 1st up to n*th harmonic of active power, analysis value of each harmonic from 1st up to n*th
 - 4 :Reactive power (var)
 - 5 : Apparent power (VA)
 - 6 :Power factor (PF)
 - 7 :PLL source frequency (Sync)
 - 11 : Phase angle (deg) between f undamentals
 - 16 :Harmonic distortion of voltage (VTHD)
 - 17 :Harmonic distortion of current (ATHD)19 :Content of each harmonic (from 2nd to n*th)
 - of voltage (V%) 20 :Content of each harmonic (from 2nd to n *th)
 - of current (A%)
 - 21 :Content of each harmonic (from 2nd up to n^* th) of active power (W%)
 - 22 : Phase angle of current of 1st and voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st harmonic (Vdeg)
 - 23 : Phase angle of voltage of 1st and current of each harmonic from 2nd to n*th in relation to current of the 1st harmonic (Adeg)
 - "m2" indicates ON or OFF.
 - m2=0 :OFF
 - 1 :ON
 - * "n" is the upper limit of the harmonic order.

OH1,1 OHD/OHD? Initializes communication output items for harmonic analysis/queries the current settings. Four sets of default setting are available. Syntax OHDm <terminator> "m" indicates default no. m= 0 :All items are OFF. (CLEAR) 1 :Default 1 (DFLT-1) 2 :Default 2 (DFLT-2) 3 :All items are ON. (ALL) 4 :Manual setting (SEL) (Response only when a query is made) Query OHD? <terminator> Response example

OHD1

<u>OJ</u>

Description • Manual setting mode (OHD4) is validated automatically when the OH command is executed if "m" is set to a value except for "4" (manual setting) Thus, m=4 (manual setting) is effective only for response to a query, and setting OHD4 will not cause an error, but has no effect.

Requests output of judgment result data for each flicker observation period.

Syntax OJ m <terminator>

Query OHm1? <terminator>

Response example

"m" indicates the observation period no. 1 < m < 99

- **Description** The OD command requests output of the latest measured data for the current observation period, whilst the OJ command requests output of the measured data (judgment result data) obtained during past observation periods.
 - This command can be executed only during measurement of voltage fluctuation or display of judgment result. Otherwise, execution error 20 will occur (since there is no data to be output).
 - The OJ command can be executed only in addressable mode A. Executing this command in addressable mode B will cause error 11.

<u>OK/OK?</u> Sets communication output items for flicker measurement/ queries the current setting. To set whether or not the selected items is output is possible, and the item for the selected element will be output.

Syntax OK m1,m2 <terminator>

- "m1" indicates output item no.
- m= 1 :Rated voltage (Un)
 - 2 :Relative steady-state voltage change (dc)
 - 3 :Maximum relative voltage change (dmax)
 - 4 :Period d (t) 200 ms during which voltage exceeds the threshold level within one voltage change
 - 5 : Short-term flicker value (Pst)
 - 6 :Long-term flicker value (Plt)
 - 7 :Total judgment result (Total)
 - 8 :Rated voltage frequency
 - 9 :Elapsed time of measurement of voltage fluctuation
- "m2" indicates ON or OFF.
- m2=0 :OFF
- 1 :ON
- Query lkm1? <terminator>

Response example

OK1,1

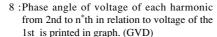
<u>OKD/OKD</u>? Sets communication output items to default settings for flicker measurement/queries the current setting. Four sets of default setting are available.

Syntax OKD m <terminator> "m" indicates default no.

- m = 0 : All items are OFF. (CLEAR)
- 1 :Default 1 (DFLT-1)
- 2 :Default 2 (DFLT-2)
- 3 :All items are ON. (ALL)
- 4 :Manual setting (SEL) (Response only when
 - an inquiry is made)

Appendix 1.2 Commands

Respon Description OR/OR? Syntax Query Respon	 OKD? <terminator></terminator> se example OKD1 Manual setting mode (OKD4) is validated automatically when the OK command is executed if "m" is set to a value except for "4" (manual setting). Thus, m=4 (manual setting) is effective only for response to a query, and setting OKD4 will not cause an error, but has no effect. Sets harmonic order to be displayed on display A/ queries the current setting. ORm <terminator> "m" indicates harmonic order, and must be set within the following range. 1 ≤ m ≤ 50 (The harmonic order must be smaller than the maximum order.)</terminator> OR? <terminator> se example OR1 If the selected order exceeds the maximum order set by </terminator> 	PF/PF? Syntax	Sets print output items for normal measurement/ queries the current settings. To set whether or not the selected item is output is possible, and the item for the selected element will be output. PFm1,m2 <terminator> "m1" indicates print output item no. m1=1 :Voltage (V) 2 :Current (A) 3 :Power (W) 4 :Reactive power (var) 5 :Apparent power (VA) 6 :Power factor (PF) 7 :Frequency (Frq) 9 :Watt-hour (Wh) 10 :Ampere-hour (Ah) 11 :Phase angle (deg) 12 :Voltage peak (Vpk) 13 :Current peak (Apk) 14 :Computed result (MATH) 15 :Elapsed time of integration (INTEG-TIME)</terminator>
	HO command or if it exceeds the maximum limit determined by the fundamental frequency of the input set by PS command, parameter error 12 will occur.		 24 :Positive watt-hour (Wh+) 25 :Negative watt-hour (Wh-) 26 :Positive ampere-hour (Ah+) 27 :Negative ampere-hour (Ah-)
•	Requests output of panel set-up information via communications. OS <terminator> se example Line 1: Model name MODEL 252101_cterminator</terminator>		"m2" indicates ON or OFF. m2=0 :OFF 1 :ON PFm1? <terminator> ise example</terminator>
	MODEL253101 <terminator> Line 2: Voltage range RV1,9;AV1,0 Line 3: Current range RA1,10;AA1,0;SA1,50.000 Line 4: Display function DA1;DB2;DC3;DD3; <terminator> Line 5: Display element EA1;EB1;EC1;ED1 <terminator> Line 6: Measurement condition WR1;FL0;FC0;KH0;KF0;QF0;NL0;CF3;SC0;AG0; HD0;S10;MT0;DG0 <terminator> Line 7: Measurement mode MV1,0;MA1,0 <terminator> Line 8: Scaling constant KV1,1.0000;KA1,1.0000;KW1,1.0000 <terminator> Line 9: Averaging setting AT0;AC1 <terminator> Line 10: Integration setting IC0;TM0,0;IL0 <terminator> Line 11: Harmonic analysis setting (possible only for the /HRM model) DH1;PS1;AF0;DF0;HW0;HO50;HA0;OR1<terminator> Line 13: D/A output setting (possible only for the /DA model) RT1,0 <terminator> Line 14: Flicker measurement setting 1 (possible only for the /FLK model) FK0;FE1;FI10,0;FM12;FDA1;FEA1;FNO1 <terminator> Line 15: Flicker measurement setting 2 (possible only for the /FLK model) UN0;UNL230.00;DC01;DCL3.00;DX01;DXL 4.00;DT01; DTL200,3.00 <terminator> Line 16: Flicker measurement setting 3 (possible only for the /FLK model) PS01;PSL1.00;PLO1;PLL0.65;PLN12;DNL1.00 <terminator> Line 17: Command/format group CM3 <terminator> Line 18: Output end END <terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator></terminator>	Query Respor Description	PF1,1 Initializes print output items for normal measurement/queries the current settings. Four sets of default setting are available. PFDm <terminator> "m" indicates default no. m= 0 : All items are OFF. (CLEAR) 1 :Default 1 (DFLT-1) 2 :Default 2 (DFLT-2) 3 :All items are ON. (ALL) 4 :Manual setting (SEL) (Response only when an inquiry is made) PFD? <terminator> rese example PFD1 1• Manual setting mode (PFD4) is validated automatically when the PF command is executed if "m" is set to a value except for "4" (manual setting). Thus, m=4 (manual setting) is effective only for response to a query, and setting PFD4 will not cause an error, but has no effect. Sets print output items for harmonic analysis/ gueries the current settings. To set whether or not the selected element will be output. PHm1,m2 <terminator> "m1" indicates print output item no. m1=1 : Analysis current value and relative harmonic content are printed in numeric. (A) 3 : Analysis active power value and relative harmonic content are printed in numeric. (M) 4 :Phase angle of voltage of each harmonic from 2nd to n*th in relation to voltage of the lst and phase angle of voltage of each harmonic from 2nd to n*th in relation to current of the 1st are printed in numeric. (GV)</terminator></terminator></terminator>
Description	 The number of lines varies depending on the options used and model type. 		6 :Analysis current value is printed in graph. (GA)7 :Analysis active power value is printed in graph. (GW)



- 9 :Phase angle of current of each harmonic from 2nd to n*th in relation to current of the 1st is printed in graph. (GAD)
- 10 :Relative harmonic content of voltage is printed in graph. (CGV)
- 11 :Relative harmonic content of current is printed in graph. (CGA)
- 12 :Relative harmonic content of active power is printed in graph. (CGW)
- "m2" indicates ON or OFF.
- m2=0:OFF

1 :ON.

- * "n" is the upper limit of the harmonic order.
- Query PHm1? <terminator>

Response example

PH1,1

PHD/PHD? Initializes print output items for harmonic analysis/queries the current settings. Four sets of default setting are available.

Syntax PHDm <terminator>

- "m" indicates default no.
 - m= 0 : All items are OFF. (CLEAR)
 - 1 :Default 1 (DFLT-1)
 - 2 :Default 2 (DFLT-2)
 - 3 : All items are ON. (ALL)
 - 4 :Manual setting (SEL) (Response only when a query is made)

Query PHD? <terminator>

Response example

PHD1

Description • Manual setting mode (PHD4) is validated automatically when the PH command is executed if "m" is set to a value except for "4" (manual setting). Thus, m=4 (manual setting) is effective only for response to a query, and setting PHD4 will not cause an error, but has no effect.

 PI/PI?
 Sets print interval in auto print mode/queries the current setting.

 Syntax
 PIm1,m2,m3 < terminator>

 "m1" indicates hour
 0 ≤ m1 ≤ 99

 "m2" indicates minute
 0 ≤ m2 ≤ 59

 "m3" indicates second
 0 ≤ m3 ≤ 59

 Query
 PI? < terminator>

Response example

PI0,1,0

- **Description** The minimum settable print interval is 10 seconds. If the interval is set below 10 seconds, parameter error 12 will occur.
- **PK/PK?** Sets printer output items for flicker measurement/ queries the current setting. To set whether or not the selected items is output is possible, and the item for the selected element will be output.

Syntax PK m1,m2 <terminator>

- "m1" indicates printer output item no.
- m1=1 :Cumulative probability function graph (CPF) 2 :Flicker meter judgment result table
- "m2" indicates ON or OFF.
- m2=0 :OFF

1 :ON

Query Pkm1? <terminator> Response example

PK1,1

<u>PKD/PKD</u>? Sets printer output items to default settings for flicker measurement/queries the current setting. Four sets of default setting are available.

- Syntax PKD m <terminator> "m" indicates default no.
 - m = 0 : All items are OFF. (CLEAR)
 - 1 :Default 1 (DFLT-1)
 - 2 :Default 2 (DFLT-2)
 - 3 :All items are ON. (ALL)
 - 4 :Manual setting (SEL) (Response only when
 - an inquiry is made)
- Query PKD? <terminator>
- **Response example**

PKD1

Description • Manual setting mode (PKD4) is validated automatically when the PK command is executed if "m" is set to a value except for "4" (manual setting). Thus, m=4 (manual setting) is effective only for response to a query, and setting PKD4 will not cause an error, but has no effect.

PLL/PLL? Sets the limit for long-term flicker value Plt/ queries the current setting.

- Syntax PLL m <terminator>
 - "m" indicates the limit.
 - 0.10 ≤ m ≤ 99.99
- Query PLL? <terminator>
- Response example

PLL0.65

Description • Executing this command during measurement of voltage fluctuation or display of judgment result will cause execution error 20.

<u>PLN/PLN</u>? Sets N value for long-term flicker value Plt (constant used in Plt equation)/queries the current setting.

- - 1 :Used as judgment item.
 - Query PLO? <terminator>

Response example

- PLO1
- **Description** Executing this command during measurement of voltage fluctuation or display of judgment result will cause execution error 20.

Prints out measured data.

- Syntax PO <terminator> Description • This command is valid whether print mode is auto or manual.
- PP Prints out panel set-up information.

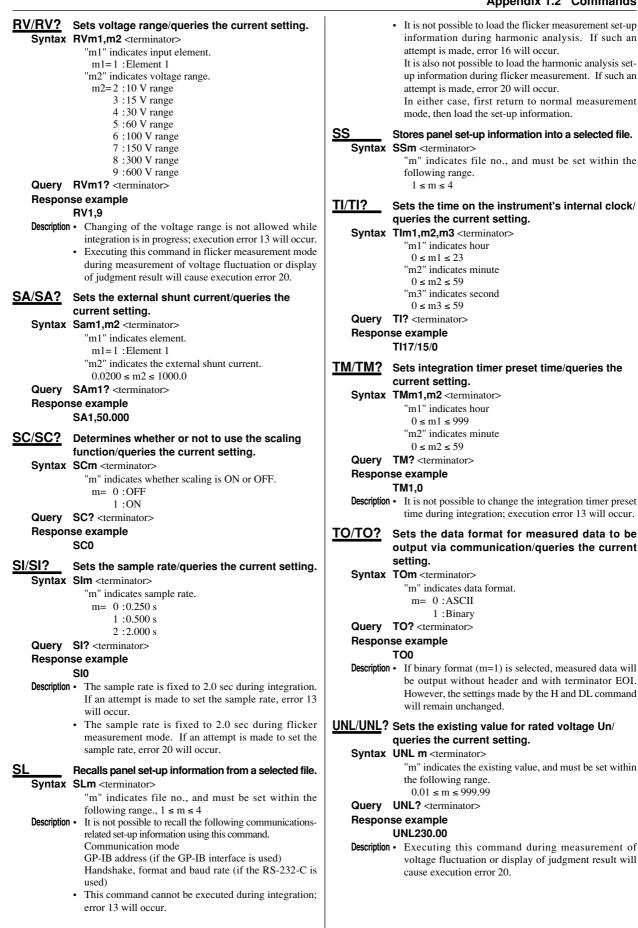
PO

Syntax PP <terminator>

PR/PR? Sets print mode /queries the current setting. Syntax PRm <terminator>

- "m" indicates print mode. m= 0 :Auto print OFF 1 :Auto print ON
- Query PR? <terminator> Response example
- PR0

PS/PS?	Sets the input to be used as the fundamental	<u>PY/PY?</u>	Sets the print synchronous method for auto print
	frequency (PLL source) for PLL synchronization/ queries the current setting.	Syntax	mode/queries the current setting. PYm <terminator></terminator>
Syntax	PSm <terminator></terminator>	Gyntax	"m" indicates synchronous print method.
	"m" indicates the input to be used as the PLL source. m= 1 :V1		m= 0 :Start/stop time synchronous print method1 :Integration time synchronous print method
	2 :A1		2 :Flicker measurement synchronous print
•	PS? <terminator></terminator>		method (possible only for the /FLK model)
Respon	se example PS1		PY? <terminator> ase example</terminator>
	-	пезроп	PY0
<u>P3L/P3L</u> ?	Sets the limit for short-term flicker value Pst/ queries the current setting.	Description	• Changing the synchronous print method during auto
Syntax	PSL m <terminator></terminator>		print mode (PR1) is not allowed; execution error 15 will occur. To change the synchronous print method,
	"m" indicates the limit. $0.10 \le m \le 99.99$		set auto print to OFF, then change the method.
Query	PSL? <terminator></terminator>	QF/QF?	Sets the frequency filter ON or OFF/queries the
Respon	se example	Currtow	current setting.
Description	PSL1.00Executing this command during measurement of	Syntax	QFm <terminator> "m" indicates whether the frequency filter is ON or OFF.</terminator>
Description	voltage fluctuation or display of judgment result will		m= 0 :OFF
	cause execution error 20.	Querv	1 :ON QF? <terminator></terminator>
PSO/PSO?	Sets whether or not short-term flicker value Pst be	-	ise example
Syntax	used as judgment item/queries the current setting. PSO m <terminator></terminator>		QF0
Cyntax	"m" indicates whether or not short-term flicker value is	RA/RA?	Sets current range/queries the current setting.
	used as judgment item. m= 0 :Not used as judgment item.	Syntax	RAm1,m2 <terminator> "m1" indicates input element.</terminator>
	1 :Used as judgment item.		m1 = 1 :Element 1
•	PSO? <terminator></terminator>		"m2" indicates current range. m2=5 :1 A range
Respon	se example PSO1		6 :2 A range
Description	• Executing this command during measurement of		7 :5 A range 8 :10 A range
	voltage fluctuation or display of judgment result will cause execution error 20.		9 :20 A range
			10 :30 A range 15 :50 mV range
PT/PT?	Sets the integration start time and stop time/ queries the current settings.		16 :100 mV range
	· · · · · · · · · · · · · · · · · · ·		
Syntax	PT m1/m2/m3/m4/m5/m6,m7/m8/m9/m10/m11/	Querv	17 :200 mV range RAm1? <terminator></terminator>
Syntax	m12 <terminator></terminator>		RAm1? <terminator></terminator>
Syntax		Respon	RAm1? <terminator> ise example RA1,10</terminator>
Syntax	m12 <terminator> "m1" indicates start year 1996 ≤ m1 ≤ 2095 "m2" indicates start month</terminator>	Respon	RAm1? <terminator></terminator>
Syntax	m12 <terminator> "m1" indicates start year 1996 ≤ m1 ≤ 2095 "m2" indicates start month 1 ≤ m2 ≤ 12</terminator>	Respon	 RAm1? <terminator></terminator> ase example RA1,10 Anse of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode
Syntax	m12 <terminator> "m1" indicates start year $1996 \le m1 \le 2095$ "m2" indicates start month $1 \le m2 \le 12$ "m3" indicates start day $1 \le m3 \le 30$ or 31 or 28 or 29</terminator>	Respon	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur.
Syntax	m12 <terminator> "m1" indicates start year $1996 \le m1 \le 2095$ "m2" indicates start month $1 \le m2 \le 12$ "m3" indicates start day</terminator>	Respon	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for
Syntax	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute</terminator>	Respon	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20.
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23</terminator>	Respon	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command.
Syntax	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute 0 \le m5 \le 59 "m6" indicates start second 0 \le m6 \le 59</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator>
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop month</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command.
Syntax	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute 0 \le m5 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m7" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop month 1 \le m8 \le 12</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m6" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop month 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop month 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29 "m10" indicates stop hour</terminator>	Respon Description <u>RC</u> Syntax Description	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used)
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop month 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29</terminator>	Respon Description <u>RC</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop pointh 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \leq m10 \leq 23 "m11" indicates stop minute 0 \leq m11 \leq 59</terminator>	Respon Description <u>RC</u> Syntax Description	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used)
Syntax	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop month 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \leq m10 \leq 23 "m11" indicates stop minute</terminator>	Respon Description RC Syntax Description	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting. RTm1,m2 <terminator></terminator>
Query	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute 0 \le m5 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m7" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop day 1 \le m8 \le 12 "m9" indicates stop day 1 \le m9 \le 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \le m10 \le 23 "m11" indicates stop minute 0 \le m11 \le 59 PT? <terminator></terminator></terminator>	Respon Description RC Syntax Description	 RAm1? <terminator></terminator> ase example RA1,10 Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting.
Query	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute 0 \le m5 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m7" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop day 1 \le m8 \le 12 "m9" indicates stop day 1 \le m9 \le 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \le m10 \le 23 "m11" indicates stop minute 0 \le m11 \le 59 PT? <terminator> se example</terminator></terminator>	Respon Description RC Syntax Description	 RAm1? <terminator></terminator> ase example RA1,10 An Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode GP-IB anddress (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting. RTm1,m2 <terminator></terminator> "m1" indicates hour 0 ≤ m1 ≤ 999 "m2" indicates minute
Query Respon	m12 <terminator> "m1" indicates start year 1996 \le m1 \le 2095 "m2" indicates start month 1 \le m2 \le 12 "m3" indicates start day 1 \le m3 \le 30 or 31 or 28 or 29 "m4" indicates start hour 0 \le m4 \le 23 "m5" indicates start minute 0 \le m5 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m6" indicates start second 0 \le m6 \le 59 "m7" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop year 1996 \le m7 \le 2095 "m8" indicates stop day 1 \le m8 \le 12 "m9" indicates stop day 1 \le m9 \le 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \le m10 \le 23 "m11" indicates stop minute 0 \le m11 \le 59 PT? <terminator></terminator></terminator>	Respon Description <u>RC</u> Syntax Description <u>RT/RT?</u> Syntax	 RAm1? <terminator></terminator> ase example RA1,10 An Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting. RTm1,m2 <terminator></terminator> "m1" indicates hour 0 ≤ m1 ≤ 999 "m2" indicates minute 0 ≤ m2 ≤ 59
Query Respon	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop day 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \leq m11 \leq 59 "m12" indicates stop second 0 \leq m12 \leq 59 PT? <terminator> se example PT1996/4/1/17/35/0, 1996/4/3/19/35/0 • If the stop time is before the start time, parameter error 12 will occur.</terminator></terminator>	Respon Description RC Syntax Description <u>RT/RT?</u> Syntax Query	 RAm1? <terminator></terminator> ase example RA1,10 An Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting. RTm1,m2 <terminator></terminator> "m1" indicates hour 0 ≤ m1 ≤ 999 "m2" indicates minute 0 ≤ m2 ≤ 59 RT? <terminator></terminator>
Query Respon	m12 <terminator> "m1" indicates start year 1996 \leq m1 \leq 2095 "m2" indicates start month 1 \leq m2 \leq 12 "m3" indicates start day 1 \leq m3 \leq 30 or 31 or 28 or 29 "m4" indicates start hour 0 \leq m4 \leq 23 "m5" indicates start minute 0 \leq m5 \leq 59 "m6" indicates start second 0 \leq m6 \leq 59 "m7" indicates start second 0 \leq m6 \leq 59 "m7" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop year 1996 \leq m7 \leq 2095 "m8" indicates stop day 1 \leq m8 \leq 12 "m9" indicates stop day 1 \leq m9 \leq 30 or 31 or 28 or 29 "m10" indicates stop hour 0 \leq m10 \leq 23 "m11" indicates stop minute 0 \leq m11 \leq 59 "m12" indicates stop second 0 \leq m12 \leq 59 PT? <terminator> se example PT1996/4/1/17/35/0, 1996/4/3/19/35/0 • If the stop time is before the start time, parameter error</terminator></terminator>	Respon Description RC Syntax Description RT/RT? Syntax Query Respon	 RAm1? <terminator></terminator> ase example RA1,10 An Changing of the current range is not allowed while integration is in progress; execution error 13 will occur. Executing this command in flicker measurement mode during measurement of voltage fluctuation or display of judgment result will cause execution error 20. Ranges 50mV, 100mV and 200mV are available for the external shunt. To use these ranges, set the correct shunt current value using the SA command. Initializes panel set-up information. RC <terminator></terminator> It is not possible to initialize the following communications-related set-up information using this command. Communication mode GP-IB address (if the GP-IB interface is used) Handshake, format and baud rate (if the RS-232-C is used) Sets the rated integration time when integrated values are to be output as an analog signal/queries the current setting. RTm1,m2 <terminator></terminator> "m1" indicates hour 0 ≤ m1 ≤ 999 "m2" indicates minute 0 ≤ m2 ≤ 59 RT? <terminator></terminator>



UNO/UNO? Sets the acquisition method for rated voltage Un/ queries the current setting.

Syntax UNO m <terminator>

- "m" indicates the acquisition method for rated voltage.
- m= 0 : Acquires by measurement. 1 :Uses the existing value.
- Query UNO? <terminator>

Response example

UNO0

 $\ensuremath{\text{Description}}$ $\ensuremath{\cdot}$ Executing this command during measurement of voltage fluctuation or display of judgment result will cause execution error 20.

WR/WR? Sets the wiring system/queries the current setting.

Syntax WRm <terminator> m= 1 :1Φ2W

Query WR? <terminator>

Response example

WR1

Appendix 1.3 Status Byte Format

DI08	DI07	DI06	DI05	DI04	DI03	DI02	DI01
Integration Flicker BUSY	SRQ	ERROR	Printer BUSY	OVER	Syntax ERROR	Integration Flicker END	Computation END

Integration Flicker BUSY (DIO 8)

This bit is set to "1" when integration is in progress or during measurement of voltage fluctuation. This bit cannot be disabled by the IM command since it is a status bit. Even if this bit is set to "1", SRQ will not be affected.

SRQ(DIO 7)

This bit is set to "1" when computation END (DIO 1), integration END (DIO 2), OVER (DIO 4) or syntax ERROR (DIO 3) occurs. When RQS is set to "1", SRQ is set to TRUE, issuing a service request to the controller. This bit is reset to "0" when a response is sent to the serial poll. To prevent the SRQ and status byte being affected by computation END, integration END, OVER or syntax ERROR, this bit must be disabled by the IM command.

After an "IM15", SRQ is affected by a computation END, integration END, syntax ERROR or OVER.

After an "IM1", SRQ is affected only by a computation END.

In the case of "IM4", the SRQ is affected only by a syntax ERROR.

ERROR(DIO 6)

When a syntax ERROR or OVER occurs, this bit is set to "1" and the SRQ is set to TRUE.

Printer BUSY (DIO 5)

This bit is set to "1" when printing of data is in progress. This bit cannot be disabled by the IM command since it is a status bit. Even if this bit is set to "1", SRQ will not be affected.

OVER(DIO 4)

This bit is set to "1" and the SRQ is set to TRUE when an overrange occurs in the measured data. However, this is not valid if the bit has been disabled by the IM command. This bit is reset after a response is made to the serial poll. The nature of OVER can be identified by the OE command.

Syntax ERROR (DIO 3)

This bit is set to "1" when a command error, parameter error or execution error occurs. The error no. can be identified by the OE command. This bit is reset after a response is made to the serial poll. However, this is not valid if the bit has been disabled by the IM command.

Integration Flicker END (DIO 2)

This bit is set to "1" when integration has been completed or when each observation period for short-term flicker value Pst has been completed in flicker measurement mode.

Computation END (DIO 1)

This bit is set to "1" when computation has been completed and the display is updated. The bit is reset when a response is made to the serial poll. However, this is not valid if the bit has been disabled by the IM command.

Appendix 1.4 Data Output Format

Output Format for Measured/Computed Data

Data Format

Measured data normally consists of 6 bytes of header and 11 bytes of data.

Header Data

Header Section

The header section consists of 6 bytes (h1 to h6.)

Tl	ne hea	der se	ection	consi	sts of	6 byt	es (h1 to h6.)	
	h1	h2	h3	h4	h5	h6]	
hl	to h4	: Data	a type	, elem	ent			
•	Wher	n the d	lata ty	pe is '	V	to A/I	В	
hl	to h3	B: Data	a type					
	V	: Vo	ltage			A	: Current	W: Power
	VA_	: Ap	parent	power		Var	: Reactive power	PF_ : Power factor
	HzV	: Vol	ltage fr	equenc	y .	HzA	: Current frequency	Wh_: Watt-hour
	Ah_	: An	npere-	hour		DEG	: Phase angle	Wh+ : Positive watt-hour
	Wh-	: Neg	gative w	att-hou	r.	Ah+	: Positive ampere-hour	Ah- : Negative ampere-hour
	Vpk	: Pea	ak vol	tage		Apk	: Peak current	
	HM	: Ela	apsed	time o	of inte	gratio	on	
	CV1	: Cro	est fac	tor of	V1		CA1 : Crest f	actor of A1
	A+B	: Va	lue or	n displ	ay A	+ Val	lue on display B	
	A-B	: Va	lue or	n displ	ay A	– Val	lue on display B	
	A*B	: Va	lue or	n displ	ay A	* Val	lue on display B	
	A/B	: Va	lue or	n displ	ay A	/ Val	ue on display B	
h∠	l: Eler	nent						
	1 : E	lemer	nt 1					
	_ : N	o elei	nent (for H	M_, C	CV1 to	o A/B)	
•	Wher	n the d	lata ty	pe is .	A/B2	or A2	2/B	
hl	to h4	: Data	a type					
	A/B2	: Disj	play A	/(Dis	play l	$B)^2$		
	A2/B	: (Dis	splay	$A)^2/D$	isplay	νB		
h	5 : Dat	ta stat	e					
	N: N	Jorma	ıl	I : C)verra	nge	O: Computation over	erflow P: Peak overflow
	E: N	lo dat	a					
hð	5 : Ind	icates	phas	e lead	or lag	g whe	n the data type is DE	EG (phase angle).
	"_	_" (spa	ace) is	s selec	ted if	the d	lata type is not DEG.	
	G: I	Lag		D : 1	Lead		: Not detectab	le

Data Section

The data section consists of 11 bytes (d1 to d11.)

d1	d2	d3	d4	d5	d6	d7	d8	d9	d10	d11	
d1		: Pola	arity;	_(spa	ace) o	r - (m	inus)				
d2 to	to d8 : Mantissa, floating-point number of the maximum 6 digi								its		

u1 to u	• • • • • • • • • •	, noung point number of the mannah o as	5
d9 to d	11 : Expor	ent E-3 \Rightarrow m, E+0, E+3 \Rightarrow k, E+6 \Rightarrow M	
If the d	ata type is H	Eff	
d9	: %	d10 to d11 : _(space)	

• Data state in the case of an overrange (aL, ---- is displayed.)

h1	h2	h3	h4				9	9	9	9	9	9	-	E	+	3
				-	-	-	-	-	-	•	-	•	-		•	-

Data state in the case of a computation overflow

(0	, F, P	FEr	r,dE	GEr,	Errl	L o, l	ЕггН	, is displayed.)
-----	--------	-----	------	------	------	--------	------	-----------------	---

Data state in the case of no data

"I" of data causing an overrange becomes "E".

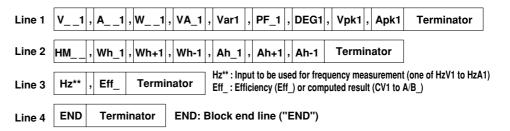
Elapsed time of integration

H M _ N _ d1 d2 d3 d4 d5 d6 d7 d8	d9
---	----

d1 to d3	: Elapsed time of integration	Hour
d4	· · · · · · · · · · · · · · · · · · ·	
d5 to d6	: Elapsed time of integration	Minute
d7	: ": "	
d8 to d9	: Elapsed time of integration	Second

Output Format when "SEL" (manual setting) is Selected

Measured/computed data can be output simultaneously, and the user is allowed to choose any output items. Each output block is of the following format.



Each output block normally consists of 4 lines including the block end line ("END"). However, if all output items on a line are set to "no output", this line will be omitted, reducing the number of output lines to 4. For instance, if all output items (V_1 to Apk1) are set to "no output", line 1 will be omitted.

Furthermore, if any output item on a line is set to "no output", all data following this item on the line will be shifted forward. For instance, if A_1 on line 1 is set to "no output", V_1 will be followed immediately by the data for W_1 .

Output Format when "DFLT-1" is Selected

Line 1	V1, A1, W1	I Terminator
Line 2	Hz** Terminator	Hz**: Input to be used for frequency measurement (one of HzV1 to HzA1)
Line 3	END Terminator	END: Block end line ("END")

Output Format when "DFLT-2" is Selected

Line 1	W1 Terminator
Line 2	HM, Wh_1, Wh+1, Wh-1, Ah_1, Ah+1, Ah-1 Terminator
Line 3	Hz** Terminator Hz**: Input to be used for frequency measurement (one of HzV1 to HzA1)
Line 4	END Terminator END: Block end line ("END")

Output Format for Harmonic Analysis Data

Data Format

Output data consists of 8 bytes of header and 11 bytes of data.

Header Section

The header section consists of 8 bytes (h1 to h8.)

h1 h2	h2 h3 h4	h5 h6	h7 h8
-------	----------	-------	-------

- h1 to h3 : Data type
 - V_{--} : Total rms value of 1st to n^{*}th of voltage, analysis value of each harmonic from 1st to n^{*}th of voltage
 - A__ : Total rms value of 1st to n^{*}th of current, analysis value of each harmonic from 1st to n^{*}th of current
 - W__ : Total rms value of 1st to n^{*}th of active power, analysis value of each harmonic from 1st to n^{*}th of active power
 - VA_ : Apparent power
 - Var : Reactive power
 - PF_ : Power factor of 1st
 - HzV : Fundamental frequency of PLL source voltage
 - HzA : Fundamental frequency of PLL source current
 - DEG : Phase angle between fundamentals
 - VTH : Harmonic distortion of voltage
 - ATH : Harmonic distortion of current
 - VCN : Content of each harmonic from 2nd to n*th of voltage
 - ACN : Content of each harmonic from 2nd to n*th of current
 - WCN : Content of each harmonic from 2nd to n*th of active power
 - DGV : Phase angle of current of 1st and voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st
 - DGA : Phase angle of voltage of 1st and current of each harmonic from 2nd to n^{*}th in relation to current of the 1st
- h4 : Element
 - 1 : Element 1

h5 : Data state

- N : Normal I : Overrange O : Computation overflow P : Peak overflow E : No data
- h6, h7 : Order
 - 01 to 50: Order of the fundamental or harmonic (must be smaller than the maximum order)
 - _ : No order (total rms value of harmonic from 1st to n^{*}th of V__, A__ and W__, VA_, Var, PF_, HzV, HzA, DEG, VTH, ATH)
- h8 : Indicates phase lead or lag when the data type is DGV or DGA, and order is 01.
 - "_" (space) is selected if the data type is not DGV or DGA. G : Lag D : Lead _ : Not detectable
 - G : Lag D : Lead _: N * "n" is the upper limit of the harmonic order.

Data Section

The data section consists of 11 bytes (d1 to d11.)

d1 d2 d3 d4 d5 d6 d7 d8 d9 d10 d1

d1 : Polarity ; _ (space) or - (minus)

d2 to d8 : Mantissa, floating-point number of the maximum 6 digits d9 to d11 : Exponent $E-3 \Rightarrow m, E+0, E+3 \Rightarrow k, E+6 \Rightarrow M$ If the data type is VTH, ATH, VCN, ACN, WCN d9 : % d10 to d11 : _(space)

Output Format when "SEL" (manual setting) is Selected

Harmonic analysis data can be output simultaneously, and the user is allowed to choose any output items. Each output block is of the following format.

"##" indicates the maximum order. Data for orders exceeding the maximum order will not be output.

Line 1	V_1N_ , V_1N01 , V_1N02 , · · · · · · · · · V_1N## Terminator	
		_
Line 2	A1N, A1N01, A1N02, · · · · · · · · · A1N## Terminator	
Line 3	W1N, W1N01, W1N02, · · · · · · · · · W1N## Terminator	
Line 4	VA_1N , Var1N , PF_1N , DEG1N, VTH1N , ATH1N Termina	tor
Line 5	VCN1N02 , VCN1N03 , · · · · · · · · · VCN1N## Terminator	
Line 6	ACN1N02, ACN1N03, ·····ACN1N## Terminator	
Line 7	WCN1N02, WCN1N03, ·······WCN1N## Terminator	
Line 8	DGV1N01 , DGV1N02 , DGV1N03 , · · · · · · · · DGV1N## Terminator	
		_
Line 9	DGA1N01 , DGA1N02 , DGA1N03 , · · · · · · · · DGA1N## Terminator	
Line 10	Hz**N Terminator Hz**: PLL source frequency (one of HzV1 to HzA1)	
Line 11	END Terminator END: Block end line ("END")	

Each output block normally consists of 11 lines including the block end line ("END"). However, if all output items on a line are set to "no output", this line will be omitted, reducing the number of output lines to 30. For instance, if all output items $(VA_1N_- \text{ to } ATH1N_-)$ are set to "no output", line 4 will be omitted. However, lines 1 to 3 and 5 to 9 will not be output if they are set to "no output", since only one output item is contained in those lines.

Furthermore, if any output item on a line is set to "no output", all data following this item on the line will be shifted forward. For instance, if VarIN_ on line 4 is set to "no output", VA_1N_ will be followed immediately by the data for $PF_1N_$.

Output Format when "DFLT-1" is Selected

"##" indicates the maximum order. Data for orders exceeding the maximum order will not be output.

Line 1	V1N V1N01 V1N02 V V1N## Terminator
Line 2	A1N A1N01 A1N02 · · · · · · · · · · · · A1N## Terminator
Line 3	W1N, W1N01 W1N02 W1N02 W1N## Terminator
Line 4	VTH1N, ATH1N Terminator
Line 5	VCN1N02 , VCN1N03 , · · · · · · · · VCN1N## Terminator
Line 6	ACN1N02 , ACN1N03 , · · · · · · · · ACN1N## Terminator
Line 7	WCN1N02, WCN1N03, ····· WCN1N## Terminator
Line 8	Hz**N_ Terminator Hz**: PLL source frequency (one of HzV1 to HzA1)
Line 9	END Terminator END: Block end line ("END")

Output Format when "DFLT-2" is Selected

"##" indicates the maximum order. Data for orders exceeding the maximum order will not be output.

Line 1	DEG1N_ Terminator				
Line 2	DGV1N01 DGV1N02 , DGV1N03 , · · · · · · · · DGV1N## Terminator				
Line 3	DGA1N01 DGA1N02 , DGA1N03 , · · · · · · · · DGA1N## Terminator				
Line 4	Line 4 Hz**N_ Terminator Hz**: PLL source frequency (one of HzV1 to HzA1)				
Line 5	END Terminator END: Block end line ("END")				

Output Format for Flicker Measurement Data

Data Format

Flicker measurement data consists of 8 bytes of header and 11 bytes of data.

Header	Data
--------	------

Header Section

The header section	on consists o	of 8 bytes	(h1 to h8).
--------------------	---------------	------------	-------------

1 h2 h3	h4	h5	h6	h7	h8
---------	----	----	----	----	----

- h1 to h3 : Data type
 - V__ : Voltage (nominal voltage)
 - HzV : Voltage frequency
 - HM_ : Elapsed time
 - dc_ : Relative steady-state voltage change (dc)
 - dmx : Maximum relative voltage change (dmax)
 - dt_ : Period during which voltage change exceeds the threshold level during a voltage change in one fluctuation
 - Pst : Short-term flicker value (Pst)
 - Plt : Long-term flicker value (Plt)
 - Ttl : Total judgment result (Total)
- h4 : Element

1 : Element 1

h5 : Data state

N : NormalI : OverrangeO : Computation overflow P : Peak overflowE : No dataU : Undefined (dc)

h6 to h7 : Observation period no.

h8 : Judgment result

8			
_: No judgment	F : FAIL	P:PASS	I : Judgment impossible

Data Section

	d1	d2	d3	d4	d5	d6	d7	d8	d9	d10	d11		
(11	: Polarity; _ (space) or - (minus)											

 $\begin{array}{l} d2 \text{ to } d8 & : \text{ Mantissa, floating-point number of the maximum 6 digits} \\ d9 \text{ to } d11 & : \text{Exponent E-3} \Rightarrow \text{m, E+0, E+3} \Rightarrow \text{k, E;6} \Rightarrow \text{M} \\ \text{If the data type is } dc_{\text{or }} \text{dmx :} \\ d9 & : \% \quad d10 \text{ to } d11 : _(\text{space}) \end{array}$

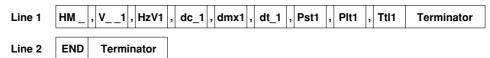
- The data state in the case of overrange, computation overflow and no data is the same as the one for normal measurement.
- The data format for elapsed time is the same as the one for elapsed time of integration.
- Data when undefined (dc) (" $u = d \xi \xi$ " is displayed)

	d	с	_	h4	U	h6	h7	I	-	9	9	9	9	9	9		Е	+	3
]	Data for total judgment result (Total)																		
]	In the	e cas	e of	PAS	S														
	т	t	I	h4	Ν	_	Ι	Р		0	0	0	0	0		0	Е	+	0
]	In the	e cas	e of	FAII															
	т	t	I	h4	Ν	_	_	F	-	0	0	0	0	1		0	Е	+	0
]	In the case of Judgment impossible																		
	т	t	I	h4	N	_	_	Т	-	0	o	0	0	2		0	Е	+	0

Output Format when "SEL" (manual setting) is Selected

Line 1	НМ _	, V1 , HzV1	, (lc_1	,	dmx1	,	dt_1	,	Pst1	,	Plt1	,	Tti1	Terminator
Line 2	END	Terminator]												

Output Format when "DFLT-1" is Selected



Output Format when "DFLT-2" is Selected

Line 1	НМ _	,	dc_1	,	dmx1	,	dt_	1	,	Pst1	,	Plt1	,	Ttl1	Terminator
Line 2	END		Termi	n	ator										

Output Format (Binary) for Latest CPF (Cumulative Probability Function) Data Registered at Elapse of Short-term Flicker Value Measurement Time

The CPF data is output as a response for the communication command CPF1.

Data Format

CPF data assignment (4100 bytes = $1025 \times \text{Single real data}) + \text{EOI}$

CPF[0]	CPF[1]	 CPF[31]	
CPF[32]	CPF[33]	 CPF[63]	
CPF[64]	CPF[65]	 CPF[95]	
CPF[992]	CPF[993]	 CPF[1023]	CPF[1024]

For a detailed description of data format, refer to "Output Format for Binary Data" on the next page.

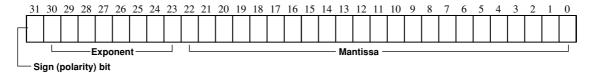
Output Format for Binary Data

Data Section

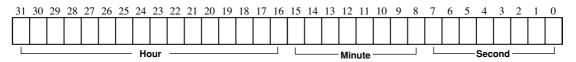
The data section consists of 4 bytes of IEEE SINGLE REAL data. The data can be converted to physical value using the following formula. (MSB of the data is output first.)

$$D = (-1)^{S} x 2^{(E-127)} x (1 + \frac{M}{2^{23}})$$

- D : Physical value
- S: Sign (polarity) bit (0 or 1)
- E: Exponent (0 to 254)
- M : Mantissa (23 bits of binary value)



- Data state in the case of an overrange or computation overflow (aL, aF, PFErr, dEGEr, ErrLa, ErrHi is displayed.)
- [9.9E+37] (+∞) is output.
- Elapsed time of integration (---- is displayed.) [9.91E+37] (NAN) is output.
- Elapsed time of integration, elapsed time of voltage fluctuation measurement Hour: 16-bit binary value Minute: 8-bit binary value
 - Second: 8-bit binary value



Header is always omitted, irrespective of whether or not addition of header is set by the communication command H.

Output Format

All data selected as described in Section 14.1, "Selecting the Output Items" is output at one time as one block data (4 bytes × number of data sets).

- Data of each items is output in the same order as ASCII format.
- No comma is inserted between data of each item to separate them.
- A terminator, which is normally added at the end of each line, is not added.
- "END", which is output as the block end line, is not output. However, "EOI" will become TRUE when the final data byte is output.

Output Format for Set-up Information/Error Codes

Refer to the application examples of the OS and OE commands given in the Appendix 1.2. To see the contents of the displays in these examples, refer also to the description of the commands given in the Appendix 1.2.

Appendix1.5 For Users Using Communication Commands of Digital Power Meter 2533E

This instrument differs from the 2533E in communications command and data format. This instrument has a function which enables the user to use communications programs created for the 2533E. This function is described below in detail.

Communications Commands

To use 2533E command group with this instrument, setting command CM2 is required. (For a detail description of the CM command, refer to Appendix 1.2, "Commands".

Description is given below for those commands which differ from this instrument when the 2533E command group is selected.

Note .

- For a description of how to set the addressable mode, refer to page 14-6.
- The error codes and status byte format are the same as those used with this instrument. For a detailed description, refer to page App 1-16. They differ from those used with the 2533E.
- To receive harmonic analysis data via RS-232-C interface, set handshake mode to a value other than "0", since harmonic analysis data contains a large number of output bytes.

ΔΔ/ΔΔ?	Sets auto or manual range mode for the current	MN/MN/?	Sets the measurement mode/queries the current
	ranges/queries the current setting.		setting.
Syntax	AAm <terminator></terminator>	Syntax	MNm <terminator></terminator>
Oyntax	"m" indicates whether range mode is auto or manual.	Cyntax	"m" indicates measurement mode.
	m = 0: Manual range		m = 0 : RMS
	1 : Auto range		1 :MEAN
Querv	AA? <terminator></terminator>		2 :DC
•	se example	Query	MN? <terminator></terminator>
nespon	AAO	Respon	ise example
	AAU		MNO
AV/AV?	Sets auto or manual range mode for the voltage		
	ranges/queries the current setting.	<u>OF/OF?</u>	Sets communication output items for normal
Svntax	AVm <terminator></terminator>		measurement/queries the current settings. Up to
- ,	"m" indicates whether range mode is auto or manual.		14 measured data can be selected and output.
	m= 0 : Manual range	Syntax	OF m1,m2,m3 <terminator></terminator>
	1 : Auto range		"m1" indicates output channel no., and must be within
Querv	AV? <terminator></terminator>		the following range.
•	se example		$1 \le m1 \le 14$
neepen	AV0		"m2" indicates output item no.
			m2=0 :No output (None)
DS	Sets the delimiter EOI output timing. This		1 :Voltage (V)
	command is used with the 2533E, but cannot be		2 :Current (A)
	used with this instrument even if 2533E command		3 :Power (W)
	group is selected by the CM command.		4 :Reactive power (var) 5 :Apparent power (VA)
	• · · ·		6 :Power factor (PF)
<u>kv/kv?</u> ,	(A/KA?,KW/KW?		7 :Frequency (Frq)
	Sets the scaling constant/queries the current setting.		9 :Watt-hour (Wh)
	KV is used for voltage measurement, KA for current		10 : Ampere-hour (Ah)
	measurement, and KW for power measurement.		m=0:Manual range
Syntax	KVm <terminator></terminator>		11 : Phase angle (deg)
	KAm <terminator></terminator>		12 :Voltage peak (Vpk)
	KWm <terminator></terminator>		13 :Current peak (Apk)
	"m" indicates scaling constant, and must be set within		14 : Computed result (MATH)
	the following range.		15 :Elapsed time of integration (INTEG-TIME)
	$0.0001 \le m \le 10000.$		(possible only for the /INTG model)
Query	KV? <terminator></terminator>		24 :Positive watt-hour (Wh+)
•	KA? <terminator></terminator>		25 :Negative watt-hour (Wh-)
	KW? <terminator></terminator>		26 :Positive ampere-hour (Ah+) 27 :Negative ampere-hour (Ah-)
Respon	se example		"m3" indicates element.
nespon	KV1.0000		$m_3=1$: Element 1
	KA1.0000	Querv	OFm1? <terminator></terminator>
		•	ise example
	KW1.0000	nespon	OF1,3,1
			011,0,1

<u>OL</u>

Function: Requests output of setup information. Output format differs from that of the 2533E. Syntax OL <terminator> **Response example** The following lines differ from the response example for OS command given on page App 1-12. Voltage range Line 2 : RV9;AV0 <terminator> Line 3 : Current range RA10;AA0;SA50.000 <terminator> Measurement mode Line 7 : MN0 <terminator> Line 8 : Scaling constant KV,1.0000;KA,1.0000;KW,1.0000 <terminator> OS Requests output of setup information. This command cannot be used if 2533E command group is selected by the CM command. However, in this case OL command can be used instead. RA/RA? Sets current range/queries the current setting. Syntax RAm <terminator> "m" indicates current range. m= 5 :1A range 6:2A range 7:5A range 8 :10A range 9:20A range 10:30A range 15 :50mV range 16 :100mV range 17 :200mV range Query RA? <terminator> **Response example** RA9 RV/RV? Sets voltage range/queries the current setting. Syntax RVm <terminator> "m" indicates voltage range. m2=2 :10V range 3 :15V range 4:30V range 5 :60V range 6 :100V range 7 :150V range 8 :300V range 9:600V range Query RV? <terminator> **Response example** RV9 SA/SA? Sets the external shunt current/queries the current setting. Syntax SAm <terminator> "m2" indicates the external shunt current. $0.0200 \le m \le 1000.0$ Query SA? <terminator> **Response example** SA50.000 WR/WR? Sets the wiring system/queries the current setting. Syntax WRm <terminator> "m" indicates wiring system. m= 2 :1Φ2W Query WR? <terminator> **Response example** WR2

Output Items

To read measured data using 2533E communication program, this instrument's addressable mode B must be set. Output items do not match those displayed on each display as in the 2533E, but match those set for ch.1 to ch.3 by the OF command of the 2533E command group. Select output items according to the 2533E communications program.

Note _

• For the 2533E and 2531 command group, output items can be set only by using the OF command. It is not possible to set output items using the panel keys.

Data Output Format

Data consists of 12 bytes of header and 12 bytes of data. The entire data output format is shown below.

ah 1	heade	-	ch.1 c	lata		ah 2	head	.	ch.2 dat			ch.3 h	oodor	ch.3 data
-				ลเล	,	cn.z	nead	er	ch.z da	เส	,	cn.s n	eader	ch.s data
Header Section														
h1	h2	h3	h4	h5	h6	h7	h8	h9	h10	h	11	h12		
h1 to h	1 to h2 : Output channel													
DA	DA: ch.1 $DB: ch.2$ $DC: ch.3$													
h1 to h	14 : Da	ita ty	р											
0:	No ou	itput	•	7	: Hz	V (Vol	tage fre	equenc	y) 14	: M	ATH	(Efficienc	y and co	omputed result)
1:	V (Vo	oltage	e)	8	: Hz/	A (Cur	rent fre	quenc					-	integration)
	A (Cu	•	-		: Wł	ı (Wa	tt-hou	r)				Positive		
3:	W (Po	ower))	10	: Ah	(Am	pere-h	our)	25	: W	/h- (1	Negative	watt-ł	iour)
4 :	Var (Re	eactive	e powe	r) 11	: DE	G (Pl	1ase ai	ngle)	26	: A	h+ (F	Positive a	ampere	-hour)
	VA(Ap		•					•				legative	-	
	PF(Po	-	-		-							e		,
• If	"15" is s	set to	h3 and	d h4 wł		B" is s	et to h	1 and I	12, "DB4_	_" is (output	to h1 thro	ough h4	. This is done to
h5 to h	16: Ou	tput c	chann	el										
EA	: ch.1		EF	3 : ch	.2	EC	: ch.3							
h7: Ele	ement													
1 : E	Elemen	nt 1												
h8: Da	ita stat	e												
N : 1	Norma	ıl	I :	Overn	ange/	'no da	ta		O :	Con	iputa	tion over	rflow	
h9 to h	n11: U	nit												
V	: V		VA_	: VA		DEG	: DE	G	Wh- : \	Wh-				
A	: A		HZ_	: Hz		Vpk	: Vpk		Ah+ : /	4h+				
W_	_ : W		Wh_	: Wh		Apk	: Apk		Ah-: A	h-				
VAI	R : var		Ah_	: Ah		Wh+	·:Wh	+	:	othe	r			
MA	TH(C)	V1.C.	A1.A-	+B,A-	B,A*	B,A/E	B,A/B	mear	ing A/B	2),A	A2/(m	eaning A	A2/B))	

MATH(CV1,CA1,A+B,A-B,A*B,A/B,A/B(meaning A/B2),A2/(meaning A2/B)) h12: Fixed to ",".

Data Section

	d1	d2	d3	d4	d5	d6	d7	d8	d9	d10	d11	d12
Ċ	d1: Polarity; _ (space) or - (minus)											
Ċ	d2 - d9 : Mantissa, floating-point number of the maximum 7 digits											
Ċ	110-d1	12 :	Expo	nent								
			E-3 =	⇒ m								
	E+0											
			E+3 =	⇒ k								
			E+6 =	⇒M								

Appendix

Appendix1.6 For Users Using Communication Commands of Digital Power Meter 2531

This instrument differs from the 2531 in communications command and data format. This instrument has a function which enables the user to use communications programs created for the 2531. This function is described below in detail.

Communications Commands

To use 2531 command group with this instrument, setting command CM0 or CM1 is required. (For a detailed description of the CM command, refer to Appendix 1.2, "Commands".

Description is given below for those commands which differ from this instrument when the 2531 command group is selected.

OH/OH? OF/OF? Sets communication output items for harmonic Sets communication output items for normal analysis/queries the current settings. measurement/queries the current settings. Syntax OH m1,m2 <terminator> Up to 14 measured data can be selected and "m1" indicates output item no. output. m1=1 : Analysis voltage value and relative Syntax OF m1,m2,m3 <terminator> harmonic content are output in numeric. "m1" indicates output channel no., and must be within the following range. (V) 2 : Analysis current value and relative $1 \leq m1 \leq 14$ "m2" indicates output item no. harmonic content are output in numeric. m2=0 :No output (None) (A) 1 : Voltage (V) 3 : Analysis active power value and relative 2 :Current (A) harmonic content are output in numeric. 3 :Power (W) (W) 4 :Reactive power (var) 4 : Phase angle of voltage of each harmonic 5 : Apparent power (VA) from 2nd to n*th in relation to voltage of 6 : Power factor (PF) the 1st and phase angle of current of each 7 :Frequency (Frq) harmonic from 2nd to n*th in relation to 9 : Watt-hour (Wh) current of the 1st are output in numeric. 10 : Ampere-hour (Ah) (deg). 11 : Phase angle (deg) 13 : Voltage, current, active power and phase 12 : Voltage peak (Vpk) angle are output in numeric. (AAL) 13 :Current peak (Apk) "m2" indicates input. 14 : Computed result (MATH) m2=1 :Element 1 15 :Elapsed time of integration (INTEG-TIME) "n" is the upper limit of the harmonic order. 24 : Positive watt-hour (Wh+) Query OH? <terminator> 25 :Negative watt-hour (Wh-) 26 : Positive ampere-hour (Ah+) **Response example** 27 :Negative ampere-hour (Ah-) OH3,1 "m3" indicates element. m3=1 :Element 1 Query OFm1? <terminator> Response example OF1,3,1 OFD/OFD? Initializes communication output items for normal measurement/queries the current settings. Two sets of default setting are available. Syntax OFD m <terminator> "m" indicates default no. m= 0 : Default for normal measurement 1 : Default for integration 2 : Select mode (possible only for inquiry command) Query OFD? <terminator> **Response example** OFD1 Description • Select mode (OFD2) is validated automatically when the OF command is executed if "m" is set to "0" (default for normal measurement) or "1" (default for integration).

Output Format for Measured/Computed Data

Data Output Format

The data format is the same as that described in Appendix 1.4 "Data Output Format". Refer to page App 1-17.

Output Format

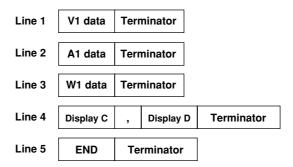
Up to 14 measured/computed data can be output simultaneously, and the user is allowed to choose any output items. Each output block is of the following format.

Line 1	ch.1	,	ch.2	,	ch.3	,	ch.4	Terminator
Line 2	ch.5	,	ch.6	,	ch.7	,	ch.8	Terminator
Line 3	ch.9	,	ch.10	,	ch.11	,	ch.12	Terminator
Line 4	ch.13	,	ch.14	Те	rminator]		
Line 5	ne 5 END Terminator				1			

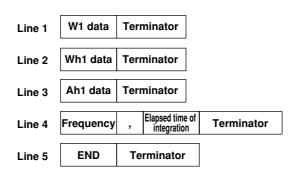
Each output block normally consists of 5 lines including the block end line ("END"). However, if all output items on a line are set to "no output", this line will be omitted, reducing the number of output lines to 4. For instance, if all output items (ch.9 to ch.12) are set to "no output", line 3 will be omitted.

Furthermore, if any output item on a line is set to "no output", all data following this item on the line will be shifted forward. For instance, if ch.2 on line 2 is set to "no output", ch.1 will be followed immediately by the data for ch.3.

Output Format when Default for Normal Measurement is Selected (DFD0)



Output Format when Default for Integration is Selected (DFD1)



Output Format for Harmonic Analysis Data

Data Output Format

The data format is the same as that described in Appendix 1.4 "Data Output Format". Refer to page App 1-18.

Output Format

The output format is specified as shown below according to the output items selected using the OH command.

Voltage or current

Line 1	Total rms value of harmonic from 1st to 50th		,	THD	Terminator
Line 2	Analysis fundame		,	Frequency	Terminator
Line 3	Analysis value for 2nd harmonic			Content for 2nd harmonic	Terminator
Line 51	Analysis value for 50th harmonic		,	Content for 50th harmonic	Terminator
Line 52	END	Terminato	r		

Active power

Line 1	Total rms value of harmonic from 1st to 50th		,	Power factor	Terminator
Line 2		value for ental (1st)	,	Frequency	Terminator
Line 3	Analysis value for 2nd harmonic		,	Content for 2nd harmonic	Terminator
		1			
Line 51	Analysis 50th ha	value for armonic	,	Content for 50th harmonic	Terminator
Line 52	END	Terminato	r		

Phase angle

Line 1	Phase angle between fundamentals (1st harmonic) of voltage and current,			Frequency	Terminator
Line 2	Phase angle between fundamental and 2nd harmonic of voltage			Phase angle between fundamental and 2nd harmonic of current	Terminator
Line 3	Phase angle between fundamental and 3rd harmonic of voltage			Phase angle between fundamental and 3rd harmonic of current	Terminator
Line 50	Phase angle between fundamental and 50th harmonic of voltage		,	Phase angle between fundamental and 50th harmonic of current	Terminator
Line 51	END	Terminato	r		

Output order when "ALL" is selected

Output items are output in the order of voltage \rightarrow current \rightarrow active power \rightarrow phase angle \rightarrow END (terminator).

- Each output data is output in the format specified for each output item.
- The END line is not output for each output item. The END line is output only at the end of entire output operation.

Output Format for Set-up Information/Error Codes

Refer to the application examples of the OS and OE commands given in the Appendix 1.2. To see the contents of the displays in these examples, refer also to the description of the commands given in the Appendix 1.2.

Appendix1.7 Sample Programs

Before Programming

Required System

- Computer : IBM PC/AT and compatible system with National Instruments AT-GPIB/TNT IEEE-488.2 board installed
- OS : Quick Basic Version 4.0/4.5

Basic Programming Format

The following shows the structure of a programming command statement.

Command + Parameter + Terminator ASCII codes are used.

Example	DA	2	CR LF
	Command	Parameter	Terminator

Command

Predefined string of 1 to 3 capital letters

Parameter

Numeric values or character string (ASCII code)

Terminator

· GP-IB interface

When this instrument is used as a listener, "CR+LF", "LF" or "EOI" can be used. When this instrument is used as a talker, the terminator set by the DL command will be used. Refer to page App 1-5.

• RS-232-C

Refer to pages 14-12 and App 1-5.

Multi-Command Statement

A single line can contain multiple commands. In this case, make sure that command statements (command + parameter) are separated by a semicolon (;).

Note .

· space or tab between the command and parameter can be omitted.

Query Command

Query commands can easily be identified since "?" is added to the end of the command. Data returned in response to a query command is shown below.

Query command Returned data

DA? \Rightarrow DA1

Numerical Parameter

Floating-point parameters are correct to four decimal places.

Note

When the message of GPIBERR or DVMERR is returned, refer to "NI-488.2 Driver Sample Programs".

Sample Programs

```
'*
'* Sample Program (1) for the WT2000 series
'*
'* Used to set measurement conditions/ranges for normal measurement mode, and read \ast
'* and display the following data each time measured/computed data is updated.
'*
           Voltage (V), current (A), active power (W), voltage frequency (VHz)
14
REM $INCLUDE: 'qbdecl.bas'
  DECLARE SUB gpiberr (msg$)
DECLARE SUB dvmerr (msg$, SPR%)
   CLS
   PRINT
   CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%)
   IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
' Interface clear
   CALL IBCLR(dvm%)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibclr Error")
 set communication command group.
  WRT$ = "CM3"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set measurement condition.
   WRT$ = "HD0;SI1;MV1,0;MA1,0;FL0;SC0;AG0"
   CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set measurement range.
WRT$ = "RV1,6;RA1,7"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
 set the function of frequency to measure.
   WRT$ = "DD7;ED1"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set communication output item.
   WRT$ = "OFD1;TO0;DL0"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' wait for setting.
   FOR I% = 1 TO 10000: NEXT I%
' initialize status byte.
   WRT$ = "IM1"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' clear status byte.
   CALL IBRSP(dvm%, SPR%)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrsp Error")
   FOR 1% = 1 TO 10
      'wait finished measurement.
SBWAIT: MASK% = &H4800
                                             ' RQS + TIMO
         CALL IBWAIT(dvm%, MASK%)
         IF (IBSTA% AND (EERR OR TIMO)) THEN CALL gpiberr("Ibwait Error")
         CALL IBRSP(dym%, SPR%)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrsp Error")
IF ((SPR% AND &H41) <> &H41) GOTO SBWAIT
      'send request measurement data.
         WRT$ = "OD"
CALL IBWRT(dvm%, WRT$)
         IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
      'read measurement data.
RDDAT:
         RD\$ = SPACE\$(128)
         CALL IBRD(dvm%, RD$)
         IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
PRINT LEFT$(RD$, IBCNT% - 2)
IF LEFT$(RD$, 3) <> "END" GOTO RDDAT
   NEXT I%
  Call the IBONL function to disable the hardware and software.
   CALL IBONL(dvm%, 0)
END
```

```
'* Sample Program (2) for the WT2000 series
'*
'* Used to carry out integration in standard integration mode, and read
'* and display the following data each time measured/computed data is updated.
'* Active power (W), watt-hour (Wh, Wh+, Wh-), ampere-hour (Ah, Ah+, Ah-),
'* elapsed time of integration (IMTEG-TIME)
'*
1.8
    REM $INCLUDE: 'qbdecl.bas'
    DECLARE SUB gpiberr (msg$)
DECLARE SUB dvmerr (msg$, spr%)
    CLS
    PRINT
    CALL ibdev(0, 1, 0, T10s, 1, 0, dvm%)
IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
' clear the device.
CALL ibclr(dvm%)
    IF (ibsta% AND EERR) THEN CALL gpiberr("Ibclr Error")
  set communication command group.
    wrt$ = "CM3"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set measurement condition.
    wrt$ = "HD0;MV1,0;M1,0;FL0;SC0;AG0"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
  set measurement range.
    wrt$ = "RV1,6;RA1,7"
CALL ibwrt(dvm%, wrt$)
    IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set Integrate condition.
    Wrt$ = "IC0;TM1,0"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
  set communication output item.
    wrt$ = "OFD2;OF7,0;TO0;DL0"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' wait for setting.
    FOR i% = 1 TO 10000: NEXT i%
' initialize status byte.
 wrt$ = "IM3"
 CALL ibwrt(dvm%, wrt$)
    IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
    CALL ibrsp(dvm%, spr%)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibrsp Error")
' start integrate.
    wrt$ = "IS"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
  wait finished measurement.
SBWAIT:
mask% = &H4800
                                                       ' RQS + TIMO
    CALL ibwait(dvm%, mask%)
    IF (ibsta% AND (EERR OR TIMO)) THEN CALL gpiberr("Ibwait Error")
CALL ibrsp(dvm%, STB%)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibrsp Error")
    IF ((STB% AND &H41) <> &H41) THEN GOTO INTEGEND
' send request measurement data.
    wrt$ = "OD"
CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
  read measurement data.
RDDAT:
    rd\$ = SPACE\$(512)
    Idv = bird(dvm8, rd$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibrd Error")
    PRINT LEFT$(rd$, ibcnt% - 2)
    IF LEFT$(rd$, 3) <> "END" GOTO RDDAT
INTEGEND:
    IF ((STB% AND &H42) <> &H42) THEN GOTO SBWAIT
    Call the IBONL function to disable the hardware and software.
    CALL ibonl(dvm%, 0)
END
```

```
' *
'* Sample Program (3) for the WT2000 series
'*
'* Used to read and display the following data in harmonic analysis mode.
'* Total rms value of each harmonic from 1st to 50th of current.
'* analysis value of fundamental (1st) of current, analysis value of each harmonic
'* (2nd to 50th), harmonic distortion of current, PLL source (voltage) frequency
'*
REM $INCLUDE: 'qbdecl.bas'
   DECLARE SUB gpiberr (msg$)
  DECLARE SUB dvmerr (msg$, spr%)
  CLS
  PRINT
   CALL ibdev(0, 1, 0, T10s, 1, 0, dvm%)
   IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
' clear the device.
  CALL ibclr(dvm%)
   IF (ibsta% AND EERR) THEN CALL gpiberr("Ibclr Error")
' set communication command group.
  wrt$ = "CM3"
CALL ibwrt(dvm%, wrt$)
   IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set harmonic measurement condition.
  wrt$ = "PS1;AF0;DF0;HO50"
   CALL ibwrt(dvm%, wrt$)
   IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' harmonic measurement start.
wrt$ = "HA1"
   CALL ibwrt(dvm%, wrt$)
   IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set communication output item.
   wrt$ = "OHD0;OH2,1;OH17,1;OH7,1;TO0;DL0"
  CALL ibwrt(dvm%, wrt$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' wait for setting.
FOR I = 1 TO 1000000: NEXT I
' harmonic measurement hold and request measurement data.
   wrt$ = "HD1"
   CALL ibwrt(dvm%, wrt$)
   IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
   wrtS = "OD"
  CALL ibwrt(dvm%, wrt$)
  IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' read measurement data.
RDDAT:
   rd$ = SPACE$(1024)
  CALL ibrd(dvm%, rd$)
IF (ibsta% AND EERR) THEN CALL gpiberr("Ibrd Error")
   PRINT LEFT$(rd$, ibcnt% - 2)
   IF LEFT$(rd$, 3) <> "END" GOTO RDDAT
' start harmonic measurement.
   wrt$ = "HD0"
  CALL ibwrt(dvm%, wrt$)
  IF (ibsta% AND EERR) THEN CALL gpiberr("Ibwrt Error")
  Call the IBONL function to disable the hardware and software.
  CALL ibonl(dvm%, 0)
END
```

```
' *
'* Sample Program (4) for the WT2000 series
'*
'* Used to set measurement conditions/ranges for normal measurement mode, and read
'* and display the following data each time measured/computed data is updated.
'* Binary data: voltage (V), current (A), active power (W), voltage frequency (VHz)
' *
'*******
                                *****
   REM $INCLUDE: 'qbdecl.bas'
   DECLARE SUB gpiberr (msg$)
   DECLARE SUB dvmerr (msg$, SPR%)
   CLS
   PRINT
   DIM DT(4)
   CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%)
IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
' clear the device.
   CALL IBCLR(dvm%)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibclr Error")
' set communication command group.
   WRTS = "CM3"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set measurement condition.
   WRT$ = "HD0;SI1;MV1,0;MA1,0;FL0;SC0;AG0"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set measurement range.
   WRT$ = "RV1,6;RA1,7
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set the function of frequency to measure.
WRT$ = "DD7;ED1"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' set communication output item.
   WRT$ = "OFD1;TO1"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
' wait for setting.
  FOR I% = 1 TO 10000: NEXT I%
' initialize status byte.
   WRT$ = "IM1"
   CALL IBWRT(dvm%, WRT$)
   IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
   CALL IBRSP(dvm%, SPR%)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrsp Error")
   FOR I = 1 TO 10
       wait finished measurement.
SBWAIT: MASK% = &H4800
                                             ' RQS + TIMO
         CALL IBWAIT(dvm%, MASK%)
         IF (IBSTA% AND (EERR OR TIMO)) THEN CALL gpiberr("Ibwait Error")
         CALL IBRSP(dvm%, STB%)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrsp Error")
         IF ((STB% AND &H41) <> &H41) THEN GOTO SBWAIT
      'send request measurement data.
         WRT$ = "OD"
CALL IBWRT(dvm%, WRT$)
         IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       'read measurement data.
         RD$ = SPACE$(512)
         CALL IBRD(dvm%, RD$)
         IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
```

```
N = 0
                                  FOR J = 1 TO 16 STEP 4
                                                                   P\$ = MID\$(RD\$, J + 3, 1): SP = CVI(P\$ + CHR\$(0))

Q\$ = MID\$(RD\$, J + 2, 1): SQ = CVI(Q\$ + CHR\$(0))
\begin{array}{rcl} QS &= \mbox{ min}_{S}(KDS, \ J + 2, \ 1): \ SQ &= \ CVI(QS + \ CHRS(0)) \\ RS &= \ MIDS(RDS, \ J + 1, \ 1): \ SR &= \ CVI(RS + \ CHRS(0)) \\ TS &= \ MIDS(RDS, \ J + 0, \ 1): \ SS &= \ CVI(TS + \ CHRS(0)) \\ TS &= \ RIGHTS("0" + \ HEXS(SS), \ 2) + \ RIGHTS("0" + \ HEXS(SR), \ 2) + R \\ IGHTS("0" + \ HEXS(SQ), \ 2) + \ RIGHTS("0" + \ HEXS(SP), \ 2) \\ FOR \ K &= \ 1 \ TO \ 8 \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MIDS(TRC, \ V = \ V \\ SS(V) &= \ MID
                                                                                                    A$(K) = MID$(T$, K, 1)
                                                                                                    IF A$(K) = "0" THEN B$(K) = "0000"
IF A$(K) = "1" THEN B$(K) = "0001"
                                                                                                    IF A_{3}(K) = 1 THEN B_{3}(K) = 0001
IF A_{3}(K) = "2" THEN B_{3}(K) = "0010"
IF A_{3}(K) = "3" THEN B_{3}(K) = "0011"
                                                                                                    IF A$(K) = "4" THEN B$(K) = "0100"
                                                                                                    IF A$(K) = "5" THEN B$(K) = "0101"
                                                                                                    If A_{\xi}(K) = "6" THEN B_{\xi}(K) = "0101"
IF A_{\xi}(K) = "6" THEN B_{\xi}(K) = "0110"
IF A_{\xi}(K) = "7" THEN B_{\xi}(K) = "0111"
                                                                                                    IF A_{S}(K) = "S" THEN B_{S}(K) = "1000"
IF A_{S}(K) = "9" THEN B_{S}(K) = "1001"
IF A_{S}(K) = "A" THEN B_{S}(K) = "1010"
                                                                                                    IF A_{k}(K) = "B" THEN B_{k}(K) = "1010"
IF A_{k}(K) = "B" THEN B_{k}(K) = "1011"
IF A_{k}(K) = "C" THEN B_{k}(K) = "1100"
                                                                                                    IF A_{S}(K) = 0 THEN B_{S}(K) = 1100
IF A_{S}(K) = "D" THEN B_{S}(K) = "1101"
IF A_{S}(K) = "E" THEN B_{S}(K) = "1110"
IF A_{S}(K) = "F" THEN B_{S}(K) = "1111"
                                                                   NEXT K
                                                                    B = B = (1) + B = (2) + B = (3) + B = (4) + B = (5) + B = (6) + B = (7) + B = (8) 
  U = 0: E = 0: F = 0 
                                                                   U = VAL(LEFT$(B$, 1))
                                                                   E$ = MID$(B$, 2, 8)
FOR L = 0 TO 7
                                                                                                    E = E + (2 \land L) * VAL(MID$(E$, (8 - L), 1))
                                                                   NEXT L
                                                                   W$ = MID$(B$, 10, 23)
                                                                   FOR M = 1 TO 23
F = F + (2 \land (-M)) * VAL(MID$(W$, M, 1))
                                                                   NEXT M
                                                                   \begin{array}{l} DT(N) = ((-1) \ ^{\circ} U) \ ^{\ast} (2 \ ^{\circ} (E \ -127)) \ ^{\ast} F \\ IF \ DT(N) \ < 1E-12 \ THEN \ DT(N) \ = \ 0 \\ N \ = \ N \ + \ 1 \end{array} 
                                                                   F = F + 1
                                  NEXT J
                                 PRINT "MEASURE DATA"
                                 PRINT "ELEMENT1 : ", DT(0), DT(1), DT(2)
PRINT "FREQUENCY: ", DT(3)
                                  PRINT
              NEXT I
            Call the IBONL function to disable the hardware and software.
              CALL IBONL(dvm%, 0)
```

END

Appendix 2.1 IEEE 488.2-1987 Specifications

The GP-IB interface provided with this instrument conforms to IEEE 488.2-1987. This standard requires the following 23 points be stated in this document. This Appendix describes these points.

(1)Subsets supported by IEEE 488.1 interface functions

Refer to page 11-1.

(2)Operation of device when the device is assigned to an address other than addresses 0 to 30

The instrument does not allow assignment to an address other than 0 to 30.

(3)Reaction when the user changes the address

The current address is changed when a new address is set using the INTERFACE key. The newly set address is valid until another new address is set.

(4)Device set-up at power ON. Commands which can be used at power ON

Basically, the previous settings (i.e. the settings which were valid when power was turned OFF) are valid. All commands are available at power ON.

(5)Message transmission options

(a)Input buffer size

1024 bytes

(b)Queries which return multiple response messages

Refer to Appendix 2.3, "Commands".

(c)Queries which generate response data during analysis of the syntax

Every query generates a response data when analysis of the syntax is completed.

(d)Queries which generate response data during reception

No query generates response data when the query is received by the controller.

(e)Commands consisting of parameters which restrict one other

None

(6)Options included in command function elements and composite header elements

Refer to Appendix 2.2 and 2.3.

(7)Buffer size which affects transmission of block data

During transmission of block data, the output queue is extended according to the size of the data blocks.

(8)List of program data elements which can be used in equations, and nesting limit

Refer to the description of the commands given in Appendix 2.3.

(9)Syntax of response to queries Refer to the description of the commands given in Appendix 2.3.(10)Communications between devices which do not follow the response syntax No response syntax is followed in any communication mode other than those specified in IEEE 488.2-1987 (refer to page 14-6). (11)Size of data block of response data 0 to 4900 bytes (12)List of supported common commands Refer to Section 2.3.17, "Common Command Group". (13)Condition of device when calibration is successfully completed *CAL? is not supported. (14)Maximum length of block data which can be used for definition of *DDT trigger macro Not supported (15)Maximum length of macro label used in definition of macro, maximum length of block data which can be used for definition of macro, processing when recursion is used in definition of macro Macro functions are not supported. (16) Response to *IDN? Refer to Section 2.3.17, "Common Command Group". (17)Size of storage area for protected user data for *PUD and *PUD? *RDT and *RDT? are not supported. (18)Length of *RDT and *RDT? resource name *RDT and *RDT? are not supported. (19)Change in status due to *RST, *LRN?, *RCL and*SAV *RST Refer to Section 2.3.17, "Common Command Group" *LRN?, *RCL, *SAV These commands are not supported. (20) Execution range of self-test using the *TST? Refer to Section 2.3.17, "Common Command Group" (21)Structure of extended return status Refer to Appendix 2.4. (22)To find out whether each command is performed in parallel or sequentially Refer to Appendix 2.2.6, "Synchronization with the

Refer to Appendix 2.2.6, "Synchronization with the Controller" and to 2.3.

(23) Description of execution of each command

Refer to the description of each command given in Appendix 2.3 and to their corresponding chapters.

Appendix

Appendix 2.2 Program Format

2.2.1 Syntax Symbols

Symbols which are used in the syntax descriptions in Appendix 2.3 are shown below. These symbols are referred to as BNF notation (Backus-Nour Form). For detailed information, refer to pages App 2-6 to 2-7.

Symbo	Description		Example	Example
<>	Defined value	ELEM	ENT <x> <x>=1~3</x></x>	ELEMENT3
{}	{}One of the options	MODE	$\{ RMS MEAN DC \}$	MODE RMS
	in{} is selected.			
Ι	Exclusive OR	MODE	$\{ RMS MEAN DC \}$	MODE RMS
[]	[] Abbreviated		ing[:STATe] { <e< th=""><th>Boolean>}</th></e<>	Boolean>}
	Repeatable			

2.2.2 Messages

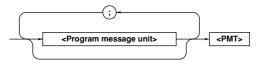
Messages

Blocks of message data are transferred between the controller and this instrument during communications. Messages sent from the controller to the instrument are called program messages, and messages sent back from the instrument to the controller are called response messages.

If a program message contains a query command, i.e. a command which requests a response, the instrument returns a response message. A single response message is always returned in reply to a program message.

Program Messages

As explained above, the data (message) sent from the controller to the instrument is called a program message. The format of a program message is shown below.



<Program message unit>

A program message consists of zero or more program message units; each unit corresponds to one command. The instrument executes commands one by one according to the order in which they are received.

Program message units are delimited by a ";".

For a description of the program message format, refer to the next section.

Example :CONFIGURE:VOLTAGE:RANGE 100V;MODE RMS <PMT>



<PMT>

PMT is a terminator used to terminate each program message. The following three types of terminator are available.

The following three	types of terminator are available.
NL (New Line)	: Same as LF (Line Feed). ASCII code
	"0AH" is used.
^END	: END message defined in IEEE488.1.
	(EOI signal)
	(The data byte sent with an END
	message will be the final item of the
	program message.)
NL^END	: NL with an END message attached
	(NL is not included in the program
	message.)

Program message unit format

The format of a program message unit is shown below.

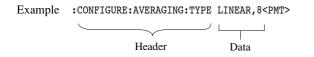


<Program header>

A program header is used to indicate the command type. For details, refer to page App 2-4.

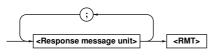
<Program data>

If certain conditions are required for the execution of a command, program data must be added. Program data must be separated from the header by a space (ASCII code "20H"). If multiple items of program data are included, they must be separated by a "," (comma).



Response Message

The data returned by the instrument to the controller is called a response message. The format of a response message is shown below.



<Response message units>

A response message consists of one or more response message units: each response message unit corresponds to one response.

Response message units are delimited by a ";".

For the response message format, refer to the next section.

Example : SAMPLE:RATE 0.500E+00;HOLD 0<RMT>

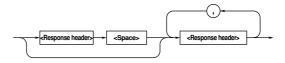


<RMT>

RMT is the terminator used for every response message. Only one type of response message is available; NL^END.

Response message unit format

The format of a program message unit is shown below.



<Response header>

A response header sometimes precedes the response data. Response data must be separated from the header by a space. For details, refer to page App 2-6.

<Response data>

Response data is used to define a response. If multiple items of response data are used, they must be separated by a "," (comma).

Example 500.0E-03<RMT>

:CONFIGURE:VOLTAGE:MODE:ELEMENT1 RMS<RMT>



If a program message contains more than one query, responses are made in the same order as the queries. Normally, each query returns only one response message unit, but there are some queries which return more than one response message unit. The first response message unit always responds to the first query, but it is not always true that the 'n'th unit always responds to the 'n'th query. Therefore, if you want to make sure that a response is made to each query, the program message must be divided up into individual messages.

Points to Note when Sending/Receiving Messages

- If the previous message contained a query, it is not possible to send another program message until a response message has been received.
- An error will occur if a program message is sent before a response message has been received in its entirety. A response message which has not been received will be discarded.
- If an attempt is made by the controller to receive a response message, even if there is no response message, an error will occur. An error will also occur if the controller makes an attempt to receive a response message before transmission of a program message has been completed.
- If a program message of more than one unit is sent and some of the units are incomplete, the instrument receives program message units which the instrument thinks complete and attempts to execute them. However, these attempts may not always be successful and a response may not always be returned, even if the program message contains queries.

Dead Lock

The instrument has a buffer memory in which both program and response messages of 1024 bytes or more can be stored. (The number of bytes available will vary depending on the operating state of the instrument.) If both buffer memories become full at the same time, the instrument becomes inoperative. This state is called dead lock. In this case, operation can be resumed by discarding the response message.

No dead lock will occur, if the size of the program message including the PMT is kept below 1024 bytes. Furthermore, no dead lock will occur if the program message does not contain a query.

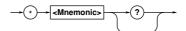
2.2.3 Commands

Commands

There are three two of command (program header) which can be sent from the controller to the instrument. They differ in the format of their program headers.

Common Command Header

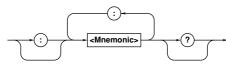
Commands defined in IEEE 488.2-1987 are called common commands. The header format of a common command is shown below. An asterisk (*) must always be attached to the beginning of a command.



An example of a common command :*CLS

Compound Header

Commands designed to be used only with the instrument are classified and arranged in a hierarchy according to their function. The format of a compound header is illustrated below. A colon (:) must be used when specifying a lowerlevel header.



An example of a compound header

:CONFIGURE:VOLTAGE:MODE:ELEMENT1 RMS

Note

• A mnemonic is a character string made up of alphanumeric characters.

When Concatenating Commands Command Group

A command group is a group of commands which have the same compound header. A command group may contain sub-groups.

Example Commands relating to integration

INTEGrate? INTEGrate:MODE INTEGrate:RTIMe? INTEGrate:RTIMe:STARt INTEGrate:RTIMe:STOP INTEGrate:TIMer INTEGrate:POLarity INTEGrate:STARt INTEGrate:STOP INTEGrate:RESet

When Concatenating Commands of the Same Group

This instrument stores the hierarchical level of the command which is currently being executed, and performs analysis on the assumption that the next command to be sent will also belong to the same level. Therefore, it is possible to omit the header if the commands belong to the same group.

Example DISPLAY1:FUNCTION V;ELEMENT 1<PMT>

When Concatenating Commands of Different Groups

A colon (:) must be included before the header of a command, if the command does not belong to the same group as the preceding command.

Example DISPLAY1:FUNCTION V;:SAMPLE:HOLD ON<PMT>

When Concatenating Common Commands

Common commands defined in IEEE 488.2-1987 are independent of hierarchical level. Thus, it is not necessary to add a colon (:) before a common command.

Example DISPLAY1:FUNCTION V;*CLS:ELEMENT 1<PMT>

• When Separating Commands with <PMT>

If a terminator is used to separate two commands, each command is a separate message. Therefore, the common header must be typed in for each command even when commands of the same command group are being concatenated.

Example DISPLAY1:FUNCTION V<PMT>DISPLAY1:ELEMENT 1<PMT>

Upper-level Query

An upper-level query is the highest-level command of a group to which a question mark is appended. Execution of an upperlevel query allows all a group's settings to be output at once. Some query groups comprising more than three hierarchical levels can output all their lower level settings.

Example SAMPLE?<PMT> \rightarrow

:SAMPLE:RATE 0.500E+00;HOLD 0

In reply to an upper-level query, a response can be returned as a program message to the instrument.

Header Interpretation Rules

The instrument interprets the header received according to the following rules.

- Mnemonics are not case sensitive.
- Example "FUNCtion" can be written as "function" or "Function".
- The lower-case part of a header can be omitted.
- Example "FUNCtion" can be written as "FUNCT" or "FUNC".
- If the header ends with a question mark, the command is a query. It is not possible to omit the question mark.
- Example "FUNCtion?" cannot be abbreviated to anything shorter than "FUNC?".
- If the "x" at the end of a mnemonic is omitted, it is assumed to be "1".
- Example If "ELEMent<x>" is written as "ELEM", this represents "ELEMent1".

• Any part of a command enclosed by [] can be omitted.

Example [CONFigure]:SCALing[:STATe] ON can be written as SCAL ON.

However, a part enclosed by [] cannot be omitted if is located at the end of an upper-level query.

Example "SCALing?" and "SCALing:STATe?" belong to different query levels.

2.2.4 Response

On receiving a query from the controller, the instrument returns a response message to the controller. A response message is sent in one of the following two forms.

- Response consisting of a header and data If the query can be used as a program message without any change, a command header is attached to the query, which is then returned.
- Example INTEGRATE:MODE?<PMT>→ :INTEGRATE:MODE NORMAL<RMT>
- Response consisting of data only

If the query cannot be used as a program message unless changes are made to it (i.e. it is a query-only command), no header is attached and only the data is returned. Some query-only commands can be returned after a header is attached to them.

Example STATUS:ERROR?<PMT> → 0, "NO ERROR"<RMT>

· When returning a response without a header

It is possible to remove the header from a response consisting of a header and data. The "COMMunicate:HEADer" command is used to do this.

Abbreviated form

Normally, a response header is returned with the lower-case part removed. It is also possible to return a response header in full form, without the lower-case part removed. The "COMMunicate:VERBose" command is used to do this. The part enclosed by [] is also omitted in the abbreviated form.

2.2.5 Data

Data

A data section comes after the header. A space must be included between the header and the data. The data contains conditions and values. Data is classified as below.

Data	Description
<decimal></decimal>	Decimal number
(Example	PT ratio setting \rightarrow CONFigure:SCALing:PT 100)
<voltage></voltage>	Physical value
<time><frequ< td=""><td>iency></td></frequ<></time>	iency>
(Example	Voltage range \rightarrow CONFigutre:VOLTage:RANGe 150V)
<register></register>	Register value expressed as either binary,
	octal, decimal or hexadecimal
(Example	Extended event register value →STATus:EESE #HFE)
<character data<="" td=""><td>a> Specified character string(mnemonic).</td></character>	a> Specified character string(mnemonic).
	Can be selected from { }.
(Example	Measuring mode \rightarrow CONFigure:MODE {RMS MEAN DC}
<boolean></boolean>	Indicates ON/OFF. Set to ON, OFF or value
(Example	Averaging $ON \rightarrow CONFigure:AVERaging[:STATe] ON$
<character stri<="" td=""><td>ng data> Arbitrary character string</td></character>	ng data> Arbitrary character string
(Example	Character string expressing time \rightarrow INTEGrate:TIMer
	"100:00")
<block data=""></block>	Arbitrary 32 bit data
(Example	Response to measured/computed data \rightarrow
	#40012ABCDEFGHIJKL)

<Decimal>

<Decimal> indicates a value expressed as a decimal number, as shown in the table below. Decimal values are given in the NR form specified in ANSI X3. 42-1975.

Symbol	Description	Example
<nr1></nr1>	Integer	125 -1 +1000
<nr2></nr2>	Fixed point number	125.090 +001.
<nr3></nr3>	Floating point number	125.0E+0 -9E-1 +.1E4
<nrf></nrf>	Any of the forms <nr1> to <n< td=""><td>R3> is allowed.</td></n<></nr1>	R3> is allowed.

- Decimal values which are sent from the controller to the instrument can be sent in any of the forms <NR1> to <NR3>. In this case, <NRf> appears.
- For response messages which are returned from the instrument to the controller, the form (<NR1> to <NR3> to be used) is determined by the query. The same form is used, irrespective of whether the value is large or small.
- In the case of <NR3>, the "+" after the "E" can be omitted, but the "-" cannot.
- If a value outside the setting range is entered, the value will be normalized so that it is just inside the range.
- If the value has more than the significant number of digits, the value will be rounded.
- <Voltage>, <Current>, <Frequency>, <Time> <Voltage>, <Current>, <Frequency> and <Time> indicate decimal values which have physical significance. <Multiplier> or <Unit> can be attached to <NRf>. They can be entered in any of the following forms.

can be entered in any of the following forms.					
Example					
5MV					
5E-3V					
5M					
5E-3					

<Multiplier>

Multipliers which can be used are	e shown below
-----------------------------------	---------------

Symbol	Word	Description		
EX	Exa	1018		
PE	Peta	1015		
Т	Tera	1012		
G	Giga	109		
MA	Mega	106		
К	Kilo	10 ³		
М	Milli	10-3		
U	Micro	10-6		
N	Nano	10-9		
Р	Pico	10-12		
F	Femto	10 ⁻¹⁵		

<Unit>

Units which can be used are shown below. Symbol Word Description

Symbol Word		Description	
v	Volt	Voltage	
А	Ampere	Current	
HZ	Hertz	Frequency	
MHZ	Megahertz	Frequency	
S	Second	Time (second)	

• <Multiplier> and <Unit> are not case sensitive.

- "U" is used to indicate "μ".
- "MA" is used for Mega (M) to distinguish it from Milli, except for in the case of Milli ampere and Megahertz, which is expressed as "MA" and "MHZ". Hence, it is not permissible to use "M" (Milli) for Hertz.
- If both <Multiplier> and <Unit> are omitted, the fundamental unit (V, A, HZ, S) will be used.
- Response messages are always expressed in <NR3> form. Neither <Multiplier> nor <Unit> is used.

<Register>

<Register> indicates an integer, and can be expressed in hexadecimal, octal or binary as well as a decimal number. <Register> is used when each bit of a value has a particular meaning. <Register> is expressed in one of the following forms.

Form	Example
<nrf></nrf>	1
#H <hexadecimal made="" of<="" td="" up="" value=""><td>#H0F</td></hexadecimal>	#H0F
the digits 0 to 9 and A to F>	
#Q <octal 0="" 7="" digits="" made="" of="" the="" to="" up="" value=""></octal>	#q777
<pre>#B<binary 0="" 1="" and="" digits="" made="" of="" the="" up="" value=""></binary></pre>	#B001100

• <Register> is not case sensitive.

• A response message is always <NR1>.

<Character Data>

<Character data> is a specified string of character data (a mnemonic). It is mainly used to indicate options, and is chosen from the character strings given in { }. For interpretation rules, refer to "Header Interpretation Rules" on page App 2-6.

Form	Example
{RMS MEAN DC }	RMS

- As with a header, the "COMMunicate:VERBose" command can be used to select whether a response message is returned in its full form or abbreviated form.
- "COMMunicate:HEADer" does not affect <character data>.

<Boolean>

<Boolean> is data which indicates ON or OFF, and is expressed in one of the following forms.

Form	Exar	nple			
{ON OFF <nrf>}</nrf>	ON	OFF	1	0	

- When <Boolean> is expressed in <NRf> form, OFF is selected if the rounded integer value is "0" and ON is selected if the rounded integer is "Not 0".
- A response message is always "1" if the value is ON and "0" if it is OFF.

<Character String Data>

<Character string data> is not a specified character string like <character data>. It is an arbitrary character string. A character string must be enclosed in single quotation marks (') or double quotation marks ('').

Form	Example
<character data="" string=""></character>	'ABC' "IEEE488.2-1987"

- If a character string contains a double quotation mark ("), the double quotation mark will be replaced by two concatenated double quotation marks (" "). This rule also applies to a single quotation mark within a character string.
- A response message is always enclosed by double quotation marks (").
- <Character string data> is an arbitrary character string, therefore the instrument assumes that the remaining program message units are part of the character string if no single (') or double quotation mark (") is encountered. As a result, no error will be detected if a quotation mark is omitted.

<Block data>

<Block data> is arbitrary 32-bit data. On the instrument, <Block data> is only used for response messages. Block data is expressed in the following form.

Form	Example
#4<4-digit decimal value> <data byte="" string=""></data>	#40012ABCDEFGHIJKL

• #4

Indicates that the data is <Block data>.

- <4-digit decimal value> Indicates the number of bytes of data. (0012 = 12 bytes)
- <Data byte string> The actual data. (ABCDEFGHIJKL)
- Data is comprised of 32-bit values (0 to 4294967295). This means that the ASCII code "0AH", which stands for "NL", can also be a code used for data. Hence, care must be taken when programming the controller.

Appendix

2.2.6 Synchronization with the Controller

There are two kinds of command; overlap commands and sequential commands. Overlap commands, which are allowed to be executed before execution of the previously sent command is completed, are not supported by this instrument. In the case of sequential commands, which are supported by this instrument, the instrument delays execution of a command until execution of the previously sent command is completed. However, synchronization is sometimes required for correct inquiry for measured data, even if a sequential command is used.

For instance, if a program message is sent when an inquiry about measured data is made immediately after the voltage range is changed, the "MEASure:VALue?" command will be executed whether update of the measured data has been completed or not and no data is displayed ("-----" is displayed instead), possibly causing "9.91E+37 (Not A Number)" to be output.

[CONFigure:]VOLTage:RANGe[:ALL]
60V;:MEASure:VALue?<PMT>

In this case, synchronization with the time at which update of measured data is completed must be accomplished, as shown on the next page.

• Using STATus:CONDition? query

A "STATUS: CONDition?" query is used to make an inquiry about the contents of the condition register (page App 2-55). It is possible to judge whether update of measured data is in progress or not by reading bit 0 of the condition register. Bit 0 is "1" if update is in progress, and "0" if update is stopped therefore making an inquiry is possible.

· Using the extended event register

Changes in the condition register are reflected in the extended event register (page App 2-55).

Example STATUS:FILTer1 FALL;:STATUS:EESE 1;EESR?;*SRE8;[:CONFigure]:VOLTage :RANGe[:ALL]60V<PMT> (Service request is awaited.) MEASure:VALue?<PMT>

"STATUS:FILTer1 FALL" indicates that the transit filter is set so that bit 0 (FILTer1) is set to "1" when bit 0 of the condition register is changed from "1" to "0".

"STATUS: EESE 1" is a command used to reflect the status of bit 0 of the extended event register in the status byte.

"STATUS: EESR?" is used to clear the extended event register.

The "*SRE" command is used to generate a service request caused solely by the extended event register.

"MEASure:VALue?" will not be executed until a service request is generated.

Using the COMMunicate:WAIT command

The "COMMunicate:WAIT" command halts communications until a specific event is generated.

Example STATUS:FILTer1 FALL;:STATUS:EESR?
;[:CONFigure]:VOLTage:RANGe
[:ALL] 60V<PMT>
(Response to STATUS:EESR? is decoded.)
COMMunicate:WAIT 1;:MEASure
:VALue?<PMT>

For a description of "STATUS:FILTEr FALL" and "STATUS:EESR?", refer to "Using the extended event register" on this page.

"COMMunicate:WAIT 1" means that communications is halted until bit 0 of the extended event register is set to "1". "MEASure:VALue" will not be executed until bit 0 of the extended event register is set to "1".

2.3 Commands

2.3.1 Command List

AOUTput Group :AOUTput?	Quarias all the summent D/A sutmut sottings	
-	Over $\beta = \beta + $	
A OTHER STATE AND A STATE AND	Queries all the current D/A output settings.	App 2-14
:AOUTput:HARMonics?	Queries all the current D/A output item settings for harmonic analysis mode.	App 2-14
:AOUTput:HARMonics:CHANnel <x></x>	Sets D/A output items for the specified channel for harmonic analysis	App 2-15
	mode /queries the current setting.	
-	Sets D/A output items for harmonic analysis mode at once.	App 2-15
AOUTput:NORMal?	Queries all the current D/A output item settings for normal measurement mode.	App 2-15
:AOUTput:NORMal:CHANnel <x></x>	Sets D/A output items for the specified channel for normal measurement mode/queries the current setting.	App 2-15
:AOUTput:NORMal:IRTime	Sets the rated integration time for D/A output of integrated values /queries the current setting.	App 2-15
:AOUTput:NORMal:PRESet	Sets D/A output items for normal measurement mode at once.	App 2-15
COMMunicate Group		
:COMMunicate?	Queries all the communications settings.	App 2-16
	Determines whether a header is to be added or not.	App 2-16
:COMMunicate:LOCKout	Turns the local lock out function ON or OFF.	App 2-16
:COMMunicate:REMote	Selects remote mode or local mode.	App 2-16
:COMMunicate:STATus?	Queries the current network status.	App 2-17
	Determines whether a response to a query is to be returned in full form	App 2-17
	or in abbreviated form/queries the current setting.	
	Waits until one of the specified extended event occurs.	App 2-17
COMMunicate:WAIT?	Generates a response when one of the specified extended events occurs.	App 2-17
CONFigure Group		
:CONFigure?	Queries all the measurement condition settings.	App 2-20
:CONFigure]:AVERaging?	Queries all the averaging function settings.	App 2-20
	Turns the averaging function ON or OFF/queries the current setting.	App 2-20
:CONFigure]:AVERaging:TYPE	Sets the averaging type/queries the current setting.	App 2-20
:CONFigure]:CFACtor	Sets the crest factor/queries the current setting.	App 2-20
:CONFigure]:CURRent?	Queries all the current measurement settings	App 2-20
:CONFigure]:CURRent:AUTO?	Queries the auto range settings for the current range.	App 2-20
	Sets current auto range ON or OFF.	App 2-20
:CONFigure]:CURRent:AUTO:ELEMent <x></x>	Sets current auto range ON or OFF/queries the current setting.	App 2-21
:CONFigure]:CURRent:ESCaling?	Queries external sensor scaling constant for each element.	App 2-21
:CONFigure]:CURRent:ESCaling[:ALL] :CONFigure]:CURRent:ESCaling:ELE	Sets external sensor scaling constant. EMent <x></x>	App 2-21
	Sets external sensor scaling constant/queries the current setting.	App 2-21
[:CONFigure]:CURRent:MODE?	Queries current measurement mode.	App 2-21
:CONFigure]:CURRent:MODE[:ALL]	Sets current measurement mode.	App 2-21
:CONFigure]:CURRent:MODE:ELEMent <x></x>	Sets current measurement mode/queries the current setting.	App 2-21
:CONFigure]:CURRent:RANGe?	Queries current range.	App 2-21
:CONFigure]:CURRent:RANGe[:ALL] :CONFigure]:CURRent:RANGe:ELEMer		App 2-21
	Sets current range/queries the current setting.	App 2-21
:CONFigure]:DEGRee	Sets phase angle display method/queries the current setting	App 2-22
:CONFigure]:FILTer?	Queries the current line filter setting.	App 2-22 App 2-22
:CONFigure]:FILTer:CUToff	Sets line filter cut-off frequency/queries the current setting.	App 2-22 App 2-22
	Turns the line filter ON or OFF/queries the current setting.	App 2-22 App 2-22
:CONFigure]:FREQuency?	Queries the current frequency setting.	App 2-22 App 2-22
	Turns the frequency filter ON or OFF/queries the current setting.	App 2-22 App 2-22
:CONFigure]:NULL?	Queries all the NULL function settings.	App 2-22 App 2-22
	Turns the NULL function ON or OFF/queries the current setting.	App 2-22 App 2-22
:CONFigure]:PHOLd?	Queries all the peak hold settings.	App 2-22 App 2-22
:CONFigure]:PHOLd:FUNCtion	Sets the peak hold function/queries the current setting.	App 2-22 App 2-22
	Turns the peak hold function ON or OFF/queries the current setting.	App 2-22 App 2-22
:CONFigure]:SCALing?	Queries all the current scaling function settings.	App 2-22 App 2-22
	Queries an me current scaling runchon settings. Queries the current scaling constant (voltage, current, power) for each element.	App 2-22 App 2-22
:CONFigure]:SCALing:{PT CT SFACtor}:	tor}[:ALL]	
	Sets scaling constant (voltage, current, power).	App 2-22

Appendix

Appendix 2.3 Commands

Command	Function Ret	erence Pa
:CONFigure]:SCALing:{PT CT SFAC	tor}:ELEMent <x></x>	
	Sets scaling constant (voltage, current, power).	App 2-23
:CONFigure]:SCALing[:STATe]	Turns the scaling function ON or OFF/queries the current setting.	App 2-23
:CONFigure]:VOLTage?	Queries all the voltage measurement settings.	App 2-23
:CONFigure]:VOLTage:AUTO?	Queries the auto range settings for the voltage range.	App 2-23
:CONFigure]:VOLTage:AUTO[:ALL]	Sets voltage auto range ON or OFF. Sets voltage auto range ON or OFF/queries the current setting.	App 2-23 App 2-23
:CONFigure]:VOLTage:AUTO:ELEMent <x> :CONFigure]:VOLTage:MODE?</x>	Queries voltage measurement mode.	App 2-23 App 2-23
:CONFigure]:VOLTage:MODE[:ALL]	Sets voltage measurement mode.	App 2-23
:CONFigure]:VOLTage:MODE:ELEMent <x></x>	•	App 2-23
:CONFigure]:VOLTage:RANGe?	Queries voltage range.	App 2-23
:CONFigure]:VOLTage:RANGe[:ALL]		App 2-23
:CONFigure]:VOLTage:RANGe:ELEMent <x></x>	Sets voltage range/queries the current setting.	App 2-23
:CONFigure]:WIRing	Sets wiring system/queries the current setting.	App 2-24
DISPlay Group		
DISPlay <x>?</x>	Queries all the current display settings for the specified display.	App 2-24
DISPlay <x>:ELEMent</x>	Sets the element to be displayed/queries the current setting.	App 2-24
DISPlay <x>:FUNCtion</x>	Sets the function to be displayed/queries the current setting.	App 2-24
LICker Group		
FLICker?	Queries all the flicker measurement settings.	App 2-26
FLICker:COUNt	Sets the number of times measurement of short-term flicker value Pst is to be performed/queries the current setting.	App 2-26
FLICker:DC?	Queries all the relative steady-state voltage change (dc) settings.	App 2-26
FLICker:DC:LIMit	Sets the limit for relative steady-state voltage change (dc) settings.	••
FLICker:DC[:STATe]	Sets judgment ON or OFF for relative steady-state voltage change dc/queries the current setting	
FLICker:DISPlay?	Queries all the flicker measurement display settings.	App 2-27
FLICker:DISPlay:ELEMent	Sets the element to be displayed during flicker measurement mode/queries the current setting.	App 2-27
FLICker:DISPlay:FUNCtion	Sets the function to be displayed during flicker measurement mode/queries the current setting	App 2-27
FLICker:DISPlay:PERiod	Sets the flicker observation period no. (display A) for flicker measurement/	App 2-27
	queries the current setting.	
FLICker:DMAX?	Queries all the maximum relative voltage change dmax settings.	App 2-27
FLICker:DMAX:LIMit	Sets the limit for maximum relative voltage change dmax/queries the current setting.	App 2-27
FLICker:DMAX [:STATe]	Sets judgment ON or OFF for maximum relative voltage change dmax/queries the current setting	App 2-27
FLICker:DIMIN?	Queries all the steady-state range dmin settings.	App 2-27
FLICker:DIMIN:LIMit	Sets the limit for steady-state range dmin/queries the current setting.	App 2-27
FLICker:DT?	Queries all the settings regarding the period d (t) $_{200 \text{ ms}}$ during which	App 2-27
	voltage exceeds the threshold level within one voltage fluctuation.	
FLICker:DT:LIMit	Sets the limit for the period d (t) $_{200 \text{ ms}}$ during which relative voltage change	App 2-27
	exceeds the threshold level during a voltage fluctuation/queries the current setting.	
FLICker:DT:[:STATe]	Sets judgment ON or OFF for the period d (t) $_{200 \text{ ms}}$ during which relative voltage	App 2-28
	change exceeds the threshold level during a voltage fluctuation/queries the current	setting.
FLICker:ELEMent <x></x>	Sets the element for which flicker measurement is to be performed/queries the current setting.	App 2-28
FLICker:INITialize	Initializes measurement of voltage fluctuation.	App 2-28
FLICker:INTerval	Sets the time required for measurement of short-term flicker value Pst/queries the current setting,	App 2-28
FLICker:PLT?	Queries all the long-term flicker value Plt settings/queries the current setting.	App 2-28
FLICker:PLT:LIMit	Sets the limit for long-term flicker value Plt/queries the current setting.	App 2-28
FLICker:PLT:NVALue	Sets N value for long-term flicker value Plt (constant used in Plt equation)/	App 2-28
FLICKEL FLI INVALUE	queries the current setting.	Арр 2-20
FLICker:PLT[:STATe]	Sets judgment ON or OFF for long-term flicker value Plt/queries the current setting.	App 2-28
FLICker:PST?	Queries all the short-term flicker value Pst settings/queries the current setting.	App 2-28
FLICker:PST:LIMit	Sets the limit for short-term flicker value Pst/queries the current setting.	App 2-28
FLICker:PST[:STATe]	Sets judgment ON or OFF for short-term flicker value Pst/queries the current setting.	
FLICker:STARt	Starts measurement of voltage fluctuation.	App 2-28
FLICker[:STATe]	Turns flicker measurement mode ON or OFF/queries the current setting.	App 2-28
FLICker:STOP	Stops measurement of voltage fluctuation.	
		App 2-29
FLICker:UN?	Queries all the nominal voltage Un settings.	App 2-29
FLICker:UN:MODE	Sets the acquisition method for nominal voltage Un/queries the current setting.	App 2-29
FLICker:UN:VALue	Sets the existing value for nominal voltage Un/queries the current setting.	App 2-29

Command	Function Re	eference Page
HARMonics Group		
:HARMonics?	Queries all the harmonic analysis settings.	App 2-30
:HARMonics:DISPlay?	Queries all the display settings for harmonic analysis.	App 2-30
:HARMonics:DISPlay:MODE	Sets display mode for harmonic analysis items to be displayed on display B/queries the current setting.	App 2-30
HARMonics:DISPlay:ORDer	Sets harmonic order to be displayed on display A/queries the current setting.	App 2-31
:HARMonics:FILTer	Turns anti-aliasing filter for harmonic analysis ON or OFF/queries the current setting.	App 2-31
HARMonics:ORDer	Sets the maximum harmonic order for harmonic analysis /queries the current setting.	App 2-31
HARMonics[:STATe]	Turns harmonic analysis mode ON or OFF/queries the current setting.	App 2-31
HARMonics:SYNChronize	Sets the input to be used as the fundamental frequency for PLL	App 2-31
HARMonics:THD	Synchronization/queries the current setting.	App 2-31
HARMonics:WINDow	Sets the window width for harmonic analysis/queries the current setting.	App 2-31
NTEGrate Group		
:INTEGrate?	Queries all the integration settings.	App 2-32
:INTEGrate:MODE	Sets integration mode/queries the current setting.	App 2-32
INTEGrate:POLarity	Sets polarity of integrated values to be displayed on display D/queries the current setting.	App 2-32
INTEGrate:RESet	Resets integrated values.	App 2-32
:INTEGrate:RTIMe?	Queries the integration start and stop time for real time counting.	App 2-32
INTEGrate:RTIMe:STARt	integration mode Sets the integration start time for real time counting integration mode	App 2-33
	/queries the current setting.	
:INTEGrate:RTIMe:STOP	Sets the integration stop time for real time counting integration mode /queries the current setting.	App 2-33
:INTEGrate:STARt	Starts integration.	App 2-33
:INTEGrate:STOP	Stops integration.	App 2-33
:INTEGrate:TIMer	Sets integration timer preset time/queries the current setting.	App 2-33
MATH Group		
MATH?	Queries all the computation settings.	App 2-34
MATH: ARIThmetic	Sets equation for four arithmetical operations/queries the current setting.	App 2-34
MATH:CFACtor MATH:TYPE	Sets equation for crest factor/queries the current setting. Sets computation type/queries the current setting.	App 2-34 App 2-34
MEASure Group		
:MEASure?	Queries all the settings for measured/computed data for communication output.	App 2-36
:MEASure:FLICker:CPF <x>?</x>	Queries the CPF (cumulative probability function) data obtained during the	App 2-36
	previous flicker observation period.	ripp 2 50
	1 I	
MEASure:FLICker:JUDGe <x>?</x>	Queries the judgment result data for each flicker observation period.	App 2-36
MEASure:FORMat	Sets communication output format for measured/computed data /queries the current setting.	App 2-36
MEASure:ITEM?	Queries all the communication output items settings for measured/computed data	App 2-36
:MEASure:ITEM:FLICker? :MEASure:ITEM:FLICker <flicker mea<="" td=""><td>Queries all the communication output items for flicker measurement. asurement function>?</td><td>APP 2-37</td></flicker>	Queries all the communication output items for flicker measurement. asurement function>?	APP 2-37
:MEASure:ITEM:FLICker <flicker mea<="" td=""><td>Queries the communication output ON/OFF for the specified flicker measurement function</td><td>n. App 2-37</td></flicker>	Queries the communication output ON/OFF for the specified flicker measurement function	n. App 2-37
	Turns communication output for the specified flicker measurement function ON or OFF.	App 2-37
:MEASure:ITEM:FLICker <flicker mea<="" td=""><td></td><td></td></flicker>		
	Turns communication output for the specified flicker measurement function ON or OFF.	App 2-37
:MEASure:ITEM:FLICker:TIME	Turns communication output of the elapsed time of voltage fluctuation measurement ON or OFF/queries the current setting.	App 2-37
MEASure:ITEM:FLICker:PRESet	Turns communication output ON or OFF for all the flicker measurement functions at once	App 2-37
:MEASure:ITEM:HARMonics? :MEASure:ITEM:HARMonics: <harmonic< td=""><td>Queries all the communication output items for harmonic analysis mode.</td><td>App 2-37</td></harmonic<>	Queries all the communication output items for harmonic analysis mode.	App 2-37
	Queries the communication output ON/OFF for the specified harmonic analysis function.	App 2-37
:MEASure:ITEM:HARMonics:{ <harmon:< td=""><td>ic analysis function>}[:ALL]</td><td>Am= 2,29</td></harmon:<>	ic analysis function>}[:ALL]	Am= 2,29
	Turns communication output for the specified harmonic analysis function ON or OFF.	App 2-38
	GN 01 011.	
:MEASure:ITEM:HARMonics: <harmonic< td=""><td></td><td>App 2-38</td></harmonic<>		App 2-38

Appendix 2.3 Commands

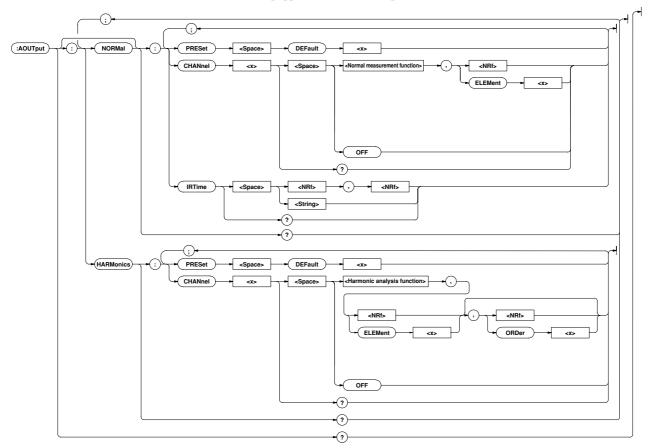
Command		erence Pag
MEASure:ITEM:HARMonics:SYNChronize	Turns communication output for PLL source ON or OFF/queries the current setting.	
MEASure:ITEM:HARMonics:PRESet	Turns communication output ON or OFF for all the harmonic analysis functions at once.	
MEASure:ITEM:NORMal?	Queries all the communication output items for normal measurement data.	App 2-38
MEASure:ITEM[:NORMal]: <normal m<="" td=""><td></td><td>• • • • •</td></normal>		• • • • •
	Queries the communication output ON/OFF for the specified normal measurement function.	App 2-38
MEASure:ITEM[:NORMal]: <normal m<="" td=""><td></td><td>Ann 2 20</td></normal>		Ann 2 20
	Turns communication output ON or OFF for the specified normal measurement	App 2-38
MEACume . IMENI . NODNell . «Newmell m	<pre>function. easurement function >:ELEMent<x></x></pre>	
MEASURE:ITEM[:NORMAI]: <normai< td=""><td>Turns communication output ON or OFF for the specified normal measurement</td><td>App 2-38</td></normai<>	Turns communication output ON or OFF for the specified normal measurement	App 2-38
	function.	App 2-36
MEASure:ITEM[:NORMal]:{TIME FRE		
MEASULE: ITEM[:NORMAI]: {ITME FRE	Turns communication output ON or OFF for the normal measurement functions	App 2-39
	(elapsed time of integration, frequency, computation)/queries the current setting.	11pp 2 37
MEASure:ITEM[:NORMal]:PRESet	Sets communication output items for normal measurement mode to the	App 2-39
	preset settings at once.	11pp 2 37
MEASure:VALue?	Queries the normal measurement data for the items which are set to ON using	App 2-39
minoure. viniae.	MEASure:ITEM commands ("MEASure:ITEM:FLICker?" through	ripp 2 37
	"MEASure:ITEM[:NORMal]:PRESet").	
RINt Group		
PRINt?	Queries all the current built-in printer settings.	App 2-45
PRINt:ABORt	Stops printing.	App 2-45
PRINt:AUTO?	Queries all the current auto print mode settings.	App 2-45
PRINt:AUTO:INTerval	Sets print interval for auto print mode/queries the current setting.	App 2-45
PRINt:AUTO:STARt	Sets start time for auto print mode/queries the current setting.	App 2-45
PRINt:AUTO[:STATe]	Turns auto print mode ON or OFF/queries the current setting.	App 2-45
PRINt:AUTO:STOP	Sets stop time for auto print mode/queries the current setting.	App 2-45
PRINt:AUTO:SYNChronize	Sets print synchronization method for auto print mode/queries the current setting.	App 2-46
PRINt:FEED	Feeds print paper.	App 2-46
PRINt:ITEM?	Queries all the printer settings for measured/computed data.	App 2-46
PRINt:ITEM:FLICker?	Queries all the printer output items for flicker measurement.	App 2-46
PRINt:ITEM:FLICker:CPF?	Queries the CPF graph print data output ON/OFF.	App 2-46
PRINt:ITEM:FLICker:CPF[:ALL]	Turns printer output of CPF graph ON or OFF.	App 2-46
PRINt:ITEM:FLICker:CPF:ELEMent <x></x>	Turns printer output of CPF graph ON or OFF/queries the current setting.	App 2-46
PRINt:ITEM:FLICker:JUDGe?	Queries the printer output ON/OFF for flicker meter judgment result table.	App 2-46
<pre>PRINt:ITEM:FLICker:JUDGe[:ALL]</pre>	Turns printer output of flicker meter judgment result table ON or OFF for all the elements at once.	App 2-46
PRINt:ITEM:FLICker:JUDGe:ELEMent <x></x>	Turns printer output of flicker meter judgment result table ON or OFF/queries	App 2-46
	the current setting.	
PRINt:ITEM:FLICker:PRESet	Turns printer output ON or OFF for all the flicker measurement functions at once.	App 2-46
PRINt:ITEM:HARMonics?	Queries all the print output items for harmonic analysis data.	App 2-46
PRINt:ITEM:HARMonics: <harmonic< td=""><td>analysis function>?</td><td></td></harmonic<>	analysis function>?	
	Queries the printer output ON/OFF for the specified harmonic analysis print function.	App 2-47
RINt:ITEM:HARMonics: <harmonic a<="" td=""><td></td><td></td></harmonic>		
	Turns printer output for the specified harmonic analysis print function ON or OFF.	App 2-47
RINt:ITEM:HARMonics: <harmonic a<="" td=""><td></td><td></td></harmonic>		
	Turns printer output for the specified harmonic analysis print function ON	App 2-47
	or OFF/queries the current setting.	
PRINt:ITEM:HARMonics:PRESet	Turns printer output ON or OFF for all the harmonic analysis print functions at once.	App 2-47
PRINt:ITEM:NORMal?	Queries all the printer output items for normal measurement data.	App 2-47
PRINt:ITEM:NORMal: <normal measu<="" td=""><td></td><td></td></normal>		
	Queries the printer output ON/OFF for the specified normal measurement function.	App 2-48
PRINt:ITEM:NORMal: <normal measu<="" td=""><td>rement function >[:ALL]</td><td></td></normal>	rement function >[:ALL]	
	Turns printer output for the specified normal measurement function ON or OFF.	App 2-48
PRINt:ITEM:NORMal: <normal measu<="" td=""><td>rement function>:ELEMent<x></x></td><td></td></normal>	rement function>:ELEMent <x></x>	
	Turns printer output for the specified normal measurement function ON or OFF	App 2-48
	/queries the current setting.	
PRINt:ITEM:NORMal:{TIME FREQuen	cy MATH}	
	Turns printer output ON or OFF for the computed elapsed time of integration,	App 2-48
	frequency and efficiency/queries the current setting.	
PRINt:ITEM:NORMal:PRESet	Turns printer output ON or OFF for all the normal measurement functions at once.	App 2-48
PRINt:PANel	Prints panel set-up information.	App 2-48
PRINt:VALue	Prints peaced of the information. Prints measured/computed data for the items which are set to ON using	App 2-48
	The second	-rr =

Command	Function	Reference Page
RECall Group		
RECall:PANel	Recalls set-up information from the specified file of the internal memory.	App 2-49
SAMPle Group		
:SAMPLe?	Queries all the current sampling settings.	App 2-49
:SAMPLe:HOLD	Turns hold mode for output data (display, communication data) ON and	
	ON/queries the current setting.	App 2-49
:SAMPLe:RATE	Sets sample rate/queries the current setting.	App 2-49
STATus Group		
:STATus?	Queries all the settings relating to the communications status function.	App 2-50
:STATus:CONDition?	Queries the contents of the condition register.	App 2-50
:STATus:EESE	Sets the extended event enable register/queries the current setting.	App 2-50
:STATus:EESR?	Queries the contents of the extended event register and clears the register.	App 2-50
:STATus:ERRor?	Queries the code and the message (at the beginning of the error queue)	
	of the error which has occurred.	App 2-50
:STATus:FILTer <x></x>	Queries all the settings relating to the specified transit filter/queries the	
	current settings.	App 2-51
:STATus:QMESsage	Selects whether or not to add the message contents to a response to	
	"STATus:ERRor?" /queries the current setting.	App 2-51
:STATus:SPOLl?(Serial Poll)	Executes serial poll.	App 2-51
STORe Group		
:STORe:PANel	Stores set-up information in the internal memory.	App 2-51
SYSTem Group		
:SYSTem?	Queries all the system (internal clock) settings.	App 2-52
:SYSTem:DATE	Sets the date/queries the current setting.	App 2-52
:SYSTem:TIME	Sets the time/queries the current setting.	App 2-52
Common Command Group		
*CLS	Clears the standard event register, extended event register and error queue.	App 2-53
*ESE	Sets the value for the standard event enable register/queries the current setting.	App 2-53
*ESR?	Queries the value of the standard event register and clears it at the same time.	App 2-53
*IDN?	Queries the instrument model.	App 2-53
*OPC	(Not supported by this instrument.)	App 2-53
*OPC?	("1" will always be returned since overlap commands are not supported by	
	this instrument.)	App 2-54
*OPT?	Queries installed options.	App 2-54
*PSC	Selects whether or not to clear the registers when power is turned ON/	
	queries the current setting.	App 2-54
*RST	Resets the current settings.	App 2-54
*SRE	Sets the value of the service request enable register/queries the current setting.	App 2-54
*STB?	Queries the value of the status byte register.	App 2-54
*TRG	Carries out the same function as when the TRIG key (SHIFT + HOLD) is pressed.	App 2-54
*TST?	Executes a self-test and queries the test result.	App 2-54
*WAI	(Not supported by this instrument.)	App 2-54

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2.3.2 AOUTput Group

The commands in the AOUTput group are used to make settings relating to and inquire about D/A output. This allows you to make the same settings and inquiries which can be made using the MISC key ("dA-out" menu and "itG-t" menu) on the front panel. These commands are available if the instrument is equipped with the D/A output function (/DA model).



AOUTput?

Function Queries all the current D/A output settings. **Syntax** AOUTput?

Syntax AOUTput?

Example AOUTPUT? →:AOUTPUT:NORMAL:CHANNEL1 V,1;CHANNEL2
 OFF;CHANNEL3 OFF;CHANNEL4 OFF;CHANNEL5
 A,1;CHANNEL6 OFF;CHANNEL7 OFF;CHANNEL8
 OFF;CHANNEL9 W,1;CHANNEL10 OFF;CHANNEL11
 OFF;CHANNEL12 OFF;CHANNEL13 W,1;CHANNEL14
 W,1;IRTIME 1,0;:AOUTPUT:HARMONICS:CHANNEL1
 A,1,1;CHANNEL2 A,1,2;CHANNEL3 A,1,3;CHANNEL4
 A,1,4;CHANNEL5 A,1,5;CHANNEL6 A,1,6;CHANNEL7
 A,1,7;CHANNEL8 A,1,8;CHANNEL9 A,1,9;CHANNEL10
 A,1,10;CHANNEL11 A,1,11;CHANNEL12 A,1,12;CHANNEL
 13 A,1,13;CHANNEL14 SYNCHRONIZE

AOUTput:HARMonics?

Function Queries all the current D/A output item settings for harmonic analysis mode.

Syntax AOUTput:HARMonics?

```
Example AOUTPUT: HARMONICS? →: AOUTPUT: HARMONICS: CHANNEL1
```

```
A,1,1;CHANNEL2 A,1,2;CHANNEL3 A,1,3;CHANNEL4
A,1,4;CHANNEL5 A,1,5;CHANNEL6 A,1,6;CHANNEL7
A,1,7;CHANNEL8 A,1,8;CHANNEL9 A,1,9;CHANNEL10
A,1,10;CHANNEL11 A,1,11;CHANNEL12 A,1,12;CHANNEL
13 A,1,13;CHANNEL14 SYNCHRONIZE
```

AOUTput:HARMonics:CHANnel<x> Function Sets D/A output items for the specified for harmonic analysis mode /queries the current setting. Syntax AOUTput:HARMonics:CHANnel<x> {<Harmonic analysis</pre> function>, (<NRf>|ELEMent<1>), (<NRf>|ORDer<1-</pre> 50>) | OFF } AOUTput:HARMonics:CHANnel<x>? <x>1 to 14(output channel) <Harmonic analysis function>= $\{V | A | W | VA | VAR | PF | DEG | V$ THD | ATHD | VCON | ACON | WCO N | VDEG | ADEG | SYNChronize } Example AOUTPUT: HARMONICS: CHANNEL1 A, 1, 1 AOUTPUT: HARMONICS: CHANNEL2 ATHD, 1 AOUTPUT: HARMONICS: CHANNEL3 OFF AOUTPUT: HARMONICS: CHANNEL1? →: AOUTPUT: HARMONICS: CHANNEL1 A.1.1 AOUTPUT: HARMONICS: CHANNEL2? →: AOUTPUT: HARMONICS: CHANNEL2 ATHD,1 AOUTPUT:HARMONICS:CHANNEL3? →:AOUTPUT:HARMONICS: CHANNEL3 OFF Description The order is set as follows according to the selected harmonic analysis function. $\{V | A | W\}$: If no order is set, total rms value from 1st to 50th will be selected. {VA | VAR | PF | DEG | VTHD | ATHD}: The order can be omitted, since it is meaningless. {SYNChronize}: The order can be omitted, since they are meaningless. AOUTput:HARMonics:PRESet

- **Function** Sets D/A output items for harmonic analysis mode to the specified default setting at once.
- Syntax AOUTput:HARMonics:PRESet {DEFault<1-2>}
 Example AOUTPUT:HARMONICS:PRESET DEFAULT1
 Description For a description of global setting for {DEFault<1-2>},
 refer to Section 12.3, "D/A Output".

AOUTput:NORMal?

Function Queries all the current D/A output item settings for normal measurement mode.

Syntax AOUTput:NORMal?

Example AOUTPUT:NORMAL? →:AOUTPUT:NORMAL:CHANNEL1
 V,1;CHANNEL2 OFF;CHANNEL3 OFF;CHANNEL4
 OFF;CHANNEL5 A,1;CHANNEL6 OFF;CHANNEL7
 OFF;CHANNEL8 OFF;CHANNEL9 W,1;CHANNEL10
 OFF;CHANNEL11 OFF;CHANNEL12 OFF;CHANNEL13
 W,1;CHANNEL14 W,1;IRTIME 1,0

AOUTput[:NORMal]:CHANnel<x>

Function Sets D/A output items for the specified channel for normal measurement mode/queries the current setting. Syntax AOUTput[:NORMal]:CHANnel<x> {<Normal measurement</pre> function>,(<NRf>|ELEMent<1>)|OFF} AOUTput[:NORMal]:CHANnel<x>? <x>1 to 14(output channel) <Normal measurement function>= {V | A | W | VA | VAR | PF | DEG | VPK APK WH WHP WHM AH AHP A HM | FREQuency | TIME } Example AOUTPUT:NORMAL:CHANNEL1 V,1 AOUTPUT:NORMAL:CHANNEL2 FREQUENCY AOUTPUT:NORMAL:CHANNEL3 OFF AOUTPUT:NORMAL:CHANNEL1? →:AOUTPUT:NORMAL: CHANNEL1 V,1 AOUTPUT:NORMAL:CHANNEL2? →:AOUTPUT:NORMAL: CHANNEL2 FREQUENCY AOUTPUT:NORMAL:CHANNEL3? →:AOUTPUT:NORMAL: CHANNEL3 OFF Description The element is set as follows according to the selected normal measurement function. {FREQuency | TIME}: The element can be omitted, since it is meaningless. AOUTput[:NORMal]:IRTime Function Sets the rated integration time for D/A output of integrated values/queries the current setting.

Syntax AOUTput[:NORMal]:IRTime {<NRf>,<NRf>|<Character
 string>}

AOUTput[:NORMal]:IRTime?

{<NRf>,<NRf>}= 0,1 to 999,59

```
{<Character string>}="HHH:MM" HHH:Hour
MM:Miniute
```

Example AOUTPUT:NORMAL:IRTIME 1,0

AOUTPUT:NORMAL:IRTIME "1:00"

AOUTPUT:NORMAL:IRTIME? →:AOUTPUT:NORMAL:IRTIME 1,0

AOUTput[:NORMal]:PRESet

Function Sets D/A output items for normal measurement mode to the specified default setting at once.

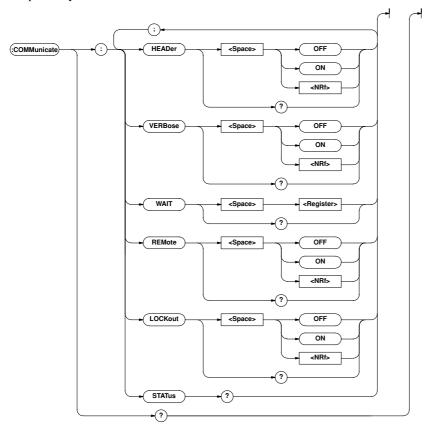
Syntax AOUTput[:NORMal]:PRESet {DEFault<1-2>}

Example AOUTPUT:NORMAL:PRESET DEFAULT1

Description For a description of global setting for {DEFault<1-2>}, refer to Section 12.3, "D/A Output".

2.3.3 COMMunicate Group

The commands in the COMMunicate group are used to make settings relating to and inquire about communications. There is no front panel key for this function.



COMMunicate?

Function Queries all the communications settings.
Syntax COMMunicate?

Example COMMUNICATE?

→:COMMUNICATE:HEADER 1;VERBOSE 1

COMMunicate:HEADer

Function Determines whether a header is added(example: CONFIGURE:VOLTAGE:RANGE:ELEMENT1 150.0E +00) or not (example:150.0E+00) when sending a response to a query/queries the current setting.

Syntax COMMunicate:HEADer {<Boolean>}
COMMunicate:HEADer?

Example COMMUNICATE: HEADER ON COMMUNICATE: HEADER?→:COMMUNICATE: HEADER 1

COMMunicate:LOCKout

Function Turns the local lock out function ON or OFF.
Syntax COMMunicate:LOCKout {<Boolean>}
COMMunicate:LOCKout?
Example COMMUNICATE:LOCKOUT ON

COMMUNICATE:LOCKOUT?→:COMMUNICATE:LOCKOUT 1 Description This command is available only for the RS-232-C interface.

COMMunicate:REMote

Function Selects remote mode or local mode. Remote mode is selected if
 this command is set to ON.
Syntax COMMunicate:REMote {<Boolean>}

COMMunicate:REMote?

Example COMMUNICATE: REMOTE ON COMMUNICATE: REMOTE?→: COMMUNICATE: REMOTE 1

Description This command is available only for the RS-232-C interface.

COMMunicate:STATus?

Function Queries the current network status.
Syntax COMMunicate:STATus?
Example COMMUNICATE:STATUS?→:COMMUNICATE:STATUS 0
Description Meaning of each bit of the status is given below.

Bit	GP-IB	RS-232-C
0	Transmission error for	Parity error
	non-recoverable 7210	
1	Always set to 0.	Framing error
2	Always set to 0.	Break character
		detection
3 or more	Always set to 0.	Always set to 0.

A status bit is set when its corresponding cause occurs, and cleared when it is read.

COMMunicate:VERBose

- Function Determines whether a response to a query is to be returned full in form (for example:CONFIGURE : VOLTAGE:RANGE:ELEMENT1 150.0E+00) or in abbreviated form (for example:VOLT:RANG:ELEM 150.0E+00)/queries the current setting.
- Syntax COMMunicate:VERBose {<Boolean>}
 COMMunicate:VERBose?

Example COMMUNICATE: VERBOSE ON

COMMUNICATE:VERBOSE?→:COMMUNICATE:VERBOSE 1

COMMunicate:WAIT

Function Waits until one of the specified extended event occurs.
Syntax COMMunicate:WAIT <Register>

<Register>= 0 to 65535(For a description of the extended event register, refer to page App 2-55.)

Example COMMUNICATE:WAIT 65535

Description For a description of synchronization using COMMunicate: WAIT, refer to page App 2-8.

COMMunicate:WAIT?

Function Generates a response when one of the specified extended events occurs.

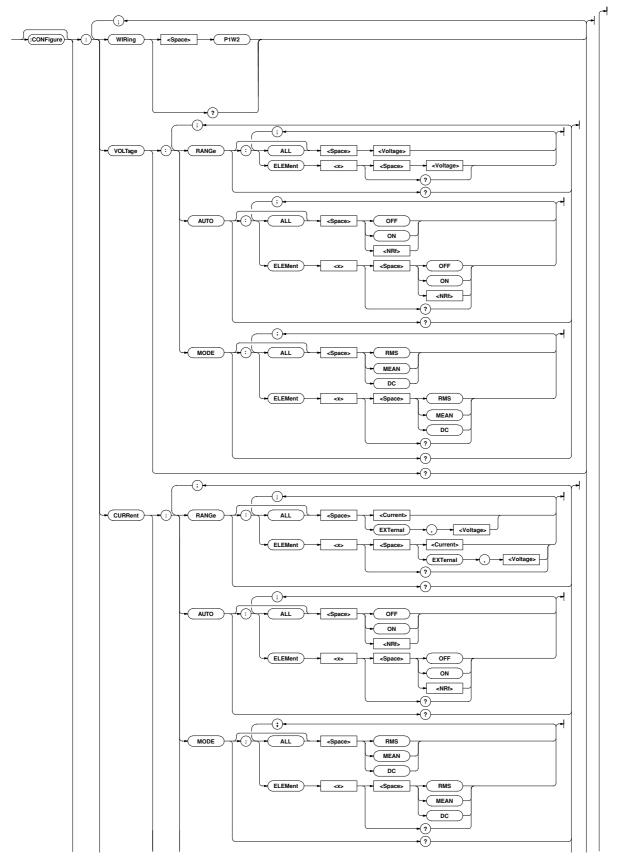
Syntax COMMunicate:WAIT? <Register>

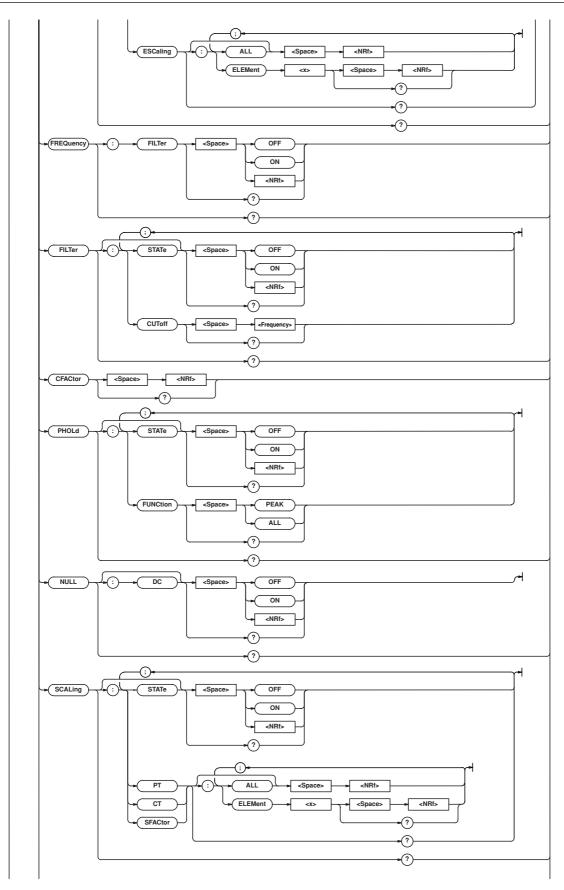
<Register>= 0 to 65535(For a description of the extended event register, refer to page App 2-55.)

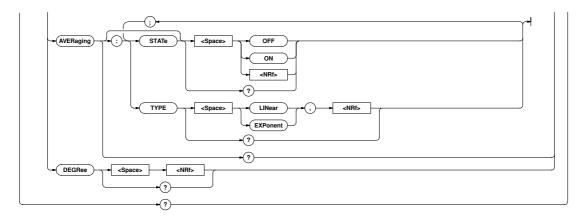
Example COMMUNICATE:WAIT? 65535→1

2.3.4 CONFigure Group

The commands in the CONFigure group are used to make settings relating to and to inquire about measurement conditions. This allows you to make the same settings and inquiries which you can make using the WIRING key, VOLTAGE (CURRENT) RANGE related keys, and LINE FILTER, SCALING, AVG, PEAK HOLD (SHIFT + RATE), CF3/CF6 (SHIFT + \land/\lor), NULL (SHIFT + TRIG) and MISC ("F-FiLt", "HOLd-F" and "dEG" menus) keys on the front panel.







CONFigure?

Function Queries all the measurement condition settings. **Syntax** CONFigure?

Example CONFIGURE ? → : CONFIGURE : WIRING P1W2 ; VOLTAGE:RANGE:ELEMENT1 600.0E+00;:CONFIGURE: VOLTAGE:AUTO:ELEMENT1 0;:CONFIGURE:VOLTAGE: MODE:ELEMENT1 RMS;:CONFIGURE:CURRENT:RANGE: ELEMENT1 30.0E+00;:CONFIGURE:CURRENT:AUTO: ELEMENT1 0;:CONFIGURE:CURRENT:MODE:ELEMENT1 RMS;:CONFIGURE:CURRENT:ESCALING:ELEMENT1 50.000E+00;:CONFIGURE:FREQUENCY:SOURCE V,1; FILTER 0;:CONFIGURE:FILTER:STATE 0;CUTOFF 0.500E+03;:CONFIGURE:CAFACTOR 3;PHOLD:STATE 0;FUNCTION PEAK;:CONFIGURE:NULL:DC 0;:CONFIGURE: SCALING:STATE 0;PT:ELEMENT1 1.0000E+00;:CONFIGURE: SCALING: CT:ELEMENT1 1.0000E+00;:CONFIGURE: SCALING:SFACTOR:ELEMENT1 1.0000E+00;:CONFIGURE: AVERAGING:STATE 0;TYPE EXPONENT,8;:CONFIGURE:DEGREE 180

[:CONFigure]:AVERaging?

Function Queries all the averaging function settings.

- Syntax [CONFigure]:AVERaging?
- Example CONFIGURE:AVERAGING? →:CONFIGURE:AVERAGING:STATE 0;TYPE EXPONENT,8

[:CONFigure]:AVERaging[:STATe]

- Function Turns the averaging function ON or OFF/queries the current setting.
- Syntax [CONFigure]:AVERaging[:STATe] {<Boolean>}
 [CONFigure]:AVERaging:STATe?

```
Example CONFIGURE:AVERAGING:STATE OFF
```

CONFIGURE:AVERAGING:STATE?→:CONFIGURE:AVERAGING :STATE 0

[:CONFigure]:AVERaging:TYPE

Function Sets the averaging type/queries the current setting.

Syntax [CONFigure]:AVERaging:TYPE

{(LINear|EXPonent),<NRf>}

[CONFigure]:AVERaging:TYPE?

{<NRf>}=8,16,32,64,128,256(averaging
 factor)

Example CONFIGURE: AVERAGING: TYPE EXPONENT, 8

CONFIGURE:AVERAGING:TYPE?

 \rightarrow :CONFIGURE:AVERAGING:TYPE EXPONENT,8

[:CONFigure]:CFACtor

Function Sets the crest factor/queries the current setting.

Syntax [CONFigure]:CFACtor {<NRf>}
[CONFigure]:CFACtor?

{<NRf>}=3, 6

Example CONFIGURE:CFACTOR 3 CONFIGURE:CFACTOR?→:CONFIGURE:CFACTOR 3

[:CONFigure]:CURRent?

Function Queries all the current measurement settings.

Syntax [CONFigure]:CURRent?

Example CONFIGURE:CURRENT?→:CONFIGURE:CURRENT:RANGE: ELEMENT1 30.0E+00;:CONFIGURE:CURRENT:AUTO: ELEMENT1 0;:CONFIGURE:CURRENT:MODE:ELEMENT1 RMS;:CONFIGURE:CURRENT:ESCALING:ELEMENT1 50.000E+00

[:CONFigure]:CURRent:AUTO?

Function Queries ON/OFF state of current auto range for each element.
Syntax [CONFigure]:CURRent:AUTO?

Example CONFIGURE:CURRENT:AUTO?→:CONFIGURE:CURRENT:AUTO: ELEMENT1 0

[:CONFigure]:CURRent:AUTO[:ALL]

Function Sets current auto range ON or OFF.

Syntax [CONFigure]:CURRent:AUTO[:ALL] {<Boolean>}
Example CONFIGURE:CURRENT:AUTO:ALL OFF

[:CONFigure]:CURRent:AUTO:ELEMent<x>

Function Sets current auto range ON or OFF/queries the current setting.
Syntax [CONFigure]:CURRent:AUTO:ELEMent<x>

- {<Boolean>}
 [CONFigure]:CURRent:AUTO:ELEMent<x>?
 <x>=1
- Example CONFIGURE:CURRENT:AUTO:ELEMENT1 OFF CONFIGURE:CURRENT:AUTO:ELEMENT1? →:CONFIGURE:CURRENT:AUTO:ELEMENT1 0

[:CONFigure]:CURRent:ESCaling?

Function Queries the external shunt current values.

Syntax [CONFigure]:CURRent:ESCaling?

Example C O N F I G U R E : C U R R E N T : E S C A L I N G ? →:CONFIGURE:CURRENT:ESCALING:ELEMENT1 50.000E+00

[:CONFigure]:CURRent:ESCaling[:ALL]

Function Sets the external shunt current value.

{<NRf>}=0.0200 to 1000.0

Example CONFIGURE:CURRENT:ESCALING:ALL 50.000

Description Scaling constants are rounded as follows.

Below 1.0000 Rounded to four decimal places.

1.0000 to 1000.0 Rounded to five significant digits.

[:CONFigure]:CURRent:ESCaling:ELEMent<x>

Function Sets the external shunt current value/queries the current setting.

Syntax [CONFigure]:CURRent:ESCaling:ELEMent<x> {<NRf>}
 [CONFigure]:CURRent:ESCaling:ELEMent<x>?
 <x>= 1

{<NRf>}=0.0200 to 1000.0

- Example CONFIGURE:CURRENT:ESCALING:ELEMENT1 50.000 CONFIGURE:CURRENT:ESCALING:ELEMENT1? →:CONFIGURE:CURRENT:ESCALING:ELEMENT1 50.000E+00
- **Description** Scaling constants are rounded in the same way as for [CONFigure]:CURRent:ESCaling[:ALL].

[:CONFigure]:CURRent:MODE?

Function Queries current measurement mode.

Syntax [CONFigure]:CURRent:MODE?

Example CONFIGURE:CURRENT:MODE?→:CONFIGURE:CURRENT :MODE:ELEMENT1 RMS

[:CONFigure]:CURRent:MODE[:ALL]

Function Sets current measurement mode.
Syntax [CONFigure]:CURRent:MODE[:ALL] {RMS|MEAN|DC}
Example CONFIGURE:CURRENT:MODE:ALL RMS

[:CONFigure]:CURRent:MODE:ELEMent<x>

Function Sets current measurement mode/queries the current setting.

Syntax [CONFigure]:CURRent:MODE:ELEMent<x>
 {RMS|MEAN|DC}
 [CONFigure]:CURRent:MODE:ELEMent<x>?

<x>=1

Example CONFIGURE:CURRENT:MODE:ELEMENT1 RMS CONFIGURE:CURRENT:MODE:ELEMENT1? →:CONFIGURE:CURRENT:MODE:ELEMENT1 RMS

[:CONFigure]:CURRent:RANGe?

[:CONFigure]:CURRent:RANGe[:ALL]

Function Sets current range (external shunt range).

Syntax [CONFigure]:CURRent:RANGe[:ALL]
 {<Current>|(EXTernal,<Voltage>)}
 <Current>=1A to 30A(1,2,5,10,20,30A)

<Voltage>=50mV to 200mV(50,100,200mV)

Example Setting current range

CONFIGURE:CURRENT:RANGE:ALL 20A

Setting external sensor input range

CONFIGURE:CURRENT:RANGE:ALL EXTERNAL,250MV

[:CONFigure]:CURRent:RANGe:ELEMent<x>

Function Sets current range (external shunt range)/queries the current setting.

```
Syntax [CONFigure]:CURRent:RANGe:ELEMent<x>
    {<Current>|(EXTernal,<Voltage>)}
    [CONFigure]:CURRent:RANGe:ELEMent<x>?
    <x>=1
    <Current>= 1A to 30A (1,2,5,10,20,30A)
```

<Voltage>= 50mV to 200mV(50,100,200mV)

Example Setting/inquiring about current range

CONFIGURE:CURRENT:RANGE:ELEMENT1 30A CONFIGURE:CURRENT:RANGE:ELEMENT1? →:CONFIGURE:CURRENT:RANGE:ELEMENT1 30.0E+00

Setting/inquiring about external sensor input range CONFIGURE: CURRENT: RANGE: ELEMENT1 EXTERNAL, 50MV

CONFIGURE: CURRENT: RANGE: ELEMENT1? →: CONFIGURE: CURRENT: RANGE: ELEMENT1 EXTERNAL, 50.0E-03

Appendix 2.3 Commands

[:CONFigure]:DEGRee

Function Sets phase angle display method/queries the current setting.

Syntax [CONFigure]:DEGRee {<NRf>}
 [CONFigure]:DEGRee?

{<NRf>}=180,360

Example CONFIGURE:DEGREE 180 CONFIGURE:DEGREE?→:CONFIGURE:DEGREE 180

[:CONFigure]:FILTer?

Function Queries the current line filter setting.

Syntax [CONFigure]:FILTer?

Example CONFIGURE:FILTER?→:CONFIGURE:FILTER:STATE 0;CUTOFF 0.500E+03

[:CONFigure]:FILTer:CUToff

Function Sets line filter cut-off frequency/queries the current setting.

Syntax [CONFigure]:FILTer:CUToff {<Frequency>}
 [CONFigure]:FILTer:CUToff?
 <Frequency>= 500HZ,5.5KHZ

Example CONFIGURE:FILTER:CUTOFF 0.5KHZ CONFIGURE:FILTER:CUTOFF?→:CONFIGURE:FILTER: CUTOFF 0.500E+03

[:CONFigure]:FILTer[:STATe]

Function Turns the line filter ON or OFF/queries the current setting.

Syntax [CONFigure]:FILTer[:STATe] {<Boolean>}
 [CONFigure]:FILTer:STATe?
Example CONFIGURE:FILTER:STATE OFF

CONFIGURE:FILTER:STATE?→:CONFIGURE:FILTER: STATE 0

[:CONFigure]:FREQuency?

Function Queries the current frequency setting.

Syntax [CONFigure]:FREQuency?

Example CONFIGURE:FREQUENCY?→:CONFIGURE:FREQUENCY :FILTER 0

[:CONFigure]:FREQuency:FILTer

Function Turns the frequency filter ON or OFF/queries the current setting.

Syntax [CONFigure]:FREQuency:FILTer {<Boolean>}
 [CONFigure]:FREQuency:FILTer?

Example CONFIGURE:FREQUENCY:FILTER OFF CONFIGURE:FREQUENCY:FILTER?→:CONFIGURE: FREQUENCY:FILTER 0

[:CONFigure]:NULL?

Function Queries all the NULL function settings.
Syntax [CONFigure]:NULL?
Example CONFIGURE:NULL:→:CONFIGURE:NULL:DC0

[:CONFigure]:NULL[:DC]

Function Turns the NULL function ON or OFF/queries the current setting.

Syntax [CONFigure]:NULL[:DC] [CONFigure]:NULL:DC?

Example CONFIGURE:NULL:DC OFF CONFIGURE:NULL:DC?→:CONFIGURE:NULL:DC 0

[:CONFigure]:PHOLd?

Function Queries all the peak hold function settings.

Syntax [CONFigure]:PHOLd?

Example CONFIGURE: PHOLD?→:CONFIGURE: PHOLD: STATE 0;FUNCTION PEAK

[:CONFigure]:PHOLd:FUNCtion

Function Sets the peak hold function/queries the current setting.

Syntax [CONFigure]:PHOLd:FUNCtion {PEAK|ALL}

[CONFigure]:PHOLd:FUNCtion?

Example CONFIGURE: PHOLD: FUNCTION PEAK CONFIGURE: PHOLD: FUNCTION→: CONFIGURE:

PHOLD:FUNCTION PEAK

Description

Description of each function is given below.

PEAK : Peak value (Vpk, Apk only)

 $ALL \quad : V, A, W, VA, var, Vpk, Apk$

[:CONFigure]:PHOLd[:STATe]

Function Turns the peak hold function ON or OFF/queries the current setting.

- Syntax [CONFigure]:PHOLd:[STATe] {<Boo|ean>}
 [CONFigure]:PHOLd:STATe?
- Example CONFIGURE: PHOLD:STATE OFF CONFIGURE: PHOLD:STATE?→:CONFIGURE: PHOLD: STATE 0

[:CONFigure]:SCALing?

Function Queries all the current scaling function settings.

Syntax [CONFigure]:SCALing?

Example CONFIGURE:SCALING?→:CONFIGURE:SCALING: STATE 0;PT:ELEMENT1 1.0000E+00;:CONFIGURE: SCALING:CT:ELEMENT1 1.0000E+00;:CONFIGURE: SCALING:SFACTOR:ELEMENT1 1.0000E+00

[:CONFigure]:SCALing:{PT | CT | SFACtor}?

Function Queries the current scaling constant (voltage, current, power).
Syntax [CONFigure]:SCALing:{PT|CT|SFACtor}?
Example CONFIGURE:SCALING:PT?→:CONFIGURE:SCALING:
PT:ELEMENT1 1.0000E+00

[:CONFigure]:SCALing:{PT | CT | SFACtor}[:ALL]

Function Sets scaling constant (voltage, current, power).

Example CONFIGURE:SCALING:PT:ALL 1.0000

Description Scaling constants are rounded as follows.

Below 1.0000 Rounded to four decimal places.

1.0000 to 10000 Rounded to five significant digits.

[:CONFigure]:SCALing:{PT|CT|SFACtor}:ELEMent<x> [:CONFigure]:VOLTage:MODE?

Function Sets scaling constant (voltage, current, power).

Syntax [CONFigure]:SCALing:{PT|CT|SFACtor}: ELEMent<x> {<NRf>}

> [CONFigure]:SCALing:{PT|CT|SFACtor}:ELEMent<x>? <x>=1

{<NRf>}=0.0001 to 10000

- Example CONFIGURE:SCALING:PT:ELEMENT1 1.0000 CONFIGURE:SCALING:PT:ELEMENT1?→:CONFIGURE :SCALING:PT:ELEMENT1 1.0000E+00
- Description Scaling constants are rounded in the same way as for [CONFigure]:SCALing:{PT|CT|SFACtor}[:ALL].

[:CONFigure]:SCALing[:STATe]

- Function Turns the scaling function ON or OFF/queries the current setting
- Syntax [CONFigure]:SCALing[:STATe] {<Boolean>} [CONFigure]:SCALing:STATe?

Example CONFIGURE:SCALING:STATE OFF CONFIGURE:SCALING:STATE?→:CONFIGURE:

SCALING:STATE 0

[:CONFigure]:VOLTage?

Function Queries all the voltage measurement settings.

Syntax [CONFigure]:VOLTage?

Example CONFIGURE: VOLTAGE? →: CONFIGURE: VOLTAGE: RANGE:ELEMENT1 600.0E+00;:CONFIGURE:VOLTAGE: AUTO:ELEMENT1 0;:CONFIGURE:VOLTAGE:MODE:ELEMENT1 RMS

[:CONFigure]:VOLTage:AUTO?

Function Queries ON/OFF state of voltage auto range.

Syntax [CONFigure]:VOLTage:AUTO?

- **Example** CONFIGURE: VOLTAGE: AUTO? →: CONFIGURE:
 - VOLTAGE: AUTO: ELEMENT1 0

[:CONFigure]:VOLTage:AUTO[:ALL]

Function Sets voltage auto range ON or OFF. Syntax [CONFigure]:VOLTage:AUTO[:ALL] {<Boolean>} Example CONFIGURE: VOLTAGE: AUTO: ALL OFF

[:CONFigure]:VOLTage:AUTO:ELEMent<x>

Function Sets voltage auto range ON or OFF/queries the current setting. Syntax [CONFigure]:VOLTage:AUTO:ELEMent<x> {<Boolean>}

> [CONFigure]:VOLTage:AUTO:ELEMent<x>? <x>=1

Example CONFIGURE: VOLTAGE: AUTO: ELEMENT1 OFF CONFIGURE:VOLTAGE:AUTO:ELEMENT1?→:CONFIGURE :VOLTAGE: AUTO: ELEMENT1 0

Function Queries voltage measurement mode. **Syntax** [CONFigure]:VOLTage:MODE? **Example** CONFIGURE: VOLTAGE: MODE?→: CONFIGURE:

VOLTAGE:MODE:ELEMENT1 RMS

[:CONFigure]:VOLTage:MODE[:ALL]

Function Sets voltage measurement mode. **Syntax** [CONFigure]:VOLTage:MODE[:ALL] {RMS | MEAN | DC} Example CONFIGURE: VOLTAGE: MODE: ALL RMS

[:CONFigure]:VOLTage:MODE:ELEMent<x>

Function Sets voltage measurement mode/queries the current setting. Syntax [CONFigure]:VOLTage:MODE:ELEMent<x> {RMS | MEAN | DC } [CONFigure]:VOLTage:MODE:ELEMent<x>? <x>= 1

Example CONFIGURE: VOLTAGE: MODE: ELEMENT1 RMS CONFTGURE: VOLTAGE: MODE: ELEMENT1?→: CONFTGURE CONFIGURE: VOLTAGE: MODE: ELEMENT1 RMS

[:CONFigure]:VOLTage:RANGe?

Function Queries voltage range.

Syntax [CONFigure]:VOLTage:RANGe?

Example CONFIGURE : VOLTAGE : RANGE ? → : CONFIGURE :VOLTAGE:RANGE:ELEMENT1 600.0E+00

[:CONFigure]:VOLTage:RANGe[:ALL]

Function Sets voltage range.

Syntax [CONFigure]:VOLTage:RANGe[:ALL] {<Voltage>} <Voltage>=10V to 600V(10,15,30,60,100, 150,300,600V) Example CONFIGURE: VOLTAGE: RANGE: ALL 1000V

[:CONFigure]:VOLTage:RANGe:ELEMent<x>

Function Sets voltage range/queries the current setting.

Syntax [CONFigure]:VOLTage:RANGe:ELEMent<x> {<Voltage>} [CONFigure]:VOLTage:RANGe:ELEMent<x>? <x>=1 <Voltage>=10V to 600V(10,15,30,60,100,

150,300,600V)

Example CONFIGURE: VOLTAGE: RANGE: ELEMENT1 600V

CONFIGURE: VOLTAGE: RANGE: ELEMENT1?→: CONFIGURE:VOLTAGE:RANGE:ELEMENT1 600.0E+00

ppendix

[:CONFigure]:WIRing

Function Sets wiring system/queries the current setting.

Syntax [CONFigure]:WIRing {P1W2}

```
[CONFigure]:WIRing?
```

```
Example CONFIGURE:WIRING P1W2
```

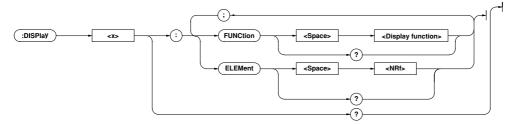
```
CONFIGURE:WIRING?→:CONFIGURE:WIRING P1W2
```

Description

P1W2: 1-phase 2-wire system

2.3.5 DISPlay Group

The commands in the DISPlay group are used to make settings relating to and inquirie about display. This allows you to make the same settings and inquiries which you can make using the FUNCTION key.



DISPlay<x>?

Function Queries all the current display settings for the specified display.
Syntax DISPlay<x>?

```
<x>=1 to 4
1:Display A
2:Display B
3:Display C
```

4:Display D

Example DISPLAY1?→:DISPLAY1:FUNCTION V;ELEMENT 1

DISPlay<x>:ELEMent

Function Sets the element to be displayed/queries the current setting.

Syntax DISPlay<x>:ELEMent {<NRf>}

```
DISPlay<x>:ELEMent?
```

```
{<NRf>}=1
```

Example DISPLAY1: ELEMENT 1

DISPLAY1:ELEMENT?→:DISPLAY1:ELEMENT 1

```
Description To set the element to be displayed during flicker measurement,
use the FLICker:DISPlay:ELEMent command.
```

DISPlay<x>:FUNCtion

Function Sets the function to be displayed/queries the current setting.
Syntax DISPlay<x>:FUNCtion {<Display function>|

DISPlay<x>:FUNCtion? During normal measurement

<Display function>={V|A|W|VA|VAR|PF|DEG|VPK|AP K|VHZ|AHZ|WH|WHP|WHM|AH|AHP |AHM|MATH|TIME}

During harmonic analsysis

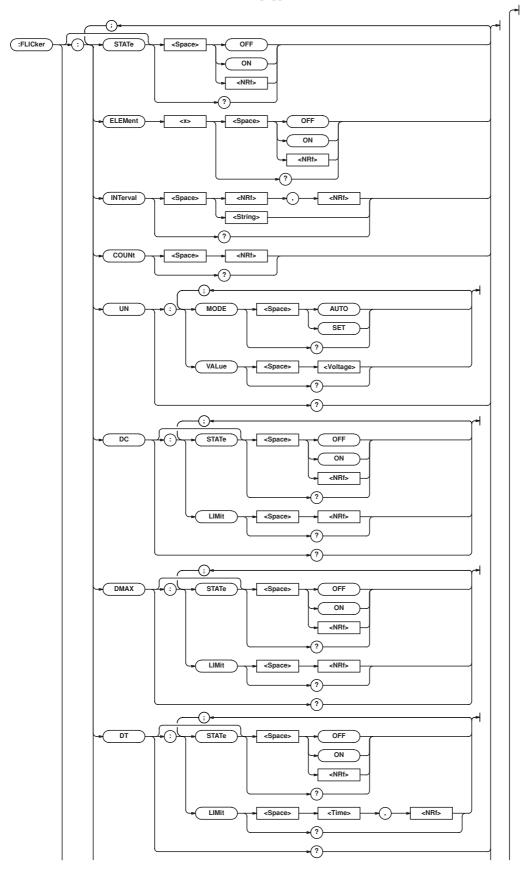
<Display function>= {V |A |W | VA | VAR | PF | DEG | VHZ | AH Z | VTHD | ATHD | VDEG | ADEG}

Example DISPLAY1: FUNCTION V

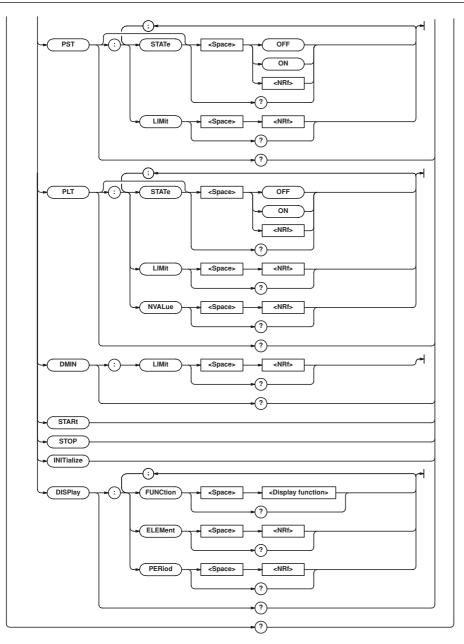
DISPLAY1:FUNCTION?→:DISPLAY1:FUNCTION V Description To set the function to be displayed during flicker measurement, use the FLICker:DISPlay:FUNCtion command.

2.3.6 FLICker Group

The commands in the FLICker Group are used to make settings relating to and inquiring about voltage fluctuation/flicker measurement. This allows you to make the same settings and inquiries which can be made using the FLICKER, START/STOP, INITIAL (SHIFT + START/STOP) and LIMIT (SHIFT + FLICKER) keys of the FLICKER TEST section on the front panel. These commands are available if the instrument is equipped with the flicker measurement function (/FL model).



Appendix



FLICker?

```
Function Queries all the voltage fluctuation/flicker measurement settings.
```

```
Syntax FLICker?
```

```
Example FLICKER?→:FLICKER:STATE 1;ELEMENT1
1;INTERVAL 10,0;COUNT 12;UN:MODE AUTO;
VALUE 2 30.00E+00;:FLICKER:DC:STATE 1;LIMIT
3.00E+00;:FLICKER:DMAX:STATE 1;LIMIT
4.00E+00;:FLICKER:DT:STATE 1;LIMIT
0.200E+00,3.00E+00;:FLICKER:PST:STATE
1;LIMIT 1.00E+00;:FLICKER:PLT:STATE 1;LIMIT
0.65E+00;NVALUE 12;:FLICKER:DMIN:LIMIT
0.10E+00;:FLICKER:DISPLAY:FUNCTION
UN;ELEMENT 1;PERIOD 1
```

FLICker:COUNt

Function Sets the number of times measurement of short-term flicker value Pst is to be performed/queries the current setting.

Syntax FLICker:COUNt {<NRf>}

FLICker:COUNt?

{<NRf>}=1 to 99

Example FLICKER:COUNT 12

FLICKER:COUNT?→:FLICKER:COUNT 12

FLICker:DC?

Function Queries all the relative steady-state voltage change (dc) settings.

Syntax FLICker:DC?

Example FLICKER:DC?→:FLICKER:DC:STATE 1;LIMIT
3.00E+00

FLICker:DC:LIMit

Function Sets the limit for relative steady-state voltage change dc/ queries the current setting.

Syntax FLICker:DC:LIMit {<NRf>}
FLICker:DC:LIMit?

{<NRf>}=1.00 to 99.99

Example FLICKER:DC:LIMIT 3.00 FLICKER:DC:LIMIT?→:FLICKER:DC:LIMIT 3.00E+00

FLICker:DC[:STATe]

Function Sets whether or not relative steady-state voltage change dc be used as judgment item/queries the current setting.

Syntax FLICker:DC[:STATe] {<Boolean>}
 FLICker:DC:STATe?
Example FLICKER:DC:STATE ON
 FLICKER:DC:STATE?→:FLICKER:DC:STATE 1

FLICker:DISPlay?

Function Queries all the flicker measurement display settings.
Syntax FLICker:DISPlay?
Example FLICKER:DISPLAY?→:FLICKER:DISPLAY:
FUNCTION UN;ELEMENT 1;PERIOD 1

FLICker:DISPlay:ELEMent

Function Sets the element to be displayed during flicker measurement mode/queries the current setting.

Syntax FLICker:DISPlay:ELEMent {<NRf>}
FLICker:DISPlay:ELEMent?
{<NRf>}=1

Example FLICKER:DISPLAY:ELEMENT 1 FLICKER:DISPLAY:ELEMENT?→:FLICKER: DISPLAY:ELEMENT 1

FLICker:DISPlay:FUNCtion

Function Sets the function to be displayed during flicker measurement mode/queries the current setting.

Syntax FLICker:DISPlay:FUNCtion{<Display
function>}
FLICker:DISPlay:FUNCtion?

<Display function>={UN|DC|DMAX|DT|PST|PLT|TOTal}

Example FLICKER:DISPLAY:FUNCTION UN FLICKER:DISPLAY:FUNCTION?→:FLICKER: DISPLAY:FUNCTION UN

FLICker:DISPlay:PERiod

Function Sets the observation period no. to be displayed during flicker measurement/queries the current setting.

Syntax FLICker:DISPlay:PERiod {<NRf>}
FLICker:DISPlay:PERiod?

{<NRf>}=1 to 99

Example FLICKER:DISPLAY:PERIOD 1 FLICKER:DISPLAY:PERIOD?→:FLICKER: DISPLAY:PERIOD 1

FLICker:DMAX?

Function Queries all the maximum relative voltage change dmax settings.

Syntax FLICker:DMAX?

Example FLICKER:DMAX?→:FLICKER:DMAX:STATE 1;LIMIT
4.00E+00

FLICker:DMAX:LIMit

Function Sets the limit for maximum relative voltage change dmax/
 queries the current setting.
Syntax FLICker:DMAX:LIMit {<NRf>}
 FLICker:DMAX:LIMit?

{<NRf>}=1.00 to 99.99

Example FLICKER:DMAX:LIMIT 4.00

FLICKER:DMAX:LIMIT?→:FLICKER:DMAX:LIMIT
4.00E+00

FLICker:DMAX [:STATe]

Function Sets whether or not maximum relative voltage change dmax be used as judgment item/queries the current setting.

Syntax FLICker:DMAX[:STATe] {<Boolean>}
FLICker:DMAX:STATe?

Example FLICKER: DMAX: STATE ON

FLICKER:DMAX:STATE? \rightarrow :FLICKER:DMAX:STATE 1

FLICker:DMIN?

Function Queries all the steady-state range dmin settings.
Syntax FLICker:DMIN?
Example FLICKER:DMIN?→:FLICKER:DMIN:LIMIT
0.10E+00

FLICker:DMIN:LIMit

FLICker:DT?

Function Queries all the settings regarding period d (t) $_{200ms}$ during which relative voltage change exceeds the threshold level during a voltage change.

Syntax FLICker:DT?

Example FLICKER:DT?→:FLICKER:DT:STATE 1;LIMIT
0.200E+00, 3.00E+00

FLICker:DT:LIMit

Function Sets the limit for the period d (t) _{200ms} during which relative voltage change exceeds the threshold level during a voltage change/queries the current setting.

Syntax FLICker:DT:LIMit {<Time>, <NRf>}
FLICker:DT:LIMit?
<Time>=1 to 99999(msec)

{<NRf>}=1.00 to 99.99

Example FLICKER:DT:LIMIT 200MS, 3.00

FLICKER:DT:LIMIT?→:FLICKER:DT:LIMIT
0.200E+00, 3.00E+00

FLICker:DT:[:STATe]

- **Function** Sets whether or not period d (t) _{200ms} during which relative voltage change exceeds the threshold level during a voltage change be used as judgment item/queries the current setting.
- Syntax FLICker:DT[:STATe] {<Boolean>}
- FLICker:DT:STATe?
 Example FLICKER:DT:STATE ON
 FLICKER:DT:STATE?→:FLICKER:DT:STATE 1

FLICker:ELEMent<x>

- **Function** Sets the element for which flicker measurement is to be performed/queries the current setting.
- Syntax FLICker:ELEMent<x> {<Boolean>}
 FLICker:ELEMent<x>?
 <x>=1
- Example FLICKER:ELEMENT1 ON FLICKER:ELEMENT1?→:FLICKER:ELEMENT1 1

FLICker:INITialize

Function Resets judgment result and performs measurement of rated
voltage.
Syntax FLICker:INITialize

Example FLICKER: INITIALIZE

FLICker:INTerval

Function Sets the time required for one measurement of short-term flicker value Pst/queries the current setting.

Syntax FLICker:INTerval {<NRf>, <NRf>|<Character string>}
FLICker:INTerval?

{<NRf>, <NRf>}=0,30 to 59,58(Minute, Second)

<Character string>="MM:SS"(MM: Minute, SS: Second)
Example FLICKER:INTERVAL 10,0

FLICKER:INTERVAL "10:00"

FLICKER:INTERVAL?→:FLICKER:INTERVAL 10,0

Description Sets seconds in even values. If an odd value, "-1" will be deducted from the set value to make it an even value. For instance, if an attempt to set 31 seconds is made, it will be replaced by a setting of 30 seconds.

FLICker:PLT?

Function Queries all the long-term flicker value Plt settings/queries the current setting.

Syntax FLICker:PLT?

Example FLICKER:PLT?→:FLICKER:PLT:STATE 1;LIMIT 0.65E+00;NVALUE 12

FLICker:PLT:LIMit

Function Sets the limit for long-term flicker value Plt/queries the current setting.

Syntax FLICker:PLT:LIMit {<NRf>}
FLICker:PLT:LIMit?

{<NRf>}=0.10 to 99.99

Example FLICKER:PLT:LIMIT 0.65

```
FLICKER:PLT:LIMIT?→:FLICKER:PLT:LIMIT
```

FLICker:PLT:NVALue

```
Function Sets N value for long-term flicker value Plt/queries the current setting.
```

Syntax FLICker:PLT:NVALue {<NRf>}
FLICker:PLT:NVALue?

{<NRf>}=1 to 99

Example FLICKER: PLT: NVALUE 12

FLICKER:PLT:NVALUE?→:FLICKER:PLT:NVALUE
12

FLICker:PLT[:STATe]

Function Sets whether or not long-term flicker value Plt be used as judgment item/queries the current setting.

Syntax FLICker:PLT[:STATe] {<Boolean>}

```
FLICker:PLT:STATe?
```

Example FLICKER: PLT: STATE ON

FLICKER:PLT:STATE? >:FLICKER:PLT:STATE 1

FLICker:PST?

Function Queries all the short-term flicker value Pst settings/queries the current setting.

Syntax FLICker:PST?

Example FLICKER:PST?→:FLICKER:PST:STATE 1;LIMIT 1.00E+00

FLICker:PST:LIMit

Function Sets the limit for short-term flicker value Pst/queries the current setting.

```
Syntax FLICker:PST:LIMit {<NRf>}
FLICker:PST:LIMit?
```

{<NRf>}=0.10 to 99.99

```
Example FLICKER: PST:LIMIT 1.00
```

```
FLICKER:PST:LIMIT?→:FLICKER:PST:LIMIT
1.00E+00
```

FLICker:PST[:STATe]

Function Sets whether or not short-term flicker value Pst be used as judgment item/queries the current setting.

Syntax FLICker:PST[:STATe] {<Boolean>}

```
FLICker:PST:STATe?
```

Example FLICKER: PST: STATE ON

FLICKER:PST:STATE?→:FLICKER:PST:STATE 1

FLICker:STARt

Function Registers rated voltage and starts measurement of voltage
fluctuation.
Syntax FLICker:STARt

Example FLICKER: START

FLICker[:STATe]

Function Turns flicker measurement mode ON or OFF/queries the current setting.

Syntax FLICker[:STATe] {<Boolean>}
FLICker:STATe?

Example FLICKER:STATE ON FLICKER:STATE?→:FLICKER:STATE 1

FLICker:STOP

Function Stops measurement of voltage fluctuation and displays judgment result.

Syntax FLICker:STOP

Example FLICKER: STOP

FLICker:UN?

Function Queries all the nominal voltage Un settings.

Syntax FLICker:UN?

Example FLICKER:UN?→:FLICKER:UN:MODE AUTO;VALUE 230.00E+00

FLICker:UN:MODE

Function Sets the acquisition method for nominal voltage Un/queries the current setting.

Syntax FLICker:UN:MODE {AUTO | SET}

FLICker:UN:MODE?

Example FLICKER:UN:MODE AUTO

FLICKER:UN:MODE? ->:FLICKER:UN:MODE AUTO

Description

Description of each acquisition method is given below.

- AUTO : Uses the voltage value measured at the start of voltage fluctuation measurement .
- SET : Uses the existing value (the value set by the FLICker:UN:VALue command).

FLICker:UN:VALue

Function Sets the existing value for nominal voltage Un/queries the current setting.

Syntax FLICker:UN:VALue {<Voltage>}

FLICker:UN:VALue?

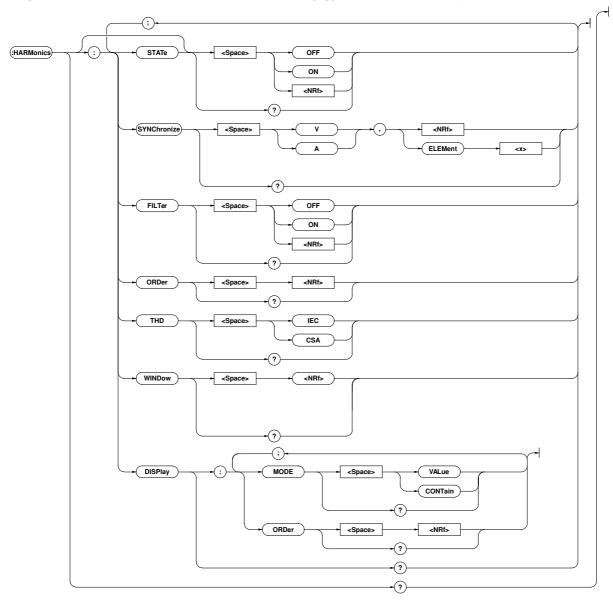
{<Voltage>}=0.01 to 999.99

Example FLICKER:UN:VALUE 230V

FLICKER:UN:VALUE?→:FLICKER:UN:VALUE
230.00E+00

2.3.7 HARMonics Group

The commands in the HARMonics group are used to make settings relating to and to inquire about harmonic analysis. This allows you to make the same settings and inquiries which can be made using the ANALYZE (HARMONICS) and SET UP keys on the front panel. These commands are available if the instrument is equipped with the harmonic analysis function (/HRM model).



HARMonics?

Function Queries all the harmonic analysis settings.

Syntax HARMonics?

Example HARMONICS?→:HARMONICS:STATE 0;SYNCHRONIZE V,1;FILTER 0;ORDER 50;THD IEC;WINDOW 16;DISPLAY:MODE VALUE;ORDER 1

HARMonics:DISPlay?

Function Queries all the display settings for harmonic analysis.

Syntax HARMonics:DISPlay?

Example HARMONICS:DISPLAY?→:HARMONICS:DISPLAY:MODE MODE VALUE;ORDER 1

HARMonics:DISPlay:MODE

Function Sets display mode for harmonic analysis items (V, A, W) to be displayed on display B/queries the current setting.

Syntax HARMonics:DISPlay:MODE {VALue|CONTain} HARMonics:DISPlay:MODE?

{VALue|CONTain}={Analysis value (measured value) display | Content display}

Example HARMONICS: DISPLAY: MODE VALUE

HARMONICS:DISPLAY:MODE?→:HARMONICS:DISPLAY: MODE VALUE

HARMonics:DISPlay:ORDer

Function Sets harmonic order to be displayed on display A/queries the current setting.

Syntax HARMonics:DISPlay:ORDer {<NRf>} HARMonics:DISPlay:ORDer? {<NRf>}=1 to 50

Example HARMONICS:DISPLAY:ORDER 1
HARMONICS:DISPLAY:ORDER?→:HARMONICS
:DISPLAY:ORDER 1

HARMonics:FILTer

Function Turns anti-aliasing filter for harmonic analysis ON or OFF/
 queries the current setting.
Syntax HARMonics:FILTer {<Boolean>}

HARMonics:FILTer?

Example HARMONICS:FILTER OFF

HARMONICS:FILTER?→:HARMONICS:FILTER 0

HARMonics:ORDer

Function Sets the maximum harmonic order for harmonic analysis /
 queries the current setting.
Syntax HARMonics:ORDer {<NRf>}
 HARMonics:ORDer?
 {<NRf>}=1 to 50
Example HARMONICS:ORDER 50

HARMONICS:ORDER?→:HARMONICS:ORDER 50

HARMonics[:STATe]

Function Turns harmonic analysis mode ON or OFF/queries the current setting.

Syntax HARMonics[:STATe] {<Boolean>}
HARMonics:STATe?

Example HARMONICS:STATE OFF HARMONICS:STATE?→:HARMONICS:STATE 0

HARMonics:SYNChronize

Function Sets the input (PLL source) to be used as the fundamental frequency for PLL synchronization/queries the current setting.

Syntax HARMonics:SYNChronize{(V|A),(<NRf>|

ELEMent<1>)}

HARMonics:SYNChronize?

Example HARMONICS:SYNCHRONIZE V,1 HARMONICS:SYNCHRONIZE?→:HARMONICS:

SYNCHRONIZE V.1

HARMonics:THD

Function Sets the equation to be used for harmonic distortion (VTHD, ATHD)/queries the current setting.

Syntax HARMonics:THD {IEC|CSA}

HARMonics:THD?

Example HARMONICS:THD IEC HARMONICS:THD?→:HARMONICS:THD IEC

HARMonics:WINDow

Function Sets the window width for harmonic analysis/queries the current setting.

Syntax HARMonics:WINDow {<NRf>}

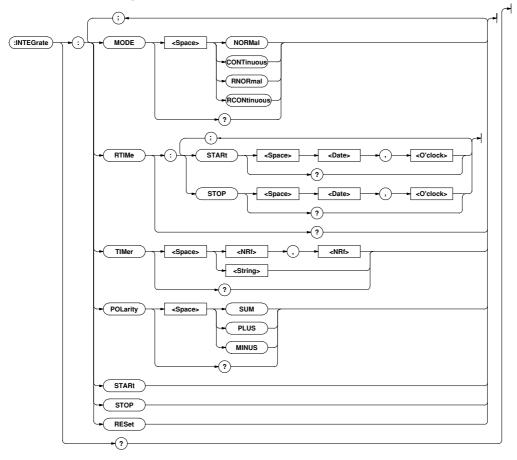
HARMonics:WINDow? {<NRf>}=1, 2, 4, 8, 16

Example HARMONICS:WINDOW 16

HARMONICS:WINDOW?→:HARMONICS:WINDOW 16

2.3.8 INTEGrate Group

IThe commands in the INTEGrate group are used to make settings relating to and to inquire about integration function. This allows you to make the same settings and inquiries which can be made using the INTEGRATOR keys (START, STOP, RESET and MODE keys) on the front panel.



INTEGrate?

Function Queries all the integration settings.

Syntax INTEGrate?

Example INTEGRATE?→:INTEGRATE:MODE NORMAL;RTIME:START 96,4,1,17,35,0;STOP96,4,3,19,35,0;:INTEGRATE: TIMER 10,0;POLARITY SUM

INTEGrate:MODE

Function Sets integration mode/queries the current setting.

Syntax INTEGrate:MODE{NORMal|CONTinuous|RNORmal
|RCONtinuous}

INTEGrate:MODE?

Example INTEGRATE:MODE NORMAL

INTEGRATE:MODE?→:INTEGRATE:MODE NORMAL

Description Selectable modes are given below.

NORMal	: Standard integration mode
CONTinuous	: Continuous integration mode
RNORmal	: Real time counting standard integration
	mode RCONtinuous
RCONtinuous	: Real time counting continuous integration
	mode

INTEGrate:POLarity

Function Sets polarity of integrated values to be displayed on display D/ queries the current setting.

Syntax INTEGrate:POLarity {SUM|PLUS|MINUS}
INTEGrate:POLarity?

Example INTEGRATE: POLARITY SUM

INTEGRATE:POLARITY?→:INTEGRATE:POLARITY SUM

INTEGrate:RESet

Function Resets integrated values.
Syntax INTEGrate:RESet
Example INTEGRATE:RESET

INTEGrate:RTIMe?

Function Queries the integration start and stop time for real time counting integration mode.

Syntax INTEGrate:RTIMe?

Example INTEGRATE:RTIME?→:INTEGRATE:RTIME:START 96,4,1,17,35,0;STOP 96,4,3,19,35,0

INTEGrate:RTIMe:STARt

Function Sets the integration start time for real time counting integration mode/queries the current setting.

Syntax INTEGrate:RTIMe:STARt {<Date>,<0'clock>}
INTEGrate:RTIMe:STARt?

<Date>={<NRf>, <NRf>, <NRf>|<Character
string>}

<O'clock>= {<NRf>,<NRf>[,<NRf>] |<Character string>}

Example INTEGRATE:RTIME:START 96,4,1,17,35,0 INTEGRATE:RTIME:START "1996/04/

01","17:35:00"

INTEGRATE:RTIME:START?→:INTEGRATE: RTIME:START 96,4,1,17,35,0

Description For <Date> and <O'clock> data, refer to Section 2.3.16, "SYSTem Group".

INTEGrate:RTIMe:STOP

Function Sets the integration stop time for real time counting integration mode/queries the current setting.

Syntax INTEGrate:RTIMe:STOP{<Date>,<0'clock>}
INTEGrate:RTIMe:STOP?

<Date>={<NRf>, <NRf>, <NRf>|<Character string>}

<O'clock>= {<NRf>, <NRf>[, <NRf>] |<Character string>}

Example INTEGRATE:RTIME:STOP 1996,04,03,19,35,0
INTEGRATE:RTIME:STOP "96/4/3","19:35:0"
INTEGRATE:RTIME:STOP?→:INTEGRATE:RTIME
:STOP 96,4,3,19,35,0

Description For <Date> and <O'clock> data, refer to Section 2.3.16, "SYSTem Group".

INTEGrate:STARt

Function Starts integration.
Syntax INTEGrate:STARt
Example INTEGRATE:START

INTEGrate:STOP

Function Stops integration.
Syntax INTEGrate:STOP
Example INTEGRATE:STOP

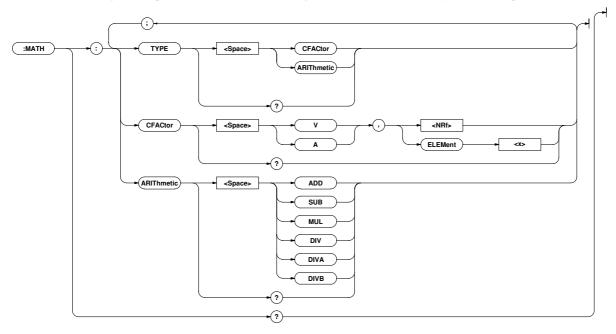
INTEGrate:TIMer

Function Sets integration timer preset time/queries the current setting.

Syntax INTEGrate:TIMer {<NRf>,<NRf>|<Character string>}
 INTEGrate:TIMer?
 {<NRf>,<NRf>}=0,0 to 999,59
 {<Character string>}="HHH:MM" HHH:Hour MM:Hour
Example INTEGRATE:TIMER 10,0
 INTEGRATE:TIMER "10:00"
 INTEGRATE:TIMER?→:INTEGRATE:TIMER 10,0

2.3.9 MATH Group

The commands in the MATH group are used to make settings relating to and to inquire about computation. This allows you to make the same settings and inquiries which can be made using the MATH (SHIFT + >) key on the front panel.



MATH?

Function Queries all the computation settings. Syntax MATH? Example MATH?→:MATH:TYPE CFACTOR;CFACTOR V,1 MATH:ARIThmetic

Function Sets equation for four arithmetical operations/queries the current setting.

Syntax MATH:ARIThmetic {ADD|SUB|MUL|DIV|DIVA|DIVB} MATH:ARIThmetic?

Example MATH:ARITHMETIC ADD

MATH:ARITHMETIC?→:MATH:ARITHMETIC ADD

Description "MATH: TYPE ARIThmetic" must be selected, otherwise this command is meaningless.

Description of each equation is given below.

- ADD : Display A + Display B
- SUB : Display A Display B
- MUL : Display A * Display B
- DIV : Display A / Display B
- DIVA : Display A / (Display B)²
- DIVB : $(Display A)^2 / Display B$

MATH:CFACtor

Function Sets equation for crest factor/queries the current setting.Sets
 equation for crest factor/queries the current setting.
Syntax MATH:CFACtor {(V|A), (<NRf>|ELEMent<1>)}

MATH:CFACtor?

Example MATH:CFACTOR V,1

MATH:CFACTOR? \rightarrow :MATH:CFACTOR V,1

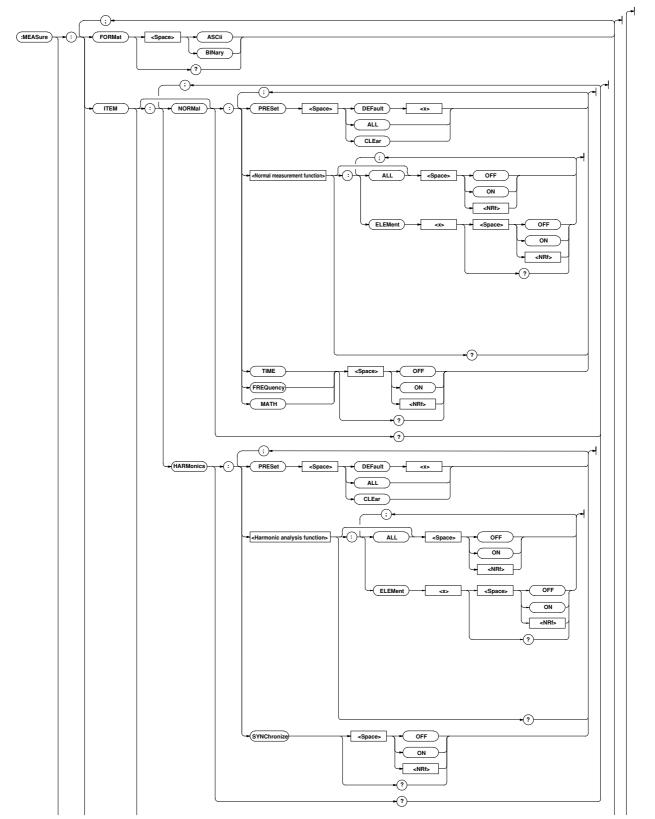
Description "MATH: TYPE CFACtor" must be selected, otherwise this command is meaningless.

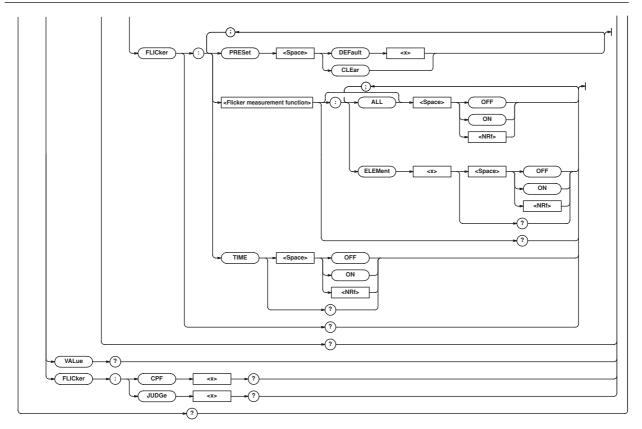
MATH:TYPE

Function Sets computation type/queries the current setting.
Syntax MATH:TYPE {CFACtor|ARIThmetic}
MATH:TYPE?
Example MATH:TYPE CFACTOR
MATH:TYPE?→:MATH:TYPE CFACTOR
Description Selectable computation types are given below.
CFACtor : Crest factor
ARIThmetic : Four arithmetical operations

2.3.10 MEASure Group

The commands in the MEASure group are used to make settings relating to and to inquire about measured/computed data to be output via communication. This allows you to make the same settings and inquiries which can be made using the MISC ("co-out" menu) on the front panel.





MEASure?

Function Queries all the communication output settings for measured/ computed data.

Syntax MEASure?

Example MEASURE? →: MEASURE: FORMAT ASCII; (":MEASURE:"
 part is excluded from the response made to
 the MEASure:ITEM? query command)

MEASure:FLICker:CPF<x>?

Function Queries the CPF (cumulative probability function) data obtained during the previous flicker observation period.

Syntax MEASure:FLICker:CPF<x>?

<x> indicates element.

```
<x>= 1
```

Example MEASURE: FLICKER: CPF1?

 \rightarrow #44100ABCDEFGHIJKLMN....

Description CPF data is output as a block data consisting of header ("#44100" in the case of the above example) and 4100-byte binary data (1025 x 4).

For a detailed description, refer to "Output Format for CPF Data" on page App 1-24.

MEASure:FLICker:JUDGe<x>?

- Function Queries the judgment result data for each flicker observation period.
- Syntax MEASure:FLICker:JUDGe<x>?

<x>=1 to 99(Observation period no.)

```
Example MEASURE:FLICKER:JUDGE1?→2, 0, 0, 1.23E+00,
2.34E+00.....
```

```
Description "MEASure:VALue?" queries the latest measured data for the
current observation period, whilst "MEASure:
FLICker:JUDGe<x>?" queries the measured data obtained
during past observation periods. However, the output format is
the same.
```

MEASure:FORMat

Function Sets communication output format for measured/computed data/queries the current setting.

Syntax MEASure:FORMat {ASCii|BINary}

MEASure:FORMat?

Example MEASURE: FORMAT ASCII

MEASURE:FORMAT?→:MEASURE:FORMAT ASCII

MEASure:ITEM?

Function Queries all the communication output items settings for measured/computed data.

Syntax MEASure:ITEM?

Example MEASURE:ITEM?→(Response to MEASure: ITEM:NORMal?);(Response to MEASure: ITEM:HARMonics?);(Response to MEASure: ITEM:FLICker?)

MEASure:ITEM:FLICker?

- Function Queries all the communication output items for flicker measurement.
- Syntax MEASure:ITEM:FLICker?
- Example MEASURE:ITEM:FLICKER?→:MEASURE:ITEM: FLICKER:UN:ELEMENT1 1;:MEASURE:ITEM: FLICKER:DC:ELEMENT1 1;:MEASURE:ITEM: FLICKER:DMAX:ELEMENT1 1;:MEASURE:ITEM: FLICKER:PST:ELEMENT1 1;:MEASURE:ITEM: FLICKER:PLT:ELEMENT1 1;:MEASURE:ITEM: FLICKER:TOTAL:ELEMENT1 1;:MEASURE:ITEM: FLICKER:VHZ:ELEMENT1 1;:MEASURE:ITEM: FLICKER:VHZ:ELEMENT1 1;:MEASURE:ITEM: FLICKER:TIME 1

MEASure:ITEM:FLICker<flicker measurement function>

- **Function** Queries all the communication output ON/OFF for the specified flicker measurement function.
- Syntax MEASure:ITEM:FLICker:<Flicker measurement
 function>?

<Flicker measurement function>=

- $\{UN | DC | DMAX | DT | PST | PL T | TOTAL | VHZ \}$
- Example MEASURE:ITEM:FLICKER:UN?→:MEASURE:ITEM: FLICKER:UN:ELEMENT1 1

MEASure:ITEM:FLICker<flicker measurement function>:[ALL]

- Function Turns communication output for the specified flicker measurement function ON or OFF .
- Syntax MEASure:ITEM:FLICker:<Flicker measurement
 function>[:ALL] {<Boolean>}

Example MEASURE: ITEM: FLICKER: UN: ALL ON

MEASure:ITEM:FLICker<flicker measurement function>:ELEMent<x>

- Function Turns communication output for the specified flicker measurement function ON or OFF.
- Syntax MEASure:ITEM:FLICker:<Flicker measurement
 function>:ELEMent<x> {<Boolean>}
 MEASure:ITEM:FLICker:<Flicker measurement
 function>:ELEMent<x>?

<x>= 1

Example MEASURE:ITEM:FLICKER:UN:ELEMENT1 ON MEASURE:ITEM:FLICKER:UN:ELEMENT1?→ :MEASURE:ITEM:FLICKER:UN:ELEMENT1 1

MEASure:ITEM:FLICker:TIME

- **Function** Turns communication output of the elapsed time of voltage fluctuation measurement ON or OFF/queries the current setting.
- Syntax MEASure:ITEM:FLICker:TIME MEASure:ITEM:FLICker:TIME?
- Example MEASURE: ITEM: FLICKER: TIME ON
 - MEASURE:ITEM:FLICKER:TIME?→:MEASURE: ITEM:FLICKER:TIME 1

MEASure:ITEM:FLICker:PRESet

Function Sets the communication output items for flicker measurement mode to the specified default setting at once.

Example MEASURE: ITEM: FLICKER: PRESET DEFAULT1

Description • For a detailed description of default setting, refer to 14.1 "Selecting the Output Items".

MEASure:ITEM:HARMonics?

```
Function Queries all the communication output items for harmonic analysis mode.
```

Syntax MEASure:ITEM:HARMonics?

Example MEASURE:ITEM:HARMONICS? →:MEASURE:ITEM:
HARMONICS:V:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:A:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:W:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:VA:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:VAR:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:PF:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:DEG:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:VTHD:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:ATHD:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:VCON:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:ACON:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:WCON:ELEMENT1 1;:MEASURE:ITEM:
HARMONICS:VDEG:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:ADEG:ELEMENT1 0;:MEASURE:ITEM:
HARMONICS:SYNCHRONIZE 1

MEASure:ITEM:HARMonics:<Harmonic analysis function>?

Function Queries all the communication output ON/OFF for the specified harmonic analysis function.

Syntax MEASure:ITEM:HARMonics:<Harmonic analysis
 function>?

<Harmonic analysis function>=

{ V | A | W | VA | VAR | PF | DEG | V | THD | ATHD | VCON | ACON | WCON | VDEG | ADEG }

Example MEASURE:ITEM:HARMONICS:V?→:MEASURE:ITEM: HARMONICS:V:ELEMENT1 1

MEASure:ITEM:HARMonics:{<Harmonic analysis function>}[:ALL]

- Function Turns communication output for the specified harmonic analysis function ON or OFF.
- Syntax MEASure:ITEM:HARMonics:<Harmonic analysis
 function>[:ALL] {<Boolean>}

Example MEASURE: ITEM: HARMONICS: V: ALL ON

MEASure:ITEM:HARMonics:<Harmonic analysis function>:ELEMent<x>

- **Function** Turns communication output for the specified harmonic analysis function ON or OFF/queries the current setting.
- Syntax MEASure:ITEM:HARMonics:<Harmonic analysis
 function>:ELEMent<x> {<Boolean>}
 MEASure:ITEM:HARMonics:<Harmonic analysis
 function>:ELEMent<x>?
 <x>=1
- Example MEASURE:ITEM:HARMONICS:V:ELEMENT1 ON MEASURE:ITEM:HARMONICS:V:ELEMENT1?→:MEASURE: ITEM:HARMONICS: V:ELEMENT1 1

MEASure:ITEM:HARMonics:SYNChronize

- Function Turns communication output for PLL source ON or OFF/queries the current setting.

MEASure:ITEM:HARMonics:SYNChronize?

Example MEASURE:ITEM:HARMONICS:SYNCHRONIZE ON MEASURE:ITEM:HARMONICS:SYNCHRONIZE?→ MEASURE:ITEM: HARMONICS:SYNCHRONIZE 1

MEASure:ITEM:HARMonics:PRESet

- Function Sets communication output items for harmonic analysis mode to the preset settings at once.
- Syntax MEASure:ITEM:HARMonics:PRESet {DEFault<12>|ALL|CLEar}

Example MEASURE:ITEM:HARMONICS:PRESET DEFAULT1

Description For a description of global setting, refer to Section 14.1, "Selecting the Output Items".

MEASure:ITEM:NORMal?

Function Queries all the communication output items for normal measurement mode.

Syntax MEASure:ITEM:NORMal?

Example MEASURE:ITEM:NORMAL?→:MEASURE:ITEM:
NORMAL:V:ELEMENT1 1;:MEASURE:ITEM:
NORMAL:A:ELEMENT1 1;:MEASURE:ITEM:
NORMAL:W:ELEMENT1 1;:MEASURE:ITEM:
NORMAL:VA:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:VAR:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:PF:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:DEG:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:VPK:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:APK:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:WH:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:WHP:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:WHM:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:AH:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:AHP:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:AHM:ELEMENT1 0;:MEASURE:ITEM:
NORMAL:TIME 0;FREQUENCY 1;MATH 0

M E A S u r e : I T E M [: N O R M a I] : < N o r m a I measurement function>?

- **Function** Queries all the communication output ON/OFF for the specified normal measurement function.
- Syntax MEASure:ITEM[:NORMal]:<Normal measurement
 function>?

<Normal measurement function>= {V | A | W | VA|VAR|PF|DEG|VPK|APK|WH|WHP|WHM|AH|AHP|AHM}

Example MEASURE:ITEM:NORMAL:V?→:MEASURE:ITEM: NORMAL:V:ELEMENT1 1

M E A S u r e : I T E M [: N O R M a I] : < N o r m a I measurement function >[:ALL]

Function Turns communication output for the specified normal measurement function ON or OFF.

Syntax MEASure:ITEM[:NORMal]:<Normal measurement
 function>[:ALL] {<Boolean>}

Example MEASURE:ITEM:NORMAL:V:ALL ON

M E A S u r e : I T E M [: N O R M a I] : < N o r m a I measurement function>:ELEMent<x>

Function Turns communication output for the specified normal measurement function ON or OFF/queries the current setting.

Syntax MEASure:ITEM[:NORMal]:<Normal measurement function>:ELEMent<x> {<Boolean>} MEASure:ITEM[:NORMal]:<Normal measurement function>:ELEMent<x>?

<x>=1

Example MEASURE:ITEM:NORMAL:V:ELEMENT1 ON MEASURE:ITEM:NORMAL:V:ELEMENT1?→:MEASURE:ITEM: NORMAL:V:ELEMENT1 1

MEASure:ITEM[:NORMal]:{TIME|FREQuency|MATH}

- Function Turns communication output ON or OFF for the elapsed time of integration, frequency and computed data.
- Example MEASURE:ITEM:NORMAL:FREQUENCY ON MEASURE:ITEM:NORMAL:FREQUENCY?→:MEASURE:IT EM:NORMAL:FREQUENCY 1

MEASure:ITEM[:NORMal]:PRESet

Function Sets communication output items for normal measurement mode to the preset settings at once.

Syntax MEASure:ITEM[:NORMal]:PRESet {DEFault<1-2>|ALL|CLE ar}
Example MEASURE:ITEM:NORMAL:PRESET DEFAULT1

Description For a description of global setting, refer to Section 14.1, "Selecting the Output Items".

MEASure:VALue?

Function Queries all the measured/computed data for the items which are set to ON using "MEASure:ITEM" commands ("MEASure :ITEM:HARMonics" through "MEASure:ITEM[:NORMal]:PRESet").

Syntax MEASure:VALue?

Example MEASURE:VALUE?→7.006E+00,6.386E+00,-36.68E+00,...

Description Measured/computed data output by this query command is updated at the rise of bit 0 (UPD) of the condition register (refer to page App 2-55). For details, refer to Section 2.2.6, "Synchronization with the Controller".

Output/Data Format for Normal Measurement, Harmonic Analysis and Flicker Measurement

The output and data format for data obtained during normal measurement, harmonic analysis and flicker measurement modes which is output by "MEASure:VALue?" are described below.

Data format for normal measurement data

```
• Data for <normal measurement function> is always output in <NR3> format.
```

(Exampl) 99.99E+00					
WH,WHP,WHM,AH,AHP,AHM	→Mantissa: floating-point number of the				
	maximum 6 digits + Exponent: 2 digits				
Except for WH, WHP, WHM, AH, AHP, AHM	\rightarrow Mantissa: floating-point number of the				
	maximum 5 digits + Exponent: 2 digits				

• The sign for the mantissa is provided only when the value is negative. However, phase lag and phase lead for phase angle (DEG) are expressed as follows.

Not detectable \rightarrow 0.0E+00 (preceded by a space)

- "9.9E+37" (+∞) is output in case of overrange or computation overflow. (-oL-, -oF-, PFErr, dEGEr, ErrLo or ErrHi is displayed.)
- "9.91E+37" (NAN) is output in case of no data ("-----" is displayed).
- For elapsed time of integration (TIME), 3 data (hour, minute and second) is output in <NR1> format. Example 999, 59, 59

Output format for normal measurement data

Output format for normal measurement data for all the items which are set to ON as described in Section 14.1, "Selecting the Output Items" or using "MEASure: ITEM[:NORMal] commands is output in one line at once. The order in which each data is output is given below. (Numbers indicate element numbers.)

 $V1 \rightarrow A1 \rightarrow W1 \rightarrow VA1 \rightarrow VAR1 \rightarrow PF1 \rightarrow DEG1 \rightarrow VPK1 \rightarrow APK1 \rightarrow$

 $TIME \rightarrow WH1 \rightarrow WHP1 \rightarrow WHM1 \rightarrow AH1 \rightarrow AHP1 \rightarrow AHM1 \rightarrow$

FREQuency→MATH

A comma is inserted between data to separate them, and a terminator (<RMT>) is added at the end of the last data.

Output examples for normal measurement data

• When the following commands are sent

(Command) MEASURE:ITEM:NORMAL:PRESET DEFAULT1

MEASURE:VALUE?

(Received data) 5.721E+00,2.4567E+00,-10.48E+00,63.998E+00

(Description of each received data)

V1 :5.721E+00 A1 :2.4567E+00 W1 :-10.48E+00 FREQ:63.998E+00

· When the following commands are sent during integration

(Command) MEASURE:ITEM:NORMAL:PRESET DEFAULT2 MEASURE:VALUE?

(Received data)

-10.49E+00,0,10,0,-1.7469E+00,0.0524E+00,-1.7993E+00,409.26E-03,409.26E-03,0.00E-

```
03,64.001E+00
```

(Description of each received data)

```
W1 :-10.49E+00
WH1 :-1.7469E+00 WHP1 :0.0524E+00 WHM1 :-1.7993E+00
AH1 :409.26E-03 AHP1 :409.26E-03 AHM1 :0.00E-03
FREQ:64.001E+00
lapsed time of integration: 0 (hour) 10 (minute) 0 (second)
```

Data format for harmonic analysis data

Data is always output in <NR3> format. (Mantissa: floating-point number of the maximum 5 digits + Exponent: 2 digits)

Output format for harmonic analysis data

Data for all the items which are set to ON as described in Section 14.1, "Selecting the Output Items" or using "MEASure:ITEM[:HARMonics] commands is output in one line at once. The order in which each data is output is given below. (Numbers indicate element numbers.)

```
V1 \rightarrow A1 \rightarrow W1 \rightarrow
VA1 \rightarrow VAR1 \rightarrow PF1 \rightarrow DEG1 \rightarrow VTHD1 \rightarrow ATHD1 \rightarrow
VCON1 \rightarrow ACON1 \rightarrow WCON1 \rightarrow
VDEG1 \rightarrow ADEG1 \rightarrow
SYNChronize
```

The following number of data sets are output by one <harmonic analysis function> or SYNChronize (PLL source frequency).

- * "n" is the upper limit of the harmonic order. The harmonic data above the upper limit are not outputted.
- V, A, W : n^*+1 data (1 data for V Σ , A Σ , W Σ)

Total rms value of 1st to n*th harmonic \rightarrow Analysis value of fundamental \rightarrow Analysis value of 2nd harmonic $\rightarrow ... \rightarrow$ Analysis value of n*th harmonic

• VA, VAR, PF, DEG: 1 data

Apparent power, reactive power, power factor or phase angle of fundamental (1st) is output. Executing the HARMonics:DEGRee? query command allows you to know which object is used for phase angle.

• VTHD, ATHD : 1 data

Harmonic distortion of voltage or current is output. (Either IEC or CSA) Executing the HARMonics:THD? query command allows you to know which equation is used.

- VCON, ACON, WCON : n*-1 data ontent of 2nd harmonic → → Content of n*th harmonic
- VDEG : n^{*} data

has angle of current of 1st in relation to voltage of 1s \rightarrow Phase angle of voltage of 2nd in relation to voltage of 1st \rightarrow Phase angle of voltage of n*th in relation to voltage of 1st

• ADEG : n* data

Phase angle of current of 1st in relation to voltage of $1s \rightarrow$ Phase angle of current of 2nd in relation to current of 1st \rightarrow Phase angle of current of n*th in relation to current of 1st

• SYNChronize (PLL source frequency): 1 data Executing the HARMonics:SYNChronize? query command allows you to know which PLL source is used.

A comma is inserted between data to separate them, and a terminator (<RMT>) is added at the end of the last data.

Output examples	for harmonic analysis data	
• When the following	g commands are sent:	
(Command)	MEASURE:ITEM:HARMONICS:PRESET CLEAR	
	MEASURE:ITEM:HARMONICS:A:ELEMENT1 ON	
	MEASURE:ITEM:HARMONICS:ACON:ELEMENT1	ON
	MEASURE:VALUE?	
(Received data)	8.195E+00,8.136E+00,0.003E+00,0.903E+00,0.001	E+00,0.326E+00,
	0.001E+00,0.168E+00,0.000E+00,0.100E+00,0.001	E+00,0.067E+00,
	0.000E+00,0.049E+00,0.001E+00,0.038E+00,0.000	E+00,0.028E+00,
	0.001E+00,0.022E+00,0.000E+00,0.019E+00,0.001	E+00,0.016E+00,
	0.000E+00,0.013E+00,0.001E+00,0.012E+00,0.001	E+00,0.010E+00,
	0.001E+00,0.011E+00,0.001E+00,0.006E+00,0.001	
	0.001E+00,0.006E+00,0.000E+00,0.006E+00,0.000	
	0.000E+00,0.005E+00,0.001E+00,0.005E+00,0.001	
	0.000E+00,0.003E+00,0.001E+00,0.04E+00,11.10E	
	4.01E+00,0.02E+00,2.07E+00,0.01E+00,1.23E+00,	
	0.82E+00,0.00E+00,0.60E+00,0.02E+00,0.46E+00,	0.00E+00,
	0.34E+00,0.01E+00,0.28E+00,0.00E+00,0.23E+00,	0.01E+00,
	0.20E+00,0.00E+00,0.17E+00,0.01E+00,0.14E+00,	0.01E+00,
	0.13E+00,0.01E+00,0.13E+00,0.02E+00,0.07E+00,	0.01E+00,
	0.08E+00,0.01E+00,0.08E+00,0.00E+00,0.07E+00,	0.01E+00,
	0.07E+00,0.00E+00,0.06E+00,0.01E+00,0.06E+00,	0.01E+00,
	0.06E+00,0.00E+00,0.04E+00,0.01E+00	
(Description of each	received data)	
	Total rms value from 1st to 50th harmonic of current	: 8.195E+00 (A)
	Analysis value of fundamental (1st)	: 8.136E+00 (A)
	Analysis value of 2nd harmonic	: 0.003E+00 (A)
	Analysis value of 3rd harmonic	: 0.903E+00 (A)
	Analysis value of 50th harmonic	: 0.001E+00 (A)
	Content of 2nd harmonic	: 0.04E+00 (%)
	Content of 3rd harmonic	: 11.10E+00 (%)
	Content of 50th harmonic	: 0.01E+00 (%)
	A total of 100 data sets are output.	

Data format for flicker measurement data

- Data for <flicker measurement function> is always output in <NR3> format. (Mantissa: floatingpoint number of 5 digits + Exponent: 2 digits)
- "9.9E+37" (+∞) is output in case of overrange or computation overflow (-oL-, -oF-, Err-Lo or Err-Hi is displayed).
- "9.91E+37" (NAN) is output in case of no data ("-----" is displayed).
- "9.9E+37" (+∞) is output in case of data by which relative steady-state voltage change (dc) cannot be defined ("undEF" is displayed).
- In the total judgment result (TOTAL), "0.0E+00" is output for pass, "-1.0E+00" is output for fail and "-2.0E+00" is output for Judgment impossible.
- For elapsed time of voltage fluctuation measurement, 3 data (hour, minute and second) is output in <NR1> format. Example: 999, 59, 59

Output format for flicker measurement data

• Data for all the items which are set to ON as described in Section 14.1, "Selecting the Output Items" or using "MEASure:ITEM:FLICker" commands is output in one line at once. The order in which each data is output is given below. (Numbers indicates element numbers.)

 $\texttt{TIME} \rightarrow \texttt{UN}(\texttt{V}) 1 \rightarrow \texttt{VHZ} 1 \rightarrow \texttt{DC} 1 \rightarrow \texttt{DMAX} 1 \rightarrow \texttt{DT} 1 \rightarrow \texttt{PST} 1 \rightarrow \texttt{PLT} 1 \rightarrow \texttt{TOTAL} 1$

• A command is inserted between data to separate them, and a terminator (<RMT>) is added at the end of the last data.

Output examples for flicker measurement data

· When the following commands are sent during measurement of voltage fluctuation (Command) MEASURE: ITEM: FLICKER: PRESET DEFAULT1 MEASURE: VALUE? (Received data) 1, 18, 56, 231.8E+00, 49.999E+00, 1.52E+00, 1.56E+00, 80.0E-0.3, 9.91E+37, 9.91E+37, 9.91E+37, (Description of each received data) UN1:231.8E+00 VHZ1:49.999E+00 DC1:1.52E+00 DMAX1:1.56E+00 DT1:80.0E-03PST1:9.91E+37 PLT1:9.91E+37 TOTAL1:9.91E+37 Elapsed time: 1 (hour) 18 (minute) 56 (second) * "9.91E+37" (no data) will be output if the MEASURE: VALUE? is sent during measurement of voltage fluctuation, since computation of PST, PLT and TOTAL is not yet ready.

• When the following commands are sent during display of judgment result

(Command)	MEASURE:ITEM:FLICKER:PRESET DEFAULT1
	MEASURE:FLICKER:JUDGE12?
(Received data)	2, 0, 0, 231.8E+00, 49.999E+00,
	1.54E+00, 1.59E+00, 80.0E-0.3, 1.18E+00,
	0.62E+00, -1.0E+00,
(Description of each received data)	UN1:231.8E+00 VHZ1:49.999E+00
	DC1:1.54E+00 DMAX1:1.59E+00
	DT1:80.0E-0.3 PST1:1.18E+00
	PLT1:0.62E+00 TOTAL1:-1.0E+00
	Elapsed time: 2 (hour) 0 (minute) 0 (second)

Data format for binary data

Refer to "Data Section" on page App 1-25.

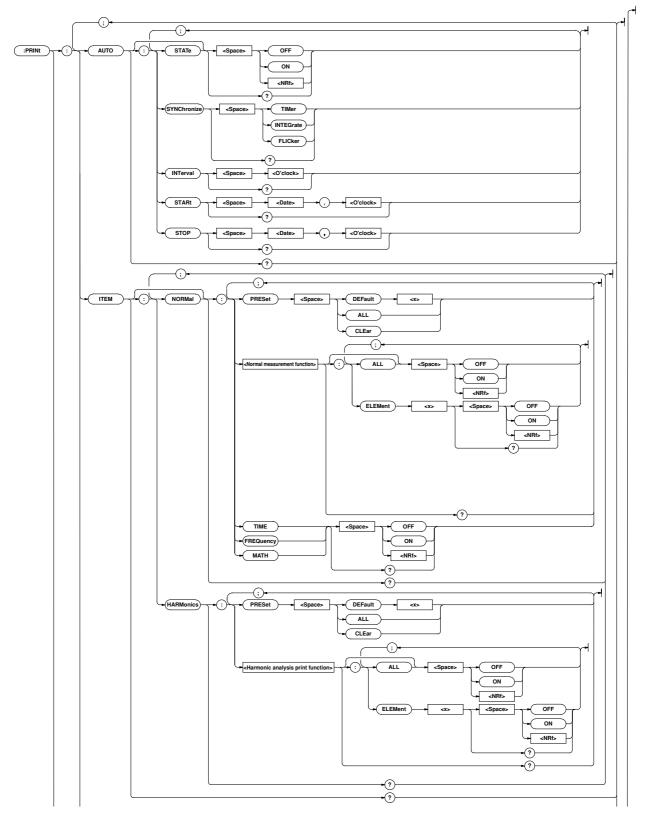
Output format for binary data

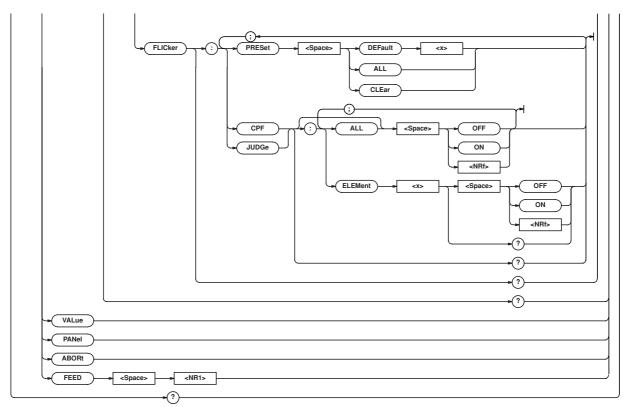
Following the steps described in Section 14.1 "Selecting the Output Items" or using the "MEASure:ITEM" group command, all data which have their communication output turned ON are outputted together as block data of "4 bytes * number of data sets."

- There is a 6-byte header in front of the block data. (Refer to App2-7 <Block data>.)
- Data of each items is output in the same order as ASCII format.
- No comma is inserted between data of each item to separate them.
- A terminator (<RMT>), which is normally added at the end of each line, is added. "EOI" becomes TRUE immediately the terminator is output.

2.3.11 PRINt Group

The commands in the PRINt group are used to make settings relating to and to inquire about built-in printer. This allows you to make the same settings and inquiries which you can make using the PRINTER keys (AUTO, PRINT, FEED SET UP (SHIFT + AUTO)) on the front panel. These commands are available only if the instrument is equipped with the built-in printer (/B5 model).





PRINt?

Function Queries all the current built-in printer settings. Syntax PRINt? Example PRINT?→(Response to PRINT:AUTO?); (Response to PRINT:ITEM?)

PRINt:ABORt

Function Stops printing. Syntax PRINt: ABORt Example PRINT: ABORT

PRINt:AUTO?

Function Queries all the current auto print mode settings. Syntax PRINt:AUTO?

Example PRINT: AUTO? →: PRINT: AUTO: STATE 0;SYNCHRONIZE TIMER; INTERVAL 0,1,0;START 96,4,1,8,30,50;STOP 96,4,1,12,5,30

PRINt:AUTO:INTerval

Function Sets print interval for auto print mode/queries the current setting. Syntax PRINt:AUTO:INTerval {<0'clock>} PRINt:AUTO:INTerval? {<O'clock>} = {<NRf>, <NRf>[, <NRf>] | <Character string>} {<NRf>, <NRf>[, <NRf>]}=0,0,10,99,59,59 {<Character string>}="HH:MM[:SS]" HHH: Hour MM: Miniute SS: Second Example PRINT: AUTO: INTERVAL 0,1,0 PRINT:AUTO:INTERVAL "0:1:0" PRINT:AUTO:INTERVAL? →:PRINT:AUTO:

INTERVAL 0,1,0

Description If second (SS) is not set, the print interval will be 0 second.

PRINt:AUTO:STARt

Function Sets start time for auto print mode/queries the current setting. Syntax PRINt:AUTO:STARt {<Date>,<0'clock>} PRINt:AUTO:STARt? <Date>={<NRf>,<NRf>,<NRf>|<Character string>} <O'clock>= { <NRf>, <NRf>[, <NRf>] |<Character string>} Example PRINT: AUTO: START 96,4,1,8,30,50 PRINT:AUTO:START "1996/04/01", "08:30:50" PRINT:AUTO:START→:PRINT:AUTO:START 96,4,1,8,30,50 Description For <Date> and <O'clock> data, refer to Section 2.3.16, "SYSTem Group". PRINt:AUTO[:STATe] Function Turns auto print mode ON or OFF/queries the current setting.

Syntax PRINt:AUTO[:STATe] {<Boolean>} PRINt:AUTO:STATe? Example PRINT: AUTO: STATE OFF PRINT:AUTO:STATE?→:PRINT:AUTO:STATE 0

PRINt:AUTO:STOP

Function Sets stop time for auto print mode/queries the current setting. Syntax PRINt:AUTO:STOP {<Date>,<0'clock>} PRINt:AUTO:STOP? <Date>={<NRf>,<NRf>,<NRf>|<Character string>} <O'clock>={<NRf>, <NRf>[, <NRf>]| <Character string>}

Example PRINT: AUTO: STOP 1996,04,01,12,05,30 PRINT:AUTO:STOP "96/4/1","12:5:30" PRINT:AUTO:STOP→:PRINT:AUTO:STOP 96,4,1,12,5,30

Description For <Date> and <O'clock> data, refer to Section 2.3.16, "SYSTem Group".

Appendix 2.3 Commands

PRINt:AUTO:SYNChronize

- Function Sets print synchronization method for auto print mode/queries the current setting.

PRINt:AUTO:SYNChronize?

Example PRINT: AUTO: SYNCHRONIZE TIMER

PRINT:AUTO:SYNCHRONIZE?→:PRINT:AUTO: SYNCHRONIZE TIMER

Description Selectable print synchronization methods are given below.

TIMer : Start/stop time synchronization

INTEGrate : Integration time synchronization

FLICker : Flicker measurement synchronization

PRINt:FEED

Function Feeds print paper.

Syntax PRINt:FEED {<NR1>}

{<NR1>}=1 to 20

Example PRINT: FEED 5

PRINt:ITEM?

Function Queries all the printer settings for measured/computed data.
Syntax PRINt:ITEM?

Example PRINT:ITEM?→(Response to PRINt:ITEM: NORMal?);
 (Response to PRINt:ITEM: HARMonics?); (Response
 to PRINt:ITEM: FLICker?)

PRINt:ITEM:FL|Cker?

Function Queries all the printer output items for flicker measurement.
Syntax PRINt:ITEM:FLICker?

Example PRINT: ITEM: FLICKER? →: PRINT: ITEM: FLICKER: CPF: ELEMENT1 1; PRINT: ITEM: FLICKER: JUDGE: ELEMENT1 1

PRINt:ITEM:FLICker:{CPF|JUDGe}?

Function Queries the printer output ON/OFF for CPF graph or flicker meter judgment result table.

Syntax PRINt:ITEM:FLICker:CPF?

Example PRINT:ITEM:FLICKER:CPF?→:PRINT:ITEM: FLICKER:CPF:ELEMENT1 1

PRINt:ITEM:FLICker:{CPF|JUDGe}[:ALL]

- **Function** Turns printer output of CPF graph or flicker meter judgment result table ON or OFF.
- Syntax PRINt:ITEM:FLICker:CPF[:ALL] {<Boolean>}
 Example PRINT:ITEM:FLICKER:CPF:ALL ON

PRINt:ITEM:FLICker:{CPF|JUDGe}:ELEMent<x>

Function Turns printer output of CPF graph or flicker meter judgment result table ON or OFF/queries the current setting.

Syntax PRINt:ITEM:FLICker:CPF:ELEMent<x>
 {<Boolean>}
 PRINt:ITEM:FLICker:CPF:ELEMent<x>?

<x>= 1

Example PRINT:ITEM:FLICKER:CPF:ELEMENT1 ON PRINT:ITEM:FLICKER:CPF:ELEMENT1?→:PRINT: ITEM:FLICKER:CPF:ELEMENT1 1

PRINt:ITEM:FLICker:PRESet

Function Sets the printer output items for flicker measurement mode to the specified default setting at once.

Syntax PRINt:ITEM:FLICker:PRESet {DEFault<12>|ALL|CLEar}

Example PRINT:ITEM:FLICKER:PRESET DEFAULT1

Description • For a detailed description of default setting, refer to 11.2 "Setting Printer Output Functions".

PRINt:ITEM:HARMonics?

Function Queries all the print output items for harmonic analysis mode.
Syntax PRINt:ITEM:HARMonics?

Example PRINT:ITEM:HARMONICS?→:PRINT:ITEM: HARMONICS:V:ELEMENT1 1;:PRINT:ITEM: HARMONICS:A:ELEMENT1 1;:PRINT:ITEM: HARMONICS:W:ELEMENT1 1;:PRINT:ITEM: HARMONICS:DEG:ELEMENT1 0;:PRINT:ITEM: HARMONICS:GV:ELEMENT1 0;:PRINT:ITEM: HARMONICS:GW:ELEMENT1 0;:PRINT:ITEM: HARMONICS:GVD:ELEMENT1 0;:PRINT:ITEM: HARMONICS:GAD:ELEMENT1 0;:PRINT:ITEM: HARMONICS:GAD:ELEMENT1 0;:PRINT:ITEM: HARMONICS:CGV:ELEMENT1 0;:PRINT:ITEM: HARMONICS:CGW:ELEMENT1 0;:PRINT:ITEM: HARMONICS:CGW:ELEMENT1 0;:PRINT:ITEM: HARMONICS:CGW:ELEMENT1 0;:PRINT:ITEM:

PRINt:ITEM:HARMonics:<Harmonic analysis function>?

- **Function** Queries the printer output ON/OFF for the specified harmonic analysis function.
- Syntax PRINt:ITEM:HARMonics:<Harmonic analysis
 function>?
- Example PRINT: ITEM: HARMONICS: V?→: PRINT: ITEM: HARMONICS: V: ELEMENT1 1
- Description Selectable functions are given below.
 - V : Analysis voltage value and relative harmonic content are printed in numeric.
 - A : Analysis current value and relative harmonic content are printed in numeric.
 - W : Analysis active power value and relative harmonic content are printed in numeric.
 - DEG : Phase angle of voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st and phase angle of voltage of each harmonic from 2nd to n*th in relation to current of the 1st are printed in numeric.
 - GV : Analysis voltage value is printed in graph.
 - GA : Analysis current value is printed in graph.
 - GW : Analysis active power value is printed in graph.
 - GVD: Phase angle of voltage of each harmonic from 2nd to n*th in relation to voltage of the 1st is printed in graph.
 - GAD: Phase angle of current of each harmonic from 2nd to n^* th in relation to current of the 1st is printed in graph.
 - CGV: Relative harmonic content of voltage is printed in graph.
 - CGA: Relative harmonic content of current is printed in graph.
 - CGW: Relative harmonic content of active power is printed in graph.
 - * "n" is the upper limit of the harmonic order.

PRINt:ITEM:HARMonics:<Harmonic analysis function>[:ALL]

Function Turns printer output for the specified harmonic analysis function ON or OFF.

Syntax PRINt:ITEM:HARMonics:<Harmonic analysis
function>[:ALL] {<Boolean>}

Example PRINT:ITEM:HARMONICS:V:ALL ON

PRINt:ITEM:HARMonics:<Harmonic analysis function>:ELEMent<x>

Function Turns printer output for the specified harmonic analysis function ON or OFF/queries the current setting.

Syntax PRINt:ITEM:HARMonics:<Harmonic analysis
 function>:ELEMent<x> {<Boolean>}

PRINt:ITEM:HARMonics:<Harmonic analysis
function>:ELEMent<x>?

<x>=1

Example PRINT: ITEM: HARMONICS: V: ELEMENT1 ON

PRINT: ITEM: HARMONICS: V: ELEMENT1?

→:PRINT:ITEM:HARMONICS: V:ELEMENT1 1

PRINt:ITEM:HARMonics:PRESet

- **Function** Sets printer output items for harmonic analysis mode to the specified default setting at once.
- Example PRINT: ITEM: HARMONICS: PRESET DEFAULT1
- **Description** For a description of global setting, refer to Section 11.2, "Setting Printer Output Functions".

PRINt:ITEM:NORMal?

Function Queries all the printer output items for normal measurement mode.

Syntax PRINt:ITEM:NORMal?

Example PRINT: ITEM:NORMAL?→:PRI	NT:ITEM:
NORMAL:V:ELEMENT1 1;:PR]	NT:ITEM:
NORMAL:A:ELEMENT1 1;:PR]	NT:ITEM:
NORMAL:W:ELEMENT1 1;:PR]	INT:ITEM:
NORMAL:VA:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:VAR:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:PF:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:DEG:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:VPK:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:APK:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:WH:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:WHP:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:WHM:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:AH:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:AHP:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:AHM:ELEMENT1 0;:PR	INT:ITEM:
NORMAL:TIME 0;FREQUENCY 1; MATH	0

PRINt:ITEM[:NORMal]:<Normal measurement function>?

Function Queries the printer output ON/OFF for the specified normal measurement function.

- Syntax PRINt:ITEM[:NORMal]:<Normal measurement function>? <Normal measurement function>={V|A|W|VA|VAR|PF|DEG |VPK|APK|WH|WHP|WHM|AH|AHP|AHM}
- Example PRINT:ITEM:NORMAL:V?→:PRINT:ITEM:NORMAL: V:ELEMENT1 1

PRINt:ITEM[:NORMal]:<Normal measurement function >[:ALL]

- **Function** Turns printer output for the specified normal measurement function ON or OFF.
- Syntax PRINt:ITEM[:NORMal]:<Normal measurement
 function>[:ALL] {<Boolean>}
- Example PRINT: ITEM: NORMAL: V: ALL ON

PRINt:ITEM[:NORMal]:<Normal measurement function>:ELEMent<x>

- **Function** Turns printer output for the specified normal measurement function ON or OFF/queries the current setting.
- Syntax PRINt:ITEM[:NORMal]:<Normal measurement
 function>:ELEMent<x> {<Boolean>}
 PRINt:ITEM[:NORMal]:<Normal measurement
 function>:ELEMent<x>?
 <x>=1
- Example PRINT:ITEM:NORMAL:V:ELEMENT1 ON PRINT:ITEM:NORMAL:V:ELEMENT1?→:PRINT:ITEM: NORMAL:V:ELEMENT1 1

PRINt:ITEM[:NORMal]:{TIME|FREQuency|MATH}

- **Function** Turns communication output ON or OFF for the elapsed time of integration, frequency and computed data/queries the current setting.
- Example PRINT:ITEM:NORMAL:FREQUENCY ON PRINT:ITEM:NORMAL:FREQUENCY?→:PRINT:IT EM:NORMAL:FREQUENCY 1

PRINt:ITEM[:NORMal]:PRESet

- Function Sets printer output items for normal measurement mode to the preset settings at once.

Example PRINT:ITEM:NORMAL:PRESET DEFAULT1

Description For a description of global setting, refer to Section 11.2, "Setting Printer Output Functions (Optional)".

PRINt:PANel

Function Prints set-up information.
Syntax PRINt:PANel
Example PRINT:PANEL

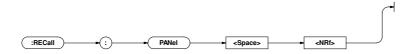
PRINt:VALue

Function Prints all the measured/computed data for the items which are set to ON using "PRINt:ITEM" commands ("PRINt:ITEM:HARMonics" through"PRINt :ITEM[:NORMal]:PRESet").

Syntax PRINt:VALue
Example PRINT:VALUE

2.3.12 RECall Group

The commands in the RECall group are used to recall set-up information. This allows you to make the same settings and inquiries which can be made using the MISC key ("RECALL" menu) on the front panel.

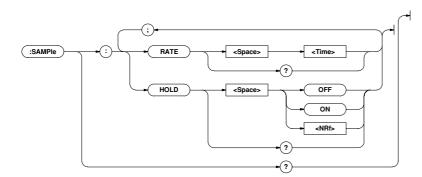


RECall:PANel

```
Function Recalls set-up information from the specified file of the
    internal memory.
Syntax RECall:PANel {<NRf>}
    {<NRf>}=1 to 4 :File no.
Example RECALL:PANEL 1
```

2.3.13 SAMPle Group

The commands in the SAMPle group are used to make settings relating to and to inquire about sampling. This allows you to make the same settings and inquiries which can be made using the HOLD and RATE keys on the front panel



SAMPle?

```
Function Queries all the current sampling settings.
Syntax SAMPle?
Example SAMPLE?→:SAMPLE:RATE 0.500E+00;HOLD 0
```

SAMPle:HOLD

 Function
 Turns hold mode for output data (display, communication data)

 ON and ON/queries the current setting.

Syntax SAMPle:HOLD {<Boolean>}
SAMPle:HOLD?

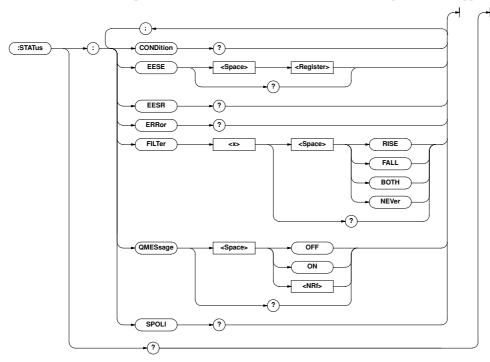
Example SAMPLE:HOLD ON SAMPLE:HOLD?→:SAMPLE:HOLD 1

SAMPle:RATE

Function Sets sample rate/queries the current setting.
Syntax SAMPle:RATE {<Time>}
 SAMPle:RATE?
 <Time>= 0.25 to 2.0sec(0.25,0.5,2.0sec)
Example SAMPLE:RATE 500MS
 SAMPLE:RATE?→:SAMPLE:RATE 0.500E+00

2.3.14 STATus Group

The commands in the STATus group are used to make settings relating to and to inquire about the communications status function. There is no front panel key for this function. For details of the status report, refer to Appendix 2.4.



STATus?

Function Queries all the settings relating to the communications status function.

Syntax STATus?

Example STATUS?→:STATUS:EESE 0;FILTER1 NEVER; FILTER2 NEVER;FILTER3 NEVER;FILTER4 NEVER; FILTER5 NEVER;FILTER6 NEVER;FILTER7 NEVER; FILTER8 NEVER;FILTER9 NEVER;FILTER10 NEVER;FILTER11 NEVER;FILTER12 NEVER; FILTER13 NEVER;FILTER14 NEVER;FILTER15 NEVER;FILTER16 NEVER;QMESSAGE 1

STATus:CONDition?

Function Queries the contents of the condition register.

- Syntax STATus:CONDition?
- Example STATUS:CONDITION→16
- **Description** For a description of the condition register, refer to Appendix 2.4, "Status Report".

STATus:EESE

```
Function Sets the extended event enable register/queries the current setting.
```

Syntax STATus:EESE <Register>
STATus:EESE?

```
<Register>=0 to 65535
```

Example STATUS: EESE 257

```
STATUS:EESE?→:STATUS:EESE 257
```

Description For a description of the extended event enable register, refer to Appendix 2.4, "Status Report".

STATus:EESR?

Function Queries the contents of the extended event register and clears the register.

Syntax STATUS: EESR?

Example STATUS: EESR?→1

Description For a description of the extended event register, refer to Appendix 2.4, "Status Report".

STATus:ERRor?

Function Queries the code and the message (at the beginning of the error queue) of the error which has occurred.

Syntax STATus:ERRor?

Example STATUS:ERROR?→113, "Undefined header"

STATus:FILTer<x>

Function Queries all the settings relating to the specified transit filter/ queries the current settings.

Syntax STATus:FILTer<x>

{RISE|FALL|BOTH|NEVer}

STATus:FILTer<x>?

<x>=1~16

Example STATUS: FILTER2 RISE

STATUS:FILTER2?→:STATUS:FILTER2 RISE

Description For a description of the transit filter, refer to Appendix 2.4, "Status Report".

STATus:QMESsage

Function Selects whether or not to add the message contents to a response to "STATUS:ERROr?"/queries the current setting.

Syntax STATus:QMESsage {<Boolean>} STATus:QMESsage? Example STATUS:OMESSAGE OFF

STATUS:QMESSAGE 0 STATUS:QMESSAGE?→:STATUS:QMESSAGE 0

STATus:SPOLI?(Serial Poll)

Function Executes serial poll. Syntax STATUS:SPOLL? Example STATUS:SPOLL?→STATUS:SPOLL 0 Description This command is available only for the RS-232-C interface.

2.3.15 STORe Group

The commands in the STORe group are used to make settings relating to and to inquire about storage of set-up information. This allows you to make the same settings and inquiries which can be made using the MISC key ("StoreE" menu) on the front panel.

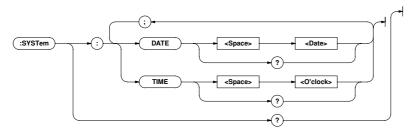


STORe:PANel

Function Stores set-up information in the internal memory
Syntax STORe:PANel {<NRf>}
 {<NRf>}=1 to 4 :File no.
Example STORE:PANEL 1

2.3.16 SYSTem Group

The commands in the SYSTem group are used to make settings relating to and to inquire about system (internal clock). This allows you to make the same settings and inquiries which you can make using the MISC key ("dAtE" menu) on the front panel.



SYSTem?

Function Queries all the system (internal clock) settings.
Syntax SYSTEm?
Example SYSTEM?→:SYSTEM:DATE 96,4,1;TIME 17,15,0

SYSTem:DATE

Function Sets the date/queries the current setting.

```
Syntax SYSTem:DATE {<Date>}
```

```
SYSTem:DATE?
{<Date>}={<NRf>,<NRf>,<NRf>|<Character
string>}
{<NRf>,<NRf>,<NRf>]=[19]96,1,1,[20]95,12,
```

```
31{<Character string>}="[YY]YY/MM/DD"
```

[YY]YY: Year MM: Month DD: Day

```
Example SYSTem:DATE 96,4,1
```

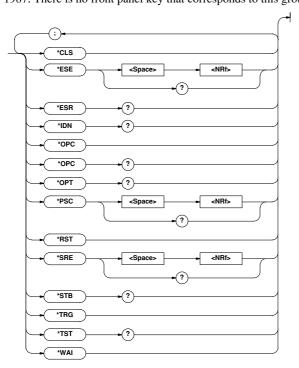
```
SYSTem:DATE 1996,04,01
SYSTem:DATE "96/04/01"
SYSTem:DATE "1996/4/1"
SYSTEM:DATE?→:SYSTEM:DATE 96,4,1
```

SYSTem:TIME

```
Function Sets the time/queries the current setting.
Syntax SYSTem:TIME {<0'clock>}
SYSTem:TIME?
{<0'clock>}={<NRf>,<NRf>[,<NRf>]|
<Character string>}
{<NRf>,<NRf>[,<NRf>]}=0,0,0,23,59,59
{<Character string>}="HH:MM[:SS]"
HH: Hour MM: Minute SS: Second
Example SYSTem:TIME 17,15,0
SYSTem:TIME 17,15
SYSTem:TIME "17:15:0"
SYSTEM:TIME "17:15:0"
SYSTEM:TIME "17:15.0"
Description If second (SS) is not set, it will be 0 second.
```

2.3.17 Common Command Group

The commands in the common command group are independent of the instrument's functions, and are specified in IEEE 488.2-1987. There is no front panel key that corresponds to this group.



*CLS

Function Clears the standard event register, extended event register and error queue.

Syntax *CLS

 $\textbf{Example} \ *\texttt{CLS}$

Description • The output queue will also be cleared if a "*CLS" command is appended after the program message terminator.

• For details of the registers and queues, refer to Appendix 2.4.

*ESE

Function Sets the value for the standard event enable register/queries the current setting.

Syntax *ESE {<NRf>}

```
*ESE?
```

{<NRf>}=0 to 255

```
Example *ESE 251
```

*ESE?→251

Description • <NRf> is the sum of the bits expressed as a decimal number.

• For example, if "*ESE 251" is set, the standard event enable register will be set to "111111011". This means that bit 2 of the standard event register is disabled so that bit 5 (ESB) of the status byte register will not be set to "1", even if a query error occurs.

- Default is "0", i.e. all bits are disabled.
- The standard event enable register will not be cleared, even if a query is made using "*ESE?".
- For details of the standard event enable register, refer to App 2-50.

*ESR?

Function Queries the value of the standard event register and clears it at the same time.

Syntax *ESR?

Example *ESR?→32

- Description The sum of the bits is returned as a decimal value.
 - It is possible to ascertain the type of event which has occurred, while SRQ is occurring.
 - For example, if "32" is returned, this means that the standard event register is "00100000", i.e. the SRQ has occurred due to a command syntax error.
 - If a query is made using "*ESR?", the standard event register will be cleared.
 - For details of the standard event register, refer to page App 2-50.

*IDN?

Function Queries the instrument model.

Syntax *IDN?

- Example *IDN?→YOKOGAWA,253101,0,F1.01
- Description A reply consists of the following sequence: <Manufacturer>, <Model>, <Serial No.> and <Firmware version>.

*OPC

Function This command sets bit 0 of the standard event register to "1" when execution of the specified overlap command has been completed. This command will be ignored since overlap commands are not supported by this instrument.

Syntax *OPC

*OPC?

Function "1" will be returned if execution of the designated overlap command has been completed. "1" will always be returned since overlap commands are not supported by this instrument.
Syntax *OPC?

Syntax "OPC

*OPT?

Function Queries installed options.

Syntax *OPT?

Example *OPT?→DA, PRINTER, HARMONICS, FLICKER

Description • "None" will be attached to the reply if no options are installed.
 "*OPT?" must always be the last query in a program message. If there is another query after "*OPT?", an error will occur.

*PSC

Function Selects whether or not to clear the following registers when power is turned ON/queries the current setting. However, they cannot be cleared if the parameter is "0".

• Standard event enable register

- Extended event enable register
- Transit filter

Syntax *PSC {<NRf>}

*PSC?

<<NRf>}= 0 (does not clear the registers) value other than 0 (clears the registers)

Example *PSC 1

*PSC?→1

Description For details of each register, refer to Appendix 2.4.

*RST

Function Resets (initialize) the current settings.

Syntax *RST

Example *RST

Description For a detailed description, refer to Section 13.1, "Storing, Recalling and Initializing Set-up Information". All the set-up information except for those relating to communication are reset.

*SRE

Function Sets the value of the service request enable register/queries the current setting.

Syntax *SRE {<NRf>}

*SRE?

{<NRf>}=0 to 255

Example *SRE 239

 $*SRE? \rightarrow 175$ (since the setting of bit 6 (MSS) is ignored) Description • <NRf> is the sum of the bits expressed as a decimal number.

- For example, if "*SRE 239" is set, the service request enable register will be set to "11101111". This means that bit 4 of the service request enable register is disabled, so that bit 4 (MAV) of the status byte register will not be set to "1", even if the output queue is not empty.
- However, bit 6 (MSS) of the status byte register is the MSS bit, so it will be ignored.
- Default is "0", i.e. all bits are disabled.
- The service request enable register will not be cleared, even if a query is made using "*SRE?".

• For details of the service request enable register, refer to page App 2-55.

*STB?

Function Queries the value of the status byte register.

Syntax *STB?

```
Example *STB?→4
```

- $\ensuremath{\text{Description}}$ $\ensuremath{\cdot}$ The sum of the bits expressed as a decimal value is returned.
 - Bit 6 is MSS not RQS, since the register is read without serial polling.
 - For example, if "4" is returned, the status byte register is set to "00000100", i.e. the error queue is not empty (an error has occurred).
 - The status byte register will not be cleared, even if a query is made using "*STB?".
 - For details of the status byte register, refer to page App 2-56.

*TRG

Function Carries out the same function as when the TRIG key (SHIFT + HOLD) is pressed.

Syntax *TRG

Description The GET (Group Execute Trigger) multi-line message also carried out the same function as this command.

*TST?

```
Function Executes a self-test and queries the test result. All internal memories boards are tested.
```

```
Syntax *TST?
```

Example *TST?→0

```
Description • "0" will be returned if the self test result is satisfactory. "1" will be returned if an abnormality is detected during the test.
```

*WAI

```
Function Waits for the command following "*WAI" until execution of
the designated overlap command has been completed. This
command will be ignored since overlap commands are not
supported by this instrument.
```

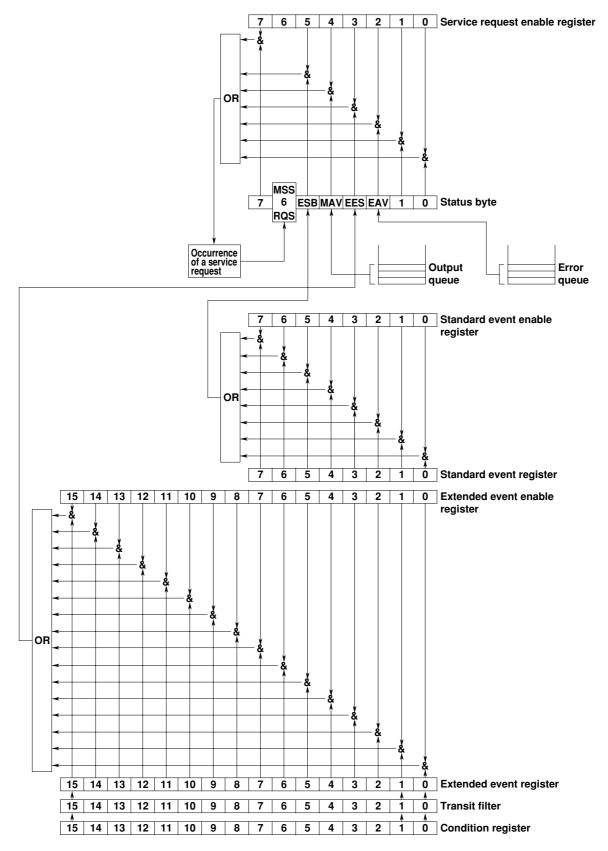
Syntax *WAI

Appendix 2.4 Status Report

2.4.1 Status Report

Overview of the Status Report

The figure below shows the status report which is read by a serial poll. This is an extended version of the one specified in IEEE 488.2-1987.



Appendix 2.4 Status Report

Overview of Registers and Queues

Name	Function	Reading					
Status byte			Serial poll				
			RQS), *STB?(MSS)				
Service request	Masks status byte.	*SRE	*SRE?				
enable register							
Standard event register	Event in the instrument	_	*ESR?				
Standard event	Masks standard	*ESE	*ESE?				
enable register	event register.						
Extended event register	Event in the instrument	_	STATUS: EESR?				
Extended event	Masks extended	STATus: EESE	STATUS: EESE?				
enable register	event register.						
Condition register	Current instrument	_	STATus:CONDition?				
	status						
Transit filter	Extended event	STATus:FILTer	STATus:FILTer <x>?</x>				
	occurrence register	<x></x>					
	conditions						
Output queue	Stores response	All queries					
	message to a query.						
Error queue	Stores error Nos.	_	STATus:ERRor?				
	and messages.						

Registers and Queues which Affect the Status Byte

Registers which affect each bit of the status byte are shown below

Standard event register	: Sets bit 5 (ESB) of status byte to
	"1" or "0".
Output queue	: Sets bit 4 (MAV) of status byte to
	"1" or "0".
Extended event register	: Sets bit 3 (EES) of status byte to
	"1" or "0".
Error queue	: Sets bit 2 (EAV) of status byte to
	"1" or "0".

Enable Registers

Registers which mask a bit so that the bit does not affect the status byte, even if the bit is set to "1", are shown below.

Status byte	: Masks bits using the service event
	enable register.
Extended event register	: Masks bits using the extended
	event enable register.

Writing/Reading from Registers

The ***ESE** command is used to set bits in the standard event enable register to "1" or "0", and the ***ESE**? query is used to check whether bits in that register are set to "1" or "0". For details of these commands, refer to Appendix 2.3.

2.4.2 Status Byte

Overview of Status Byte

 RQS

 7
 6
 ESB |MAV| EES | EAV | 1
 0

 MSS

• Bits 0, 1 and 7

Not used (always "0")

Bit 2 EAV (Error Available)

Set to "1" when the error queue is not empty, i.e. when an error occurs. For details, refer to page App 2-60.

• Bit 3 EES (Extended Event Summary Bit)

Set to "1" when a logical AND of the extended event register and the corresponding enable register is "1", i.e. when an event takes place in the instrument. Refer to page App 2-59.

• Bit 4 MAV (Message Available)

Set to "1" when the output queue is not empty, i.e. when there is data which is to be output when a query is made. Refer to page App 2-60.

Bit 5 ESB (Event Summary Bit)

Set to "1" when a logical AND of the standard event register and the corresponding enable register is "1", i.e. when an event takes place in the instrument. Refer to page App 2-58.

Bit 6 RQS (Request Service)/MSS (Master Status Summary)

Set to "1" when a logical AND of the status byte (except for bit 6) and the service request enable register is not "0", i.e. when the instrument is requesting service from the controller. RQS is set to "1" when MSS changes from "0" to "1", and is cleared when a serial poll is performed or when MSS changes to "0".

Bit Masking

To mask a bit in the status byte so that it does not cause an SRQ, set the corresponding bit of the service request enable register to "0". For example, to mask bit 2 (EAV) so that no service will be requested, even if an error occurs, set bit 2 of the service request enable register to "0". This can be done using the *SRE command. To query whether each bit of the service request enable register is "1" or "0", use *SRE?. For details of the *SRE command, refer to Appendix 2.3.

Operation of the Status Byte

A service request is issued when bit 6 of the status byte becomes "1". Bit 6 becomes "1" when any of the other bits becomes "1" (or when the corresponding bit in the service request enable register becomes "1"). For example, if an event takes place and the logical OR of each bit of the standard event register and the corresponding bit in the enable register is "1", bit 5 (ESB) will be set to "1". In this case, if bit 5 of the service request enable register is "1", bit 6 (MSS) will be set to "1", thus requesting service from the controller. It is also possible to check what type of event has occurred by reading the contents of the status byte.

Reading from the Status Byte

The following two methods are provided for reading the status byte.

• Query using the *STB? query

Making a query using the ***STB?** query sets bit 6 to MSS. This causes the MSS to be read. After completion of the read-out, none of the bits in the status byte will be cleared.

Serial poll

Execution of a serial poll changes bit 6 to RQS. This causes RQS to be read. After completion of the read-out, only RQS is cleared. Using a serial poll, it is not possible to read MSS.

Clearing the Status Byte

No method is provided for forcibly clearing all the bits in the status byte. Bits which are cleared are shown below.

- When a query is made using the *STB? query No bit is cleared.
- When a serial poll is performed Only the RQS bit is cleared.

• When the *CLS command is received When the *CLS command is received, the status byte itself is not cleared, but the contents of the standard event register (which affects the bits in the status byte) are cleared. As a result, the corresponding bits in the status byte are cleared, except bit 4 (MAV), since the output queue cannot be emptied by the *CLS command. However, the output queue will also be cleared if the *CLS command is received just after a program message terminator.

2.4.3 Standard Event Register

Overview of the Standard Event Register

7	6	5	4	3	2	1	0
PON	URQ	СМЕ	EXE	DDE	QYE	RQC	OPC

• Bit 7 PON (Power ON)

Set to "1" when power to the instrument is turned ON

- Bit 6 URQ (User Request) Not used (always "0")
- Bit 5 CME (Command Error) Set to "1" when the command syntax is incorrect. Examples: Incorrectly spelled command name
- Bit 4 EXE (Execution Error)

Set to "1" when the command syntax is correct but the command cannot be executed in the current state.

Examples: Parameters are outside the setting range.

Bit 3 DDE (Device Error)

Set to "1" when execution of the command is not possible due to an internal problem in the instrument that is not a command error or an execution error.

Bit 2 QYE (Query Error)

Set to "1" if the output queue is empty or if the data is missing even after a query has been sent.

Examples: No response data; data is lost due to an overflow in the output queue.

- Bit 1 RQC (Request Control) Not used (always "0")
- Bit 0 OPC (Operation Complete)

Set to "1" when the operation designated by the ***OPC** command has been completed.

Bit Masking

To mask a bit in the standard event register so that it does not cause bit 5 (ESB) of the status byte to change, set the corresponding bit in the standard event enable register to "0". For example, to mask bit 2 (QYE) so that ESB will not be set to "1", even if a query error occurs, set bit 2 of the standard event enable register to "0". This can be done using the ***ESE** command. To query whether each bit of the standard event enable register is "1" or "0", use the ***ESE**?. For details of the ***ESE** command, refer to Appendix 2.3.

Operation of the Standard Event Register

The standard event register is provided for eight different kinds of event which can occur inside the instrument. Bit 5 (ESB) of the status byte is set to "1" when any of the bits in this register becomes "1" (or when the corresponding bit of the standard event enable register becomes "1").

Examples

- 1. A query error occurs.
- 2. Bit 2 (QYE) is set to "1".

3. Bit 5 (ESB) of the status byte is set to "1" if bit 2 of the standard event enable register is "1"

It is also possible to check what type of event has occurred inside the instrument by reading the contents of the standard event register.

Reading from the Standard Event Register

The contents of the standard event register can be read by the ***ESR** command. After completion of the read-out, the register will be cleared.

Clearing the Standard Event Register

The standard event register is cleared in the following three cases.

- When the contents of the standard event register are read using *ESR?
- When the *CLS command is received
- · When power is turned ON again

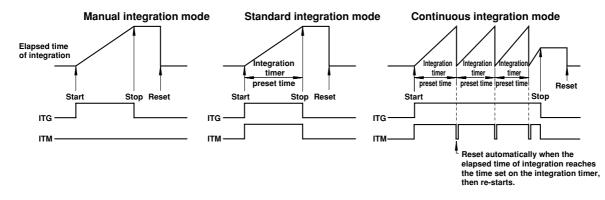
2.4.4 Extended Event Register

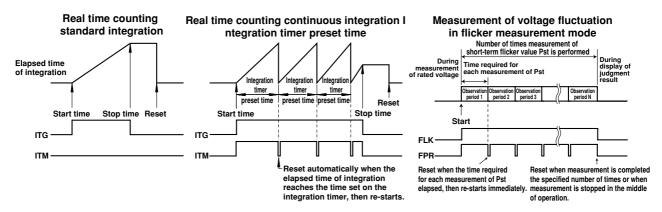
The extended event register contains the results obtained due to a change in state of the condition register (indicating the internal state of the instrument) which is detected by the transit filter.

FILTer <x>-</x>	→16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1
Condition register :STATus:CONDition?	15 0	14 0	13 ₀	12 ₀	11 0	10 ₀	9 0	8 POA1	7 POV1	6 0VR1	5 PRN	4 FOV	3 0VPS	2	1 ITG/FLK	0 UPD
	,	¥.	٠ ۲	¥	¥.	¥	¥.	V	V	V	Y	¥	V	V	V	V
Transit filter :STATus:FILTer <x></x>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	Ó
{RISE FALL BOTH NEVer}	4	¥		¥	¥	¥	¥	. ↑	¥	¥	¥	¥	۰,	. ↑	¥	¥
Extended event register :STATus:EESR?	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Function of each bit of the condition register is described below.

Bit 0	UPD(Updating)	Bit 0 Set to "1" during update of measured data. UPD changes from "1" to "0" when update is
DII U	Of D(Optianing)	
		complete.
Bit 1	ITG(Integrate busy)	Set to "1" during integration. (See the figure below.)
	FLK (Flicker busy)	Set to "1" while measurement of voltage fluctuation is in operation in flicker measurement mode
		(See the next page.)
Bit 2	ITM(Integrate timer busy)	Set to "1" while integration time is in operation. (See the figure below.)
	FPR (Flicker period)	Set to "1" while measurement of voltage fluctuation for each observation period is in operation
		in flicker measurement mode. (See the next page.)
Bit 3	OVRS (MATH results overflow)	Set to "1" when an overflow occurs in measured/computed data (computation result) for which
		the element cannot be identified. ("oF" is displayed.)
Bit 4	FOV(Frequency Over)	Set to "1" when the measured frequency is outside the range. ("ErrLo", "ErrHi" or "FrqEr" is
		displayed.)
Bit 5	PRN(PRiNter busy)	Set to "1" while the built-in printer is in operation.
Bit 6	OVR1(Element1 mesured data over)	Set to "1" when an overflow or error occurs in measured/computed data for element 1.
		("oL", "PFErr", "dEGEr" or "oF" is displayed.)
Bit 7	POV1(Element1 voltage peak over)	Set to "1" when a peak over occurs in voltage value for element 1.
Bit 8	POA1(Element1 current peak over)	Set to "1" when a peak over occurs in current value for element 1.





Parameters of the transit filter detect a change in the specified bit of the condition register, then re-write the contents of the extended event register as shown below.

RISE	Sets the specified bit of the extended event register to "1" when changes from "0" to "1".	
FALL	Sets the specified bit of the extended event register to "1" when changes from "1" to "0".	
BOTH	Sets the specified bit of the extended event register to "1" when changes from "0" to "1" or from "1" to "0".	
NEVer	Always set to "0".	

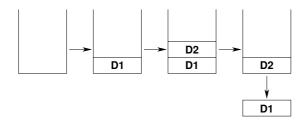
2.4.5 Output Queue and Error Queue

Overview of the Output Queue

The output queue is provided to store response messages to queries. For example, when the MEASure[:NORMal]:VALue? query is sent to request output of the measured data, the response data will be stored in the output queue until it is read out. The example below shows that data is stored record by record in the output queue, and is read out oldest item first, newest item last. The output queue is emptied in the following cases (in addition to when read-out is performed).

- · When a new message is received from the controller
- When dead lock occurs (page App 2-4)
- When a device clear command (DCL or SDC) is received
- · When power is turned ON again

The output queue cannot be emptied using the *CLS command. To see whether the output queue is empty or not, check bit 4 (MAV) of the status byte.



Overview of the Error Queue

The error queue stores the error No. and message when an error occurs. For example, when the controller sends an incorrect program message, an error occurs and its error No. 113 and message "Undefined header" will be stored in the error queue. The contents of the error queue can be read using the STATus: ERRor? query. Like the output queue, messages are read in the order oldest first, newest last. If the error queue is full, the final message will be replaced by message 350, "Queue overflow"

The error queue is emptied in the following cases (in addition to when read-out is performed).

- When the *CLS command is received
- · When power is turned ON again

To see whether the error queue is empty or not, check bit 2 (EAV) of the status byte.

Appendix 2.5 Sample Programs

Operating Environment for Sample Programs

- Computer : IBM PC/AT and compatible system with National Instruments AT-GPIB/TNT IEEE-488.2 board installed
- OS : Quick Basic version 4.0/4.5

Note

• When the message of GPIBERR or DVMERR is returned, refer to "NI-488.2 Driver Sample Programs".

Sample Programs

```
**********
and read
         REM $INCLUDE: 'qbdecl.bas'
         DECLARE SUB gpiberr (msg$)
DECLARE SUB dvmerr (msg$, SPR%)
         DIM D$(4)
          CLS
PRINT
         CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%)
CALL IBFIND("DEV1", dvm%)
IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
      clear the device.
CALL IBCLR(dvm%)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibclr Error")
      set measurement condition.
WRT$ = "SAMPLE:RATE 0.5S;HOLD OFF"
CALL IBWRT(dvm8, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "VOLTAGE:MODE RMS"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "CURRENT:MODE RMS"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "FILTER OFF"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
         WRT$ = "SCALING OFF;AVERAGING OFF"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERN) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "VOLTAGE:RANGE 100V"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
         WRT$ = "CURRENT:RANGE 5A"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
         WRT$ = "DISPLAY4:FUNCTION VHZ;ELEMENT 1"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "MEASURE:ITEM:PRESET DEFAULT1"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
          WRT$ = "MEASURE:FORMAT ASCII"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
         FOR J = 1 TO 500000: NEXT J
         WRT$ = "STATUS:FILTER1 FALL"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERN THEN CALL gpiberr("Ibwrt Error")
         FOR I = 1 TO 10
WRT$ = "STATUS:EESR?"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
                          WRT$ = "COMMUNICATE:WAIT 1"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
                         WRT$ = "MEASURE:VALUE?"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
                    'read measurement data.
RD$ = SPACE$(512)
CALL IBRD(dvm%, RD$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
                      IF (inc

C$ = RD$

FOR K = 0 TO 3

L = INSTR(C$, ",")

B = INSTR(C$, ",")

IF B = 0 THEN B = INSTR(C$, " ")

D$(K) = LEFT$(C$, (B - 1))

C$ = MID$(C$, (B + 1), L)

THE K

C$ = MID$(C$, (B + 1), L)

THE K

C$ = NOTEL

        C$ = MLD$(C$, (B - 1))

NEXT K

PRINT "ELEMENT1: ", D$(0), D$(1), D$(2)

PRINT "Frquency: ", D$(3)

NEXT I
          Call the IBONL function to disable the hardware and software. CALL IBONL(dvm%, 0)
END
```

<pre>************************************</pre>			
* elapsed time of integration (IMTEG-TIME) *			
' REM \$INCLUDE: 'qbdecl.bas'			
DECLARE SUB gpiberr (msg\$) DECLARE SUB dvmerr (msg\$, SPR%) DIM D\$(7)			
CLS PRINT			
CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%) IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")			
' clear the device. CALL IBCLR(dvm%) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibclr Error")			
<pre>' set measurement condition. WRT\$ = "SAMPLE:HOLD OFF" CALL IBURT(dvm\$, WRT\$) IF (UBGR0\$ AND FERD) "UPUN CALL cobcer("Thurt From")</pre>			
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") WRT\$ = "VOLTAGE:MODE RMS" CALL IBWRT(JWR%, WRT\$)			
CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") WRT\$ = "CURRENT:MODE RMS" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
<pre>IF (LBSTA& AND EEKR) THEN CALL gplderr("ldwrt Error") WRT\$ = "FILTER OFF" CALL IBWRT(dvm&, WRT\$)</pre>			
IF (IBSTA% AND EERR) THEN CALL gpiberr("Idwrt Error")			
WRT\$ = "SCALING OFF;AVERAGING OFF" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") WRT\$ = "VOLTAGE:RANGE 100V"			
CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "CURRENT:RANGE 5A" CALL IBWRT(dvm#, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "INTEGRATE:MODE NORMAL" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "INTEGRATE:TIMER 1,0" CALL IBWRT(dvm&, WRT\$) IF (IBSTA& AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "MEASURE:ITEM:PRESET DEFAULT2" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "MEASURE:ITEM:FREQUENCY OFF;AH OFF;AHP OFF;AHM OFF" CALL IBWRT(dvm%, WRT\$)			
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") WRT\$ = "MEASURE:FORMAT ASCII" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
'wait FOR I = 1 TO 500000: NEXT I			
WRT\$ = "STATUS:FILTER1 FALL" CALL IBWRT(dvm&, WRT\$) IF (IBSTA& AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "STATUS:FILTER2 FALL" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
WRT\$ = "STATUS:EESR?" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
RD\$ = SPACE\$(10) CALL IBRD(dvm&, RD\$) IF (IBSTA& AND EERR) THEN CALL gpiberr("Ibrd Error")			
WRT\$ = "INTEGRATE:START" CALL IBWRT(dvm%, WRT\$) IF (IBSTA& AND EERR) THEN CALL gpiberr("Ibwrt Error") FLAG = 0			
RDAR = 0 RDDAR: WRT\$ = "COMMUNICATE:WAIT 3" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") RD\$ = SPACE\$(10) CALL IBRD(dvm%, RD\$)			
CALL IBRD(dvm%; RD\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error") IF (VAL(RD\$) AND &H2) <> 0 THEN FLAG = 1			
WRT\$ = "MEASURE:VALUE?" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")			
RD\$ = SPACE\$(512) CALL IBRD(dvm%, RD\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")			
C\$ = LEFT\$(RD\$, IBCNT\$)FOR K = 0 TO 6L = LEN(C\$)B = INSTR(C\$, ",")IF B = 0 THEN B = L + 1			
B = INSTR(C\$, ",") IF B = 0 THEN B = L + 1 D\$(X) = LEFT\$(C\$, (B - 1)) C\$ = MID\$(C\$, (B + 1), L) NEXT K PRINT "Ltg Time: ", D\$(1) + ":" + D\$(2) + ":" + D\$(3)			
PRINT "Itg Time: ", D\$(1) + ":" + D\$(2) + ":" + D\$(3) PRINT "ELEMENT1: ", D\$(0), D\$(4), D\$(5), D\$(6) PRINT			
IF FLAG $<>$ 1 THEN GOTO RDDAT ' Call the IBONL function to disable the hardware and software. CALL IBONL(dwn [®] , 0)			
CALL IBONL(dvm*, 0) END			

```
END
```

Appendix 2.5 Sample Programs

```
Sample Program (3) for the WT2000 series
      Used to read and display the following data in harmonic analysis mode.
Total rms value of each harmonic from 1st to 50th of current.
analysis value of fundamental (1st) of current, analysis value of each harmonic
(2nd to 50th), harmonic distortion of current, PLL source (voltage) frequency
      *****
      REM $INCLUDE: 'qbdecl.bas'
       DIM D$(52)
       DECLARE SUB gpiberr (msg$)
DECLARE SUB dvmerr (msg$, SPR%)
       CLS
PRINT
       CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%)
IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
    clear the device.
CALL IBCLR(dvm%)
IF (IBSTR% AND EERR) THEN CALL gpiberr("Ibclr Error")
    set measurement condition.
WRT$ = "HARMONICS:SYNCHRONIZE V,1"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "HARMONICS:FILTER OFF"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "HARMONICS:THD IEC"
        CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "HARMONICS:ORDER 50"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "HARMONICS ON"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       FOR I = 1 TO 1000000: NEXT I
       WRT$ = "MEASURE:ITEM:HARMONICS:PRESET CLEAR"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "MEASURE:ITEM:HARMONICS:A:ELEMENT1 ON"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "MEASURE:ITEM:HARMONICS:ATHD:ELEMENT1 ON"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "MEASURE:ITEM:HARMONICS:SYNCHRONIZE ON"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
        WRT$ = "MEASURE:FORMAT ASCII"
       CALL IBWRT(dwm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "SAMPLE:HOLD ON"
        CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
       WRT$ = "MEASURE:VALUE?"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERN) THEN CALL gpiberr("Ibwrt Error")
       'read measurement data.
RD$ = SPACE$(1024)
CALL IBRD(dvm%, RD$)
IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
      C$ = MID$(C$, '(B + 1), L)'

NEXT J

PRINT "TOTAL : ", D$(0)

PRINT "FREQUENCY: ", D$(52)

PRINT "FREQUENCY: ", D$(52)

PRINT "1: ", D$(1), " 2: ", D$(2)

PRINT "3: ", D$(3), " 4: ", D$(4)

PRINT "5: ", D$(5), " 6: ", D$(6)

PRINT "9: ", D$(9), " 10: ", D$(10)

PRINT "11: ", D$(11), " 12: ", D$(12)

PRINT "11: ", D$(11), " 12: ", D$(12)

PRINT "11: ", D$(11), " 14: ", D$(14)

PRINT "15: ", D$(51), " 16: ", D$(16)

PRINT "15: ", D$(15), " 16: ", D$(16)

PRINT "15: ", D$(12), " 20: ", D$(22)

PRINT "15: ", D$(12), " 20: ", D$(22)

PRINT "23: ", D$(23), " 24: ", D$(24)

PRINT "23: ", D$(23), " 24: ", D$(24)

PRINT "25: ", D$(25), " 26: ", D$(30)

PRINT "31: ", D$(31), " 32: ", D$(32)

PRINT "31: ", D$(41), " 42: ", D$(42)

PRINT "41: ", D$(43), " 44: ", D$(44)

PRINT "41: ", D$(44), " 46: ", D$(46)

PRINT "41: ", D$(45), " 60: ", D$(50)

PRINT "49: ", D$(51)

WET$ = "GAMPLE: HOLD OFF"
       WRT$ = "SAMPLE:HOLD OFF"
CALL IBWRT(dvm%, WRT$)
IF (IBSTA% AND EERN THEN CALL gpiberr("Ibwrt Error")
       Call the IBONL function to disable the hardware and software. CALL IBONL(dvm%, 0)
END
```

'* Sample Program (4) for the WT2000 series *
<pre>'* Used to set measurement conditions/ranges for normal measurement mode, and read '* and display the following data each time measured/computed data is updated. '* Binary data: voltage (V), current (A), active power (W), voltage frequency (VHz) '*</pre>
REM \$INCLUDE: 'qbdecl.bas' DECLARE SUB gpiberr (msg\$)
DECLARE SUB dvmerr (msg\$, SPR%)
DIM DT(4) CLS PRINT
CALL IBDEV(0, 1, 0, T10s, 1, 0, dvm%) IF (dvm% < 0) THEN CALL gpiberr("Ibdev Error")
' clear the device. CALL IBCLR(dvm%) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibclr Error")
' set measurement condition. WRT\$ = "SAMPLE:RATE 0.55;HOLD OFF" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "VOLTAGE:MODE RMS" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "CURRENT:MODE RMS" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "FILTER OFF" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "SCALING OFF;AVERAGING OFF" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "VOLTAGE:RANGE 100V" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "CURRENT:RANGE 5A" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "DISPLAY4;FUNCTION VH2;ELEMENT 1" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "MEASURE:ITEM:PRESET DEFAULT1" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "MEASURE:FORMAT BINARY" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
FOR I = 1 TO 500000: NEXT I
WRT\$ = "STATUS:FILTER1 FALL" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
FOR I% = 1 TO 10 WRT\$ = "STATUS:EESR?" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
RD\$ = SPACE\$(10) CALL IBRD(dvm%, RD\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
WRT\$ = "COMMUNICATE:WAIT 1" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error")
WRT\$ = "MEASURE:VALUE?" CALL IBWRT(dvm%, WRT\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibwrt Error") 'road measurement data
'read measurement data. RD\$ = SPACE\$(512) CALL IBRD(dvm%, RD\$) IF (IBSTA% AND EERR) THEN CALL gpiberr("Ibrd Error")
N = 0 FOR J = 7 TO 22 STEP 4
P\$ = MID\$(RD\$, J + 3, 1): SP = CVI[P\$ + CHR\$(0)) O\$ = MID\$(RD\$, J + 2, 1): SO = CVI[Q\$ + CHR\$(0)) R\$ = MID\$(RD\$, J + 1, 1): SR = CVI[R\$ + CHR\$(0)) T\$ = MID\$(RD\$, J + 0, 1): SS = CVI[T\$ + CHR\$(0)) T\$ = RIGHT\$("0" + HEX\$(SS), 2) + RIGHT\$("0" + HEX\$(SR), 2) + R IGHT\$("0" + HEX\$(SQ), 2) + RIGHT\$("0" + HEX\$(SP), 2)
FOR K = 1 10 ° MD(T$, K, 1)$ IF A(K) = "D0"$ THEN b(K) = "0000"$
IF $AS(K) = "1"$ THEN $bS(K) = "0001"$ IF $AS(K) = "2"$ THEN $bS(K) = "0010"$ IF $AS(K) = "3"$ THEN $bS(K) = "0011"$ IF $AS(K) = "4"$ THEN $bS(K) = "0100"$
TF AS(K) = "5" THEN BS(K) = "0101"
IF $A_{S}(K) = "7"$ THEN $b_{S}(K) = "0111"$ IF $A_{S}(K) = "8"$ THEN $b_{S}(K) = "1000"$
F AS(K) = "A" "HEN DS(K) = "1010"
IF $A_{S}^{c}(K) = "C"$ THEN $b_{S}^{c}(K) = "1100"$ IF $A_{S}^{c}(K) = "D"$ THEN $b_{S}^{c}(K) = "1101"$
$\begin{array}{c} \text{IF } A \S(K) = \text{"F" THEN } b \S(K) = \text{"IIII"} \\ \text{NEXT } K \end{array}$
$ b \\ b \\ b \\ b \\ c \\ 1 \\ b \\ c \\ 1 \\ b \\ c \\ 1 \\ c \\$
$E = E + (2 \land L) * VAL(MID$(E$, (8 - L), 1))$
$W_{8}^{\text{NLM} I} = MID_{8}(b_{8}^{\text{NLM}}, 10, 23)$ FOR M = 1 TO 23 F = F + (2 ^ (-M)) * VAL(MID_{8}^{\text{NLM}}, M, 1)) NEXT M
$F = F + 1DT(N) = ((-1)^{U} + (2^{(E-127)}) + FIF DT(N) < 1E-12 THEN DT(N) = 0N = N + 1$

Appendix

```
NEXT J

PRINT "MEASURE DATA"

PRINT "ELEMENT1 : ", DT(0), DT(1), DT(2)

PRINT "FREQUENCY: ", DT(3)

NEXT 1%

' Call the IBONL function to disable the hardware and software.

CALL IBONL(dvm%, 0)

END
```

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Appendix 2.6 ASCII Character Code

ASCII character codes are given below.

	0	1		2		3		4			5		6		7
0								-				140	0 د	160	p
		10 16						-				60	96	70	-
1	1 GTL SOH	21 LLO	41	!	1 61	1		¹⁰¹			-		a ¹		
		11 17	21	- 3	3 31										
2	2	²² DC2	42		2 62		18	102	2	122		142	b 2		
	2 2	12 18	22	3	4 32		50	42	66	52	82	62	98	72	11
3	³ ETX	²³ DC3		#	3 63	3		¹⁰³ C					з С	163	
		13 19			-									-	
4		DC4		\$	4 64	4		D			Т				t
	4 4		24	3	6 34		52	44	68	54	84	64	100	74	11
5		NAK		%		5		E	1		U				u
_	5 5 6	15 21 26	25	3	7 35		53	45	69	55	85	65	101 6	75	11
6		SYN		&		6		F			V		f		V
7	6 6	16 22 27	26 47	3	8 36 7 67		54 23	46	70	56 127	86	66 147	102 7	167	2
7	BEL	ETB		,		7		G	Ì		W		g		W
8	7 7 10 GET		50		9 37 8 70								8		
0	BS	CAN 18 24		(8		Н			Χ		h		X
9	11 TCT	31 SPD	51										9		
0	HT	EM)		9					Υ		i		У
A	12		52								26		10		
	A 10	1A 26	2A	4	2 3A		58	4A	74	5A			-	7A	12
В	13	³³ ESC	53	1 +	1 73				. 11				¹¹		
	B 11	1B 27		4	3 3B						91	6B	107	7B	12
С	¹⁴ FF	³⁴ FS	54	1: ,	2 74	<	28	114 L	12	134	\ \	154	12	174	2
	C 12		2C	4			60	4C	76		92	6C		7C	12
D		³₅GS	55	-		=	29	¹¹⁵	I	135]		m	175	}
_	D 13	1D 29 36	2D 56	4			61 30	4D 116	77	5D 136	93 30	6D 156	109	7D	12
E	SO	RS		•		>		Ν			۸		n		~
F	E 14	1E 30 37	2E 57	4	-		62 NL	4E 117		5E 137	94 UNT	6E 157		7E 177	12
Г	SI			/	7 3F	?	63	4F O)	5F	_	6F	0	1	DEL BOUT
	Address	Universal	21		stene		00	41	Tall		35			ond	12
	Command	Command			dress				Ado	dress			Cor	nman	d
	Exam	ple	(Octal —	->	25 NA	P	PU <		-IB co CII ch	ode aracter c	ode			

Appendix 2.7 Communication Error Messages

Error messages related to the 488.2 communication mode are given below.

- When servicing is required, contact your nearest YOKOGAWA representative, listed on the back cover of this manual.
- The following error messages are displayed when a communication command is received in 488.2 communication mode. For a description of errors which occur in a mode other than the 488.2 communication mode or occur when a panel key is pressed, refer to Section 15.2, "Error Codes and Corrective Actions".

Errors in communication command (100 to 199) Error in communication command

Code	Message	Action Reference	Page
102	Syntax error	Incorrect syntax	Appendix 2.2,
			Appendix 2.3
103	Invalid separator	Insert a comma between data items to	App 2-3
		separate them.	
104	Data type error	Refer to pages App 2-6 to 2-7 and enter	App 2-6,
		using the correct data format.	App 2-7
105	GET not allowed	GET is not supported as a response .	—
		to an interface message	
108	Parameter not allowed	Check the number of parameters.	App 2-6,
			Appendix 2.3
109	Missing parameter	Enter required parameters.	App 2-6,
			Appendix 2.3
111	Header separator error	Insert a space between the header and the	App 2-3
110		data to separate them.	
112	Program mnemonic too long	Check the mnemonic (a character string	Appendix 2.3
113	Undefined header	consisting of letters and numbers). Check the header.	Appendix 2.3
113			Appendix 2.3
	Header suffix out of range	Check the header.	
120	Numeric data error	Numeric value must be preceded by a mantissa for <nrf> format.</nrf>	App 2-6
123	Exmonant too lance		App 2.6
125	Exponent too large	Use a smaller exponent for <nr3> format.</nr3>	App 2-6, Appendix 2.3
124	Too many digits	Limit the number of digits to 255 or less.	Appendix 2.5
124	100 many digits	Limit the number of digits to 255 of less.	Appendix 2.3
128	Numeric data not allowed	Enter in a format other than <nrf> format.</nrf>	App 2-6,
			Appendix 2.3
131	Invalid suffix	Check the unit for <voltage> and <current>.</current></voltage>	App 2-7
134	Suffix too long	Check the unit for <voltage> and <current>.</current></voltage>	App 2-7
138	Suffix not allowed	No units are allowed other than <voltage> and <current>.</current></voltage>	App 2-7
141	Invalid character data	Enter one of the character strings in {l}.	Appendix 2.3
144			
144	Character data too long	Check the spelling of the character strings in {l}.	Appendix 2.3
148	Character data not allowed	Enter in a format other than in {l}.	Appendix 2.3
150	String data error	<character string=""> must be enclosed by double quotation marks or single quotation marks.</character>	App 2-7
151	Invalid string data	Character string> is too long or contains	Appendix 2.3
	-	characters which cannot be used.	

Code	Message	Action Reference	Page
158	String data not allowed	Enter in a data format other than	Appendix 2.3
		<character string="">.</character>	
161	Invalid block data	<block data=""> is not allowed.</block>	_
168	Block data not allowed	<block data=""> is not allowed.</block>	_
171	Invalid expression	Equation is not allowed.	Appendix 2.3
178	Expression data not allowed	Equation is not allowed.	Appendix 2.3
181	Invalid outside macro definition	Does not conform to the macro function	_
		specified in IEEE488.2	

Error in communications execution (200 to 299) Error in communication execution

Code	Message	Action Reference	Page
221	Setting conflict	Check the relevant setting.	Appendix 2.3
222	Data out of range	Check the setting range.	Appendix 2.3
223	Too much data	Check the data byte length.	Appendix 2.3
224	Illegal parameter value	Check the setting range.	Appendix 2.3
241	Hardware missing	Check availability of options.	_
260	Expression error	Equation is not allowed.	_
270	Macro error	Does not conform to the macro function	_
		specified in IEEE488.2	
272	Macro execution error	Does not conform to the macro function	_
		specified in IEEE488.2	
273	Illegal macro label	Does not conform to the macro function	_
		specified in IEEE488.2	
275	Macro definition too long	Does not conform to the macro function	_
		specified in IEEE488.2	
276	Macro recursion error	Does not conform to the macro function	_
		specified in IEEE488.2	
277	Macro redefinition not allowed	Does not conform to the macro function	_
		specified in IEEE488.2	
278	Macro header not found	Does not conform to the macro function	_
		specified in IEEE488.2	

Error in communications query (400 to 499) Error in communication Query

Code	Message	Action Reference	Page
410	Query INTERRUPTED	Check transmission/reception order.	App 2-3
420	Query UNTERMINATED	Check transmission/reception order.	App 2-3
430	Query DEADLOCKED	Limit the length of the program message including <pmt> to 1024 bytes or less.</pmt>	App 2-4
440	Query UNTERMINATED after indefinite response	Do not enter any query after *IDN? and *OPT?.	_

Error in Execution (800 to 899)

Error in Execution

Code	Message	Action Reference	Page
813 to 819	Invalid operation	For the lower 2 digits of the error code, refer	_
		to Section 15.2, "Error Codes and Corrective	
		Actions".	
820 to 826	Flicker execute error	For the lower 2 digits of the error code,	_
		refer to Section 15.2, "Error Codes and	
		Corrective Actions".	
830	Internal memory access error	For the lower 2 digits of the error code,	_
		refer to Section 15.2, "Error Codes and	
		Corrective Actions".	
841 to 848	Integrator execute error	For the lower 2 digits of the error code,	
		refer to Section 15.2, "Error Codes and	
		Corrective Actions".	

Error in System Operation (912)

Error in System Operation

Code	Message	Action Reference	Page
912	Fatal error in Communication-driver	Servicing is required.	_

Other errors (350, 390)

Code	Message	Action Reference	Page
350	Queue overflow	Queue overflow Read the error queue.	App 2-59
390	Overrun error (RS-232-C only)	Reduce the baud rate.	14-12

Note _

• Code 350 occurs when the error queue is full up. This message is output only for the STATus: ERRor? query and is not displayed on the screen.

Appendix 3 Print Examples

The print examples given below may differ from the actual print outputs.

Panel Set-up Information

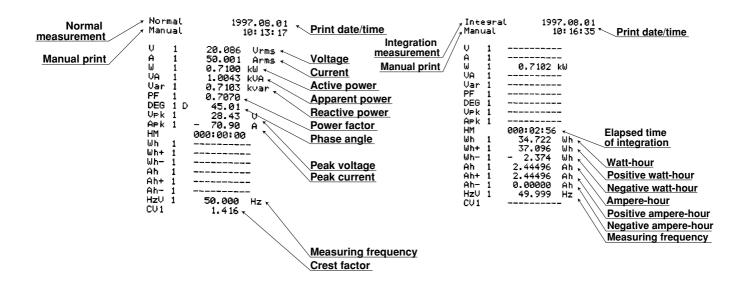
The following example shows the default settings (factory settings).

		B * * 1 * <i>#</i> *
	WT2010 Setup Lists	Print date/time
	1997.08.01	Model name
	Model Name 253101-C1 🗸	Installed options
	Option /DA/B5/HRM/FL	Voltage range and measurement mode for each element
	V1 Manual 600 Vrms 🔶 👘	
	Al Manual 30 Arms 🛀	Current range and measurement
	Ext.Shunt(A1) 50.000A/FS <	mode for each element
	Diselay A V 1	External shunt current value
	Display B A 1	Display element
	Display C W 1 Display D W 1	Display clement
	Filter Off ← Cut Off Frequency 500Hz ←	Line filter ON/OFF
	Peak Hold Off 🦟 👘 🗸	Cut-off frequency Peak hold ON/OFF
	Peak Hold Function Peak	Peak hold function
	Null Function Off	Frequency filter ON/OFF
	Crest Factor 3	NULL function ON/OFF
		Crest factor Pase angle display method
	Scaling Off PT Ratio 1 1.0000	<u>I doo diigio diopidy motifod</u>
	CT Ratio 1 1.0000	
	Scaling Factor 1 1.0000	Scaling ON/OFF and scaling values
	Averaging Off)	
	Avg Type Exp.	Averaging ON/OFF, averaging type and coefficient
	Avs Coefficient 8	Averaging ON/OFT, averaging type and coefficient
	Hold Off ← Sample Rate 500ms ←	Hold ON/OFF
	Mathematics CV1	Sample rate
	Integ. Mode Manual	MATH setting
	Integ. Timer 000h00m	
	Rated Time(DA) 001h00m J	Integration mode and integration timer preset time
ĺ	Auto Print Off	
	Print Sync. Timer Print Interval 00h01m00s	
		Auto print ON/OFF, print synchronous method
	Harmonic Off Disp. B Format Value	and print interval
	Sync. Source PLL V1	
	Setting MaxOrder 50	Harmonic analysis ON/OFF, display mode, PLL
	Disp. A Order 1	source, upper limit of the harmonic order(Setting Max Order), computation method, anti-aliasing
	Anti-Aliasing Filt. Off Window Width 16	filter ON/OFF, analysis window width
)	Voltage fluctuation/flicker measurement ON/OFF,
This can be printed only	Flicker Off Un Setting Mode Auto	nominal voltage setting, existing rated voltage, relative
when the option is installed	Un Setting Volt 230.00V	steady-state voltage change ON/OFF, limit for relative
	dc 3.00% On	steady-state voltage change, maximum relative voltage change ON/OFF, limit for maximum relative
	dmax 4.00% On d(t) 3.00%, 200ms On	voltage change, duration during which voltage
	Pst 1.00 On 🖕	exceeds the threshold level within one voltage change
	Plt 0.65 On Plt N Value 12	ON/OFF, limit for duration during which voltage exceeds the threshold level within one voltage change,
	Pst Interval 10m00s	short-term flicker value ON/OFF, limit for short-term
	Pst Measuring Count 12 dmin 0.10 %	flicker value, long-term flicker value ON/OFF, limit for
	Flicker Element 1 On	long-term flicker value, constant used in the equation, observation period for short-term flicker value,
	Communication Command 3 👡	number of times measurement is performed, steady-
(state range, and input elements
		Command group used
		group about

Appendix 3 Print Example

Output Items for Normal Measurement

The following example shows output items when " $\Re \lfloor L$ " is selected for the built-in printer output type. The number to the right of each output item indicates the element no.

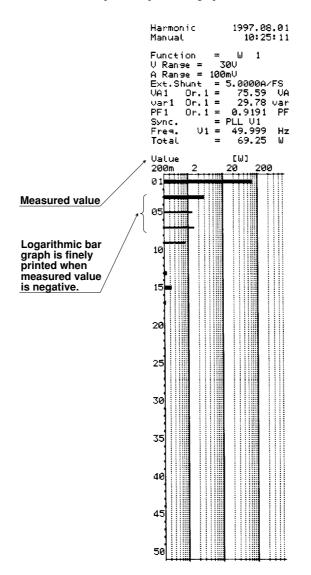


Print Examples for Harmonic Analysis

Output item: #(current) (Measured current and distortion are printed in numeric.) Output item: $\mathcal{L} - \mathcal{R}$ (current in graph) (Measured current is printed in graph.)

Harmonic analysis measurement	≁Harmonic	1997.08.01		Harmonic 1997.08	01
	≁ Manual	10:18:18	Print date/time	Manual 10:18	
Manual print	Function =	A 1 .			
Voltage/current	V Ranse = 30	V ,	Output item (current, element 1)	Function = A 1 V Range = 30V	
measuring range	*A Ranse = 100m Ext.Shunt = 5	U . 0000A/FS 🔨	<u></u>	A Ranse ≠ 100mV	
	VA1 Or.1 =	81.44 VA	External shunt	Ext.Shunt = 5.0000A/ VA1 Or.1 = 81.45	'FS VA
	vari Or.1 =-	57.59 var	Apparent power	var1 0r.1 = - 57.61	
PLL source		0.7070 PF LL V1	Reactive power	PF1 Or 1 = 0.7070	PF
(Voltage, element 1)		49.999 Hz	Power factor	Sync. = PLL V1 Freg. V1 = 49,999	Hz
Fundamental		4.0839 A 12.12 %	Total rms value	Total = 4.0846	A
frequency of PLL source	т.н.р. =	12.12 %	(fundamental + harmonics)	T. H. D. $=$ 12.12	*
	Or. Value[A],	Contain[%]	Harmonic distortion	√Value [A]	
	01 4.0542 02 0.0003	0.01	Content	/ 5 m 50m 500m 5	
/	103 0.4507	11.12	Measured value	01	
	04 0.0002	0.00	Measured value		
Harmonic (up to 50th)	05 0.1626 06 0.0001	4.01 0.00	measured value	85	
	07 0.0826	2.04			
	08 0.0000 09 0.0499	0.00 1.23			
	10 0.0000	0.00		10	
	11 0.0334	0.82			
	12 0.0001 13 0.0240	0.00 0.59		∕ ⊨⊨-	
	14 0.0000	0.00	/	15	
	15 0.0180 16 0.0002	0.44	Logarithmic bar graph		
	17 0.0141	0.00 0.35			
	18 0.0000	0.00		20	
	19 0.0112 20 0.0000	0.28 0.00			
	21 0.0092	0.23			
	22 0.0001	0.00		25	
	23 0.0076 24 0.0001 25 0.0065 26 0.0001 27 0.0057	0.19 0.00		-	
	25 0.0065	0.16			
	26 0.0001 27 0.0057	0.00 0.14		30	
	28 0.0001	0.00			
	29 0.0048	0.12			
	30 0.0001 31 0.0042	0.00 0.10		35	
	32 0.0000	0.00			
	33 0.0036 34 0.0001	0.09 0.00		40	
	34 0.0001 35 0.0033	0.00		40	
	36 0.0000	0.00			
	37 0.0030 38 0.0001	0.07 0.00		45	
	39 0.0026	0.06			
	40 0.0000	0.00			
	41 0.0024 42 0.0000	0.06 0.00		50	
	43 0.0022	0.05		⊾ ₩₩ ╋─── ₩ ─₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩₩	****
	44 0.0001 45 0.0020	0.00 0.05			
	46 0.0001	0.00			
	47 0.0019	0.05			
	48 0.0001 49 0.0016	0.00 0.04			
	50 0.0000	0.00			

Output item: $\frac{r}{2} - \frac{p}{2}$ (active power in graph) (Measured active power is printed in graph.)



			fundamental of vo	oltage is printed i	n graph.)
	Harmonic Manual	1997.08.01 10:26:27		Harmonic Manual	1997.08.01 10:26:57
Phase angle of each harmonic in relation of fundamental of voltage	Manual Function = 3 A Range = 100 Ext.Shunt = 100 Ext.Shunt = 100 UA1 Or.1 = 100 UA1 Or.1 = 100 Ext.Shunt = 100 Ext.Shunt = 100 Ext.Shunt = 100 Ext.Shunt = 100 Or. 1 = 100 Or. 200 000 01 188.13 05 0.01 06 - 124.40 07 0.03 08 129.02 09 0.04 10 148.32 11 0.04 12 145.55 13 0.07 14 70.59 15 0.08 16 - 133.38 17 0.06 18 133.00 19 0.10 20 90.98 16 - 124.40 07 0.03 08 129.02 09 0.04 10 148.32 11 0.04 12 145.55 13 0.07 14 70.59 15 0.08 16 - 133.38 17 0.06 18 133.00 19 0.10 20 90.98 21 0.12 22 160.42 23 0.11 24 109.31 25 0.12 26 123.99 29 0.17 35 0.20 34 - 9.93 35 0.20 34 - 9.93 35 0.20 40 - 107.47 41 0.26 43 0.22 44 83.60 47 0.28 48 71.29 49 0.28 49 0.28 40 0.28 4	DE61 500 5.0000A/FS 75.59 VA 29.77 Var 0.9192 PF 23.20 deg PLL V1 49.999 Hz 5.23.20 deg PLL 01 141.52 0.00 125.58 0.02 141.52 0.00 125.58 0.02 10.30 0.03 10.00 0.04 16.92 0.03 101.00 0.06 107.67 0.06 0.07 0.06 0.07	Output item (phase angle, element 1) Output item (phase angle of voltage, element 1) Phase angle between fundamentals of voltage and current Phase angle Phase angle of each harmonic in relation of fundamental of current deg (bar graph)	Manual Function = V Range = 3 A Range = 100 Ext.Shunt = VA1 0r.1 = Va1 0r.1 = PF1 0r.1 = deg 0r.1 =	U des1 500 5.0000A/FS 75.59 VA 29.78 var 0.9191 PF 23.20 des PLL V1 49.999 Hz 23.20 des
	50 158.29	- 161.43			

Appendix

Print Examples for Voltage Fluctuation/Flicker Measurement

Output item: [P F (Cumulative probability function graph)

Output item: $\mathbf{j} \cdot \mathbf{j} \cdot \mathbf{j} \cdot \mathbf{j}$ (Flicker meter judgment result table)

			*****	*****	*****	
Flicker 1996.01 Manual 07:02			Elemer ######	1t 1 F	Period = 12	
*****	##	Voltage range 🔏	V Rans Un	e = 300 V1 = 2		
Element 1 Period = ####################################		Nominal voltage Un	Freq.	V1 =	50.000 Hz	
V Range = 300V	Voltage range	Frequency of	Pst In Flapse	iterval ≠ d Time =	: 10m00s : 02h00m00s	
Un V1 = 234.19 Freg. V1 = 49.999	Nominal voltage Un	Measurement time				
Pst Interval = 10m	Bis Frequency of		##### Lmt=	dc [%] 3.00	****	
Elapsed Time = 00h20m	Measurement time	Elapsed time	No.	dc [%]	Judament Rese	
dc Lmt= 3.00%	for short-term flicker	Judgment item	$\begin{bmatrix} 1\\ 2 \end{bmatrix}$	2.21 2.33	Pass Pass	
dmax Lmt= 4.00% d(t) Lmt= 3.00%, 20		Limit	34	2.45 2.57	Pass Pass	
Pst Lmt= 1.00	Limit for each		5	2.49	Pass	
dc = 2.91% Pas	parameter	Observation ,	67	2.31 2.56	Pass Pass \lud	gment result
dmax = 2.96% Pas d(t) = 0ms Pas	\ \	period No.	8	2.64	Pass	ginent result
Pst = 2.02 Fai		v de dreev d(t)	9 10	2.41 2.37	Pass Pass	
Level-Probability[%]	Measurement data fo	ent result	11	2.25	Pass Pass	
[%] 100 	Pass:	a ware esticfied	L 12			
90	Judgment condition Fail:		##### Lmt=	dmax[%] 4.00	***	
80	Judgment condition	ns were not satisfied.	No.	dmax[%]	Judsment	
70	Judgment not poss	ible.	1 2	3.02 3.68	Pass Pass	
60	\downarrow		23	3.32	Pass	
50		14. <i>c</i>	4 5	3.18 3.37	Pass Pass	
40	Cumulative probabili	ity	6 7	3.65 3.76	Pass Pass	
30	_		8	3.51	Pass	
20	_		9 10	3.14 3.58	Pass Pass	
10	_		11	3.41	Pass	
			12	3.27	Pass	
10m 100m 1 10 100 1k Level	0k		##### Lmt=	d(t)[ms] 200]##########	
			No.	d(t)[ms]	Judament	
			1 2	0	Pass Pass	
			3	10	Pass	
			4 5	20 0	Pass Pass	
			2345678	50 0	Pass Pass	
			ś	ø	rass Pass	
			9 10	10 0	Pass Pass	
			11	ø	Pass	
			12	10	Pass	
			##### Lmt=	Pst 1.00	*****	
			No.	Pst	Judsment	
			1	0.85 0.86	Pass Pass	
			3	0.90	Pass	
			4 5	0.93 0.87	Pass Pass	
				0.98	Pass	
			6 7 8	0.99 0.88	Pass Pass	
			9 10	0.94 0.95	Pass Pass	
			11	0.92	Pass	
			12	0.91	Pass	
			#####		****	T
			Lmt= Plt=		Fail	Total judgment result
					*****	/
				Jud 9e ########	Fail ↓ ##########	

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